

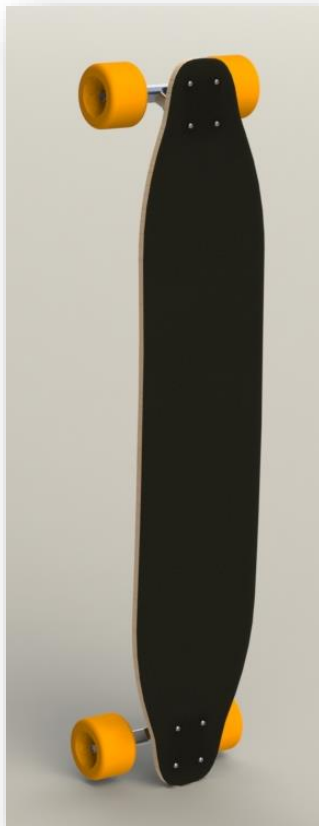
# **ME 5240 CAD and Manufacturing**

## **Section 01**

### **Final Project**

Product: Longboard

By: Oscar Chen



## Table of Contents

<b>Functionality &amp; Design Requirements</b>	<b>3</b>
<b>Instructions 1: Deck</b>	<b>4</b>
<b>Instructions 2: Baseplate</b>	<b>133</b>
<b>Instructions 3: Trucks</b>	<b>188</b>
<b>Design Binder</b>	<b>27</b>
<b>Assembly Instructions</b>	<b>28</b>
<b>Engineering Drawings</b>	<b>41</b>
<b>Design Intent &amp; Part Configuration Analysis</b>	<b>43</b>
a. Equation	4343
b. Configuration	44
<b>STL File</b>	<b>47</b>
<b>Mass Properties</b>	<b>48</b>
<b>FEM/FEA</b>	<b>52</b>
<b>Sustainable Design</b>	<b>55</b>
<b>Part Manufacturing</b>	<b>57</b>
<b>Theory Questions</b>	<b>579</b>

# Functionality & Design Requirements

A longboard is a form of transportation used by many to travel short distances to reach a destination. It can withstand some beatings and is able to be ridden for many miles within its lifetime. It utilizes four free rolling wheels on a specially made wooden deck.

