

# FORCE TORQUE SENSOR DESIGNED FOR UNIVERSAL ROBOTS

GIVE YOUR ROBOT THE SENSE OF TOUCH



# AUTOMATE FORCE SENSITIVE TASKS

### Reliably perform:

- Precision part insertion
- Assembly and fabrication
- Product testing

# MADE FOR UNIVERSAL ROBOTS

- Quick installation
- Path recording with URCap Force Torque Sensor
- Increased movement precision with ActiveDrive toolbar

## RELIABLE AND STABLE

FT 300 digital signal is not affected by external signal noise

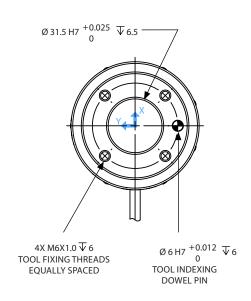


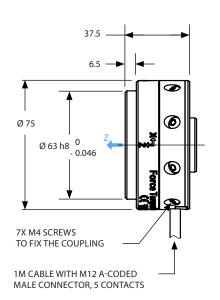


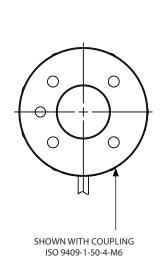
## **TECHNICAL DATA**

# FT 300

#### **TOOL SIDE**







**ROBOT SIDE** 

(MAY VARY ACCORDING TO YOUR OPTION)

UNITS: mm

SIGNAL SPECIFICATIONS	Fx (N)	Fy (N)	Fz (N)	Mx (Nm)	My (Nm)	Mz (Nm)
Measuring range	±300	±300	±300	±30	±30	±30
Signal noise*	0.1	0.1	0.1	0.005	0.005	0.003
Recommended minimum threshold for contact in robot static state	1	1	1	0.02	0.02	0.01

Recommended minimum threshold for contact during quasi-static motion

For threshold during quasi-static motion, ask your integration coach at support@robotiq.com

External noise sensitivity**	Immune
Data output rate	100 Hz
Temperature compensation***	15℃ - 35℃

<sup>\*</sup> Signal noise is the standard deviation of the signal measured over a period of one (1) second.

#### MECHANICAL SPECIFICATIONS

Outside diameter	75 mm
Thickness	37.5 mm
Weight	300 g
Overload capacity	A combined load exceeding 500% of the measuring range will permanently damage the Force Torque Sensor (Fx/300 + Fy/300 + Fz/300 + Mx/30 + My/30 + Mz/30 < 500%)
ELECTRICAL SPECIFICATIONS	
Nominal supply voltage	4.5-28 V DC
Maximum power consumption	2 W
Electrical interface	RS-485, USB

#### **SOFTWARE**

Sensor software package for Universal Robots available including: ActiveDrive, Path Recording and various Skills functions. Calibration software available for PC.

Sensor development package available for PC.

<sup>\*\*</sup> Under normal operating conditions.

<sup>\*\*\*</sup> Within this range, the temperature fluctuation is compensated for; signal quality may be affected outside of this range.