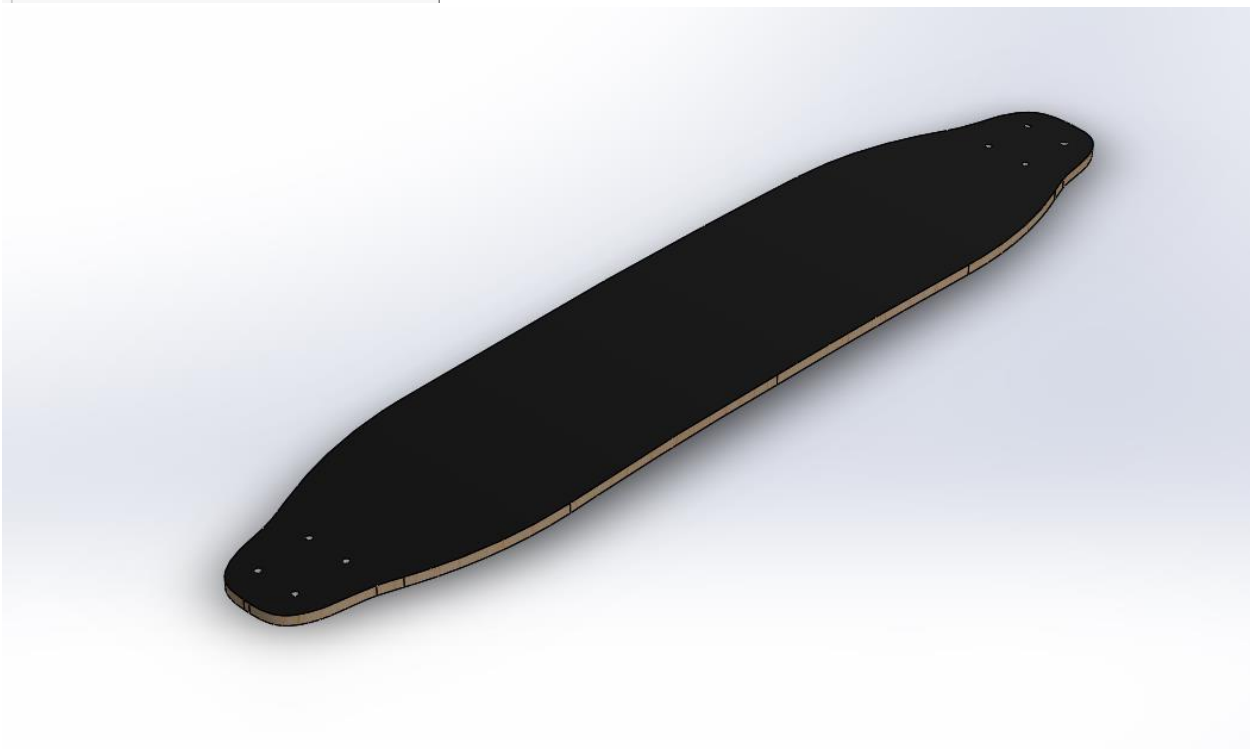
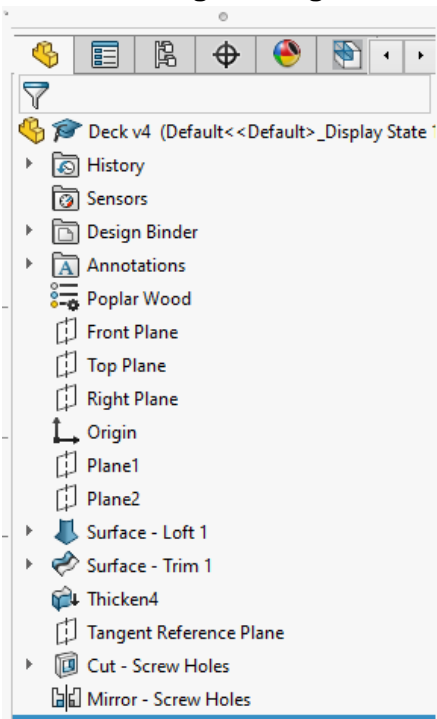
This longboard assembly includes 41 components, 10 of which are unique components. These unique components are the deck, baseplate, trucks, wheels, bushing, bushing cap, risers, screw, screw bolt, and hex nut. Each component of the assembly serves an important role. The wooden deck is the main platform where users stand on the longboard. The baseplate, trucks, bushing, and bushing caps go hand and hand together to allow for a secure and pleasant carving experience when leaning on the longboard. The riser is meant to elevate and separate the trucks from the deck. Finally, the screw, screw bolt, and hex nut are responsible for keeping certain components in place and connected.

This Solidworks assembly utilized many concepts and features, such as surfacing, extrudes, chamfers, fillets, revolves, and many more. There were three components that were focused on in this project: the wooden deck, the baseplate, and the trucks. These three components are vital to the longboard's overall composition. The deck required levels of surfacing and extruded cuts. The baseplate required complex sketching as well as thoughtful extruded cuts. The trucks required lots of thoughtfully placed fillets and boss extrusions. This paper will discuss in detail the ways to create these important parts.

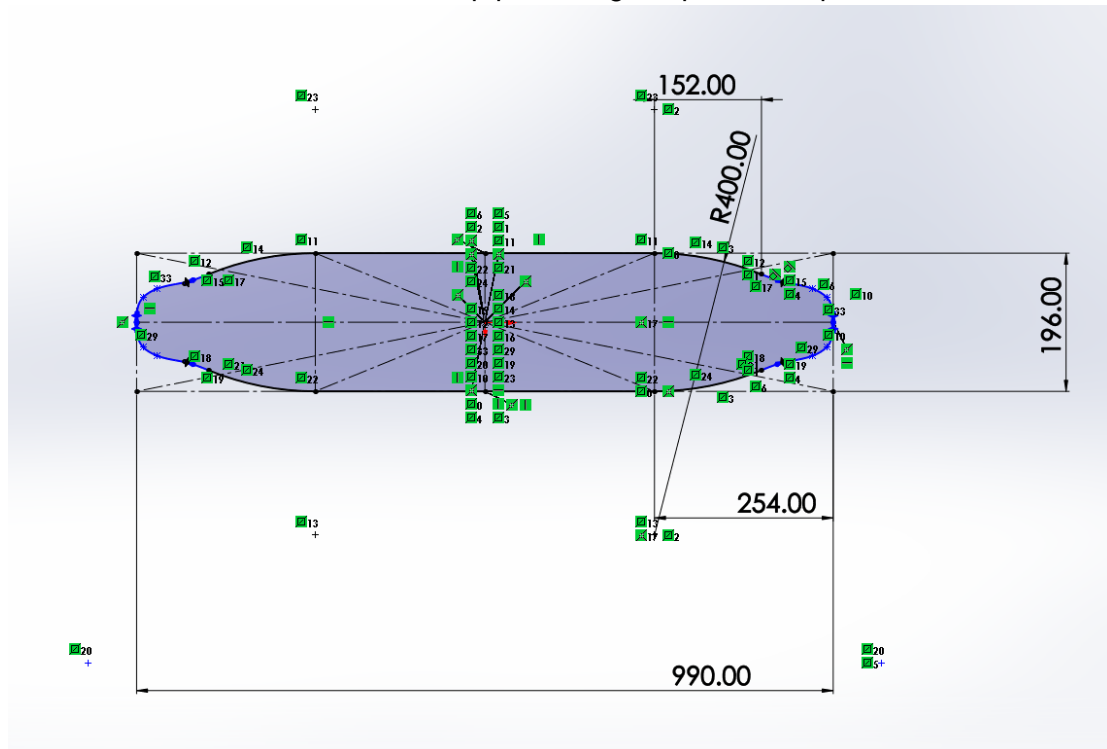
All dimensions are in mm. The materials used for all the parts are Poplar Wood for the deck, requiring custom input of material selection, ABS plastic for the risers, polyurethane for the wheels and bushings, 7075-T6 Plate (SS) for the trucks and baseplate, and Cast Carbon Steel for the screw. DISCLAIMER, the screw used in this project sourced from McMaster while every other component was self-modeled.

# Instructions 1: Wooden Deck

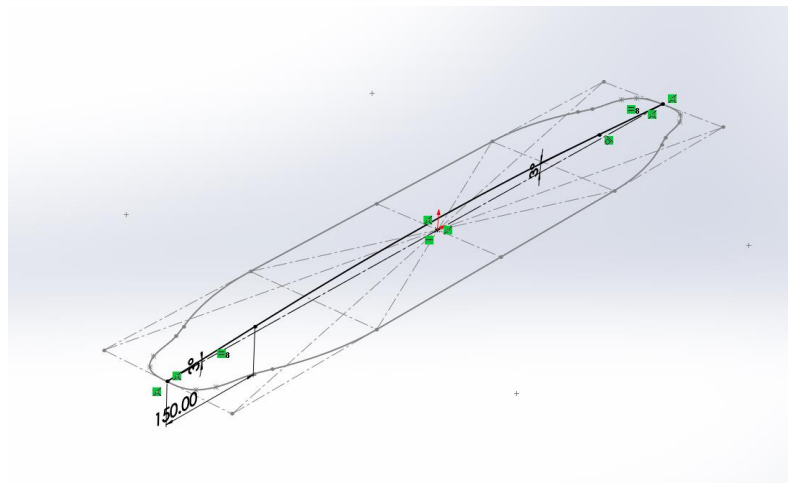
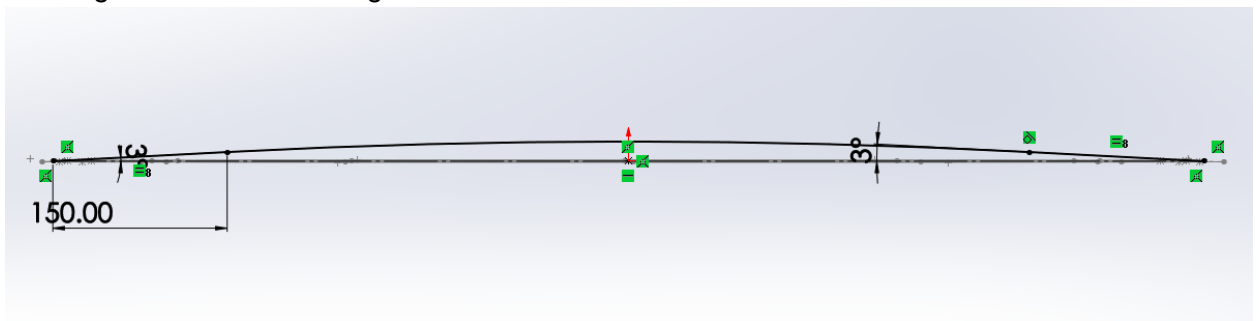
## Feature Manager Design Tree



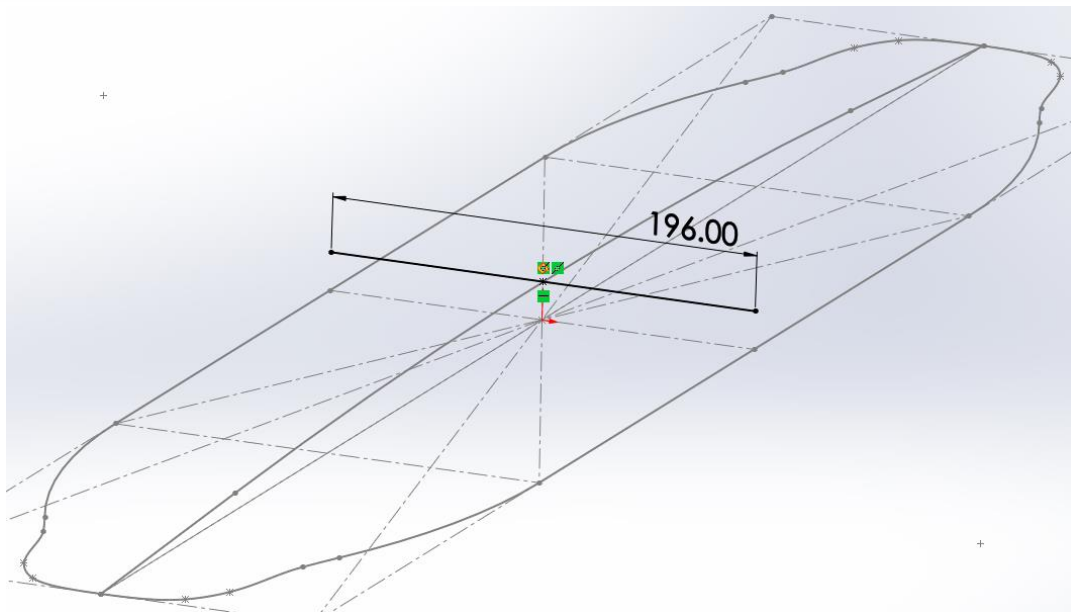
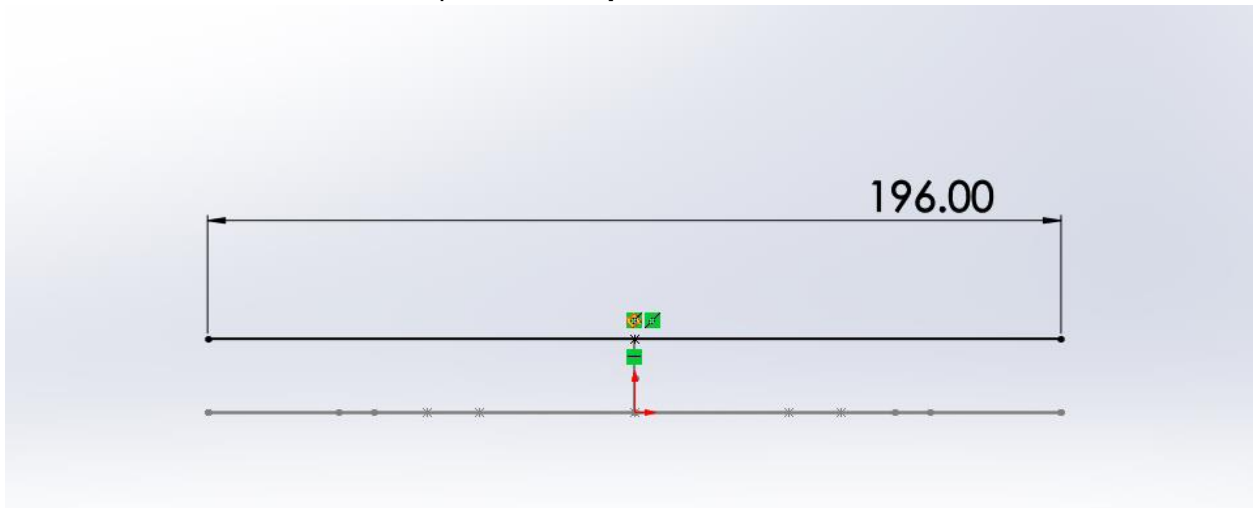
1. **Sketch 1:** Create sketch shown on top plane to get top view shape of board.



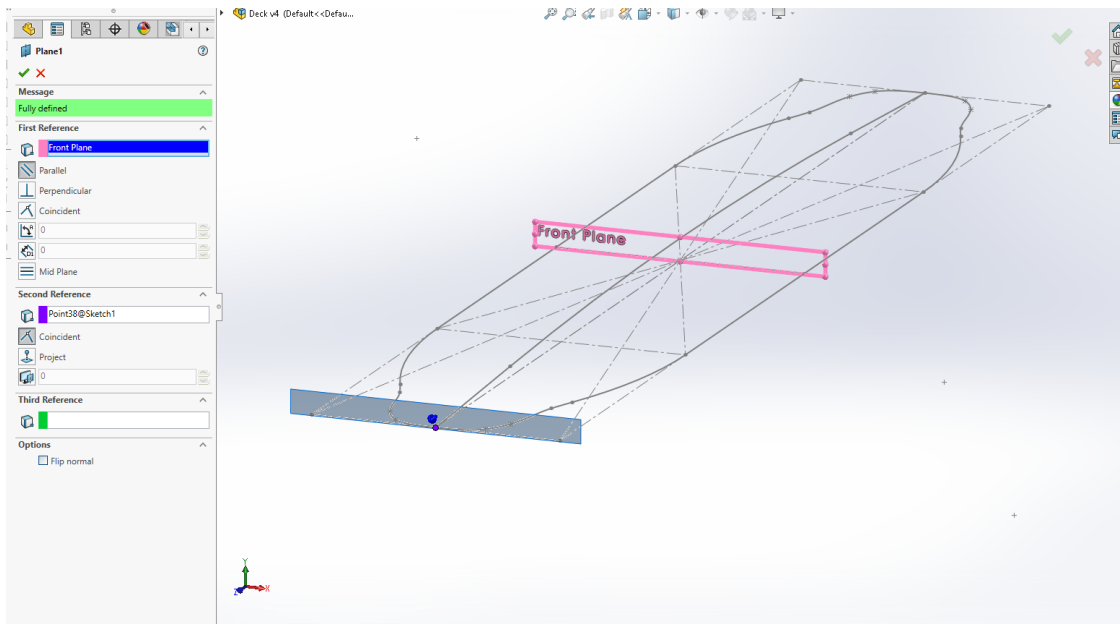
2. **Sketch 2:** Create sketch shown on right plane, connecting the ends of the sketch 1 and creating the curve of the longboard



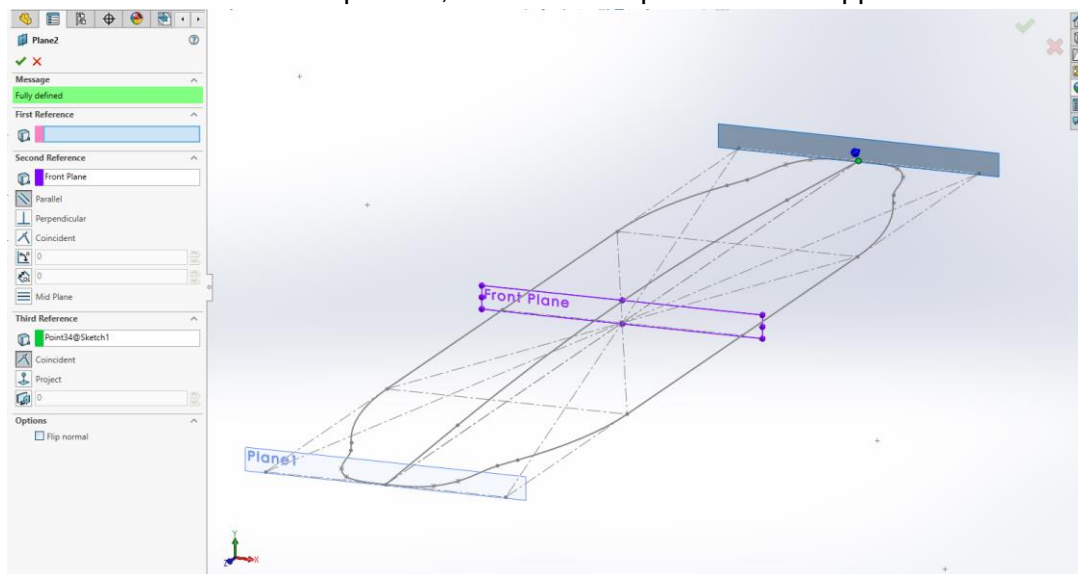
3. **Sketch 3:** Create sketch on front plane. Make **pierce relation** to sketch 2



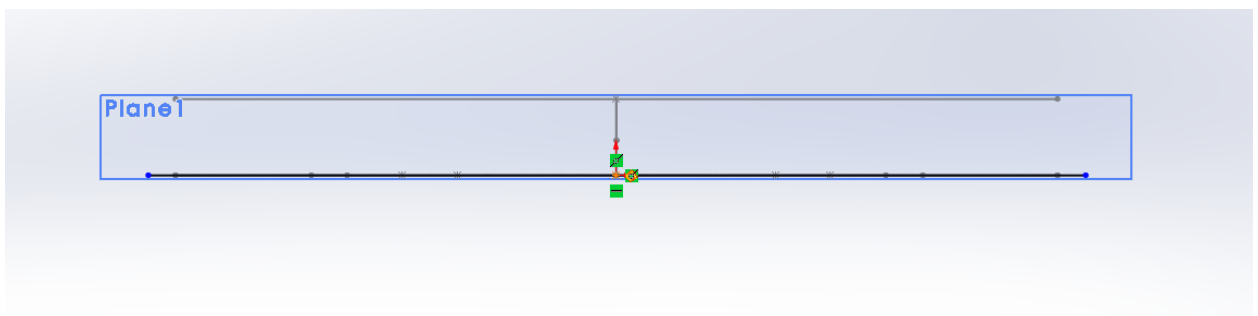
4. **Plane 1:** Create reference plane 1, parallel to front plane, coincident to furthest point in sketch 1.



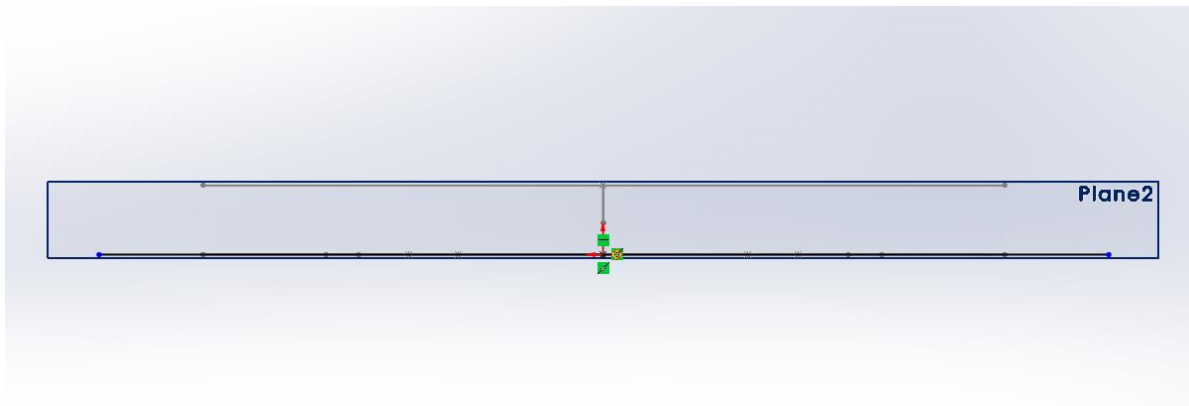
5. **Plane 2:** Create reference plane 2, like reference plane 1 in the opposite direction



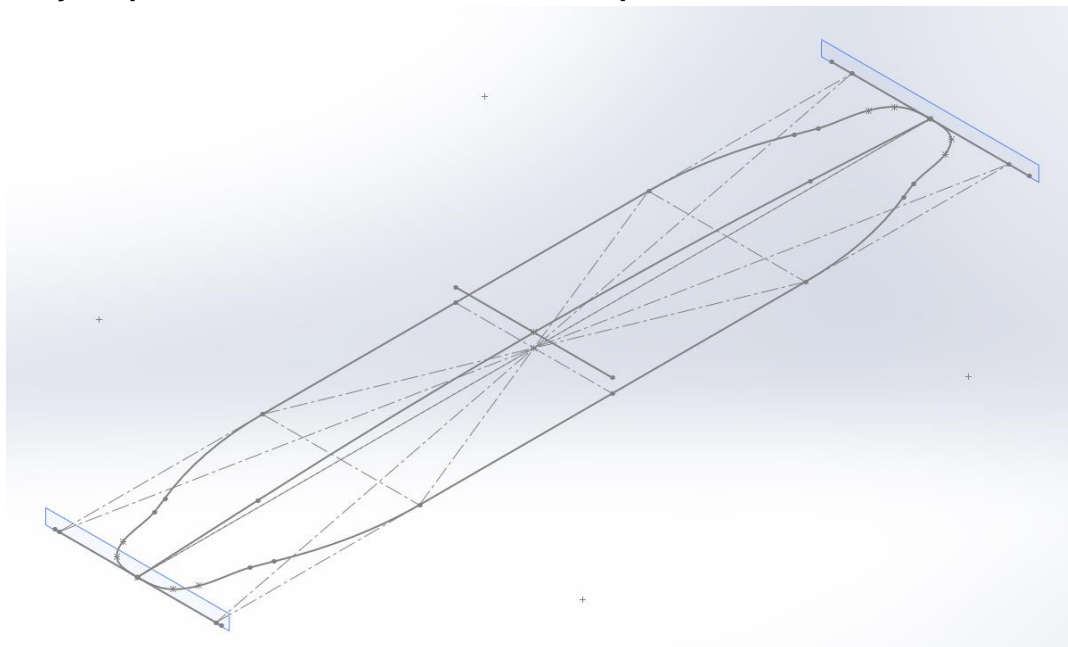
6. **Sketch 4:** Create sketch on plane 1. Create midpoint line long enough to cover the width of sketch 1. Make **Pierce** relation to sketch 2



7. **Sketch 5:** Create sketch on plane 2 like sketch 4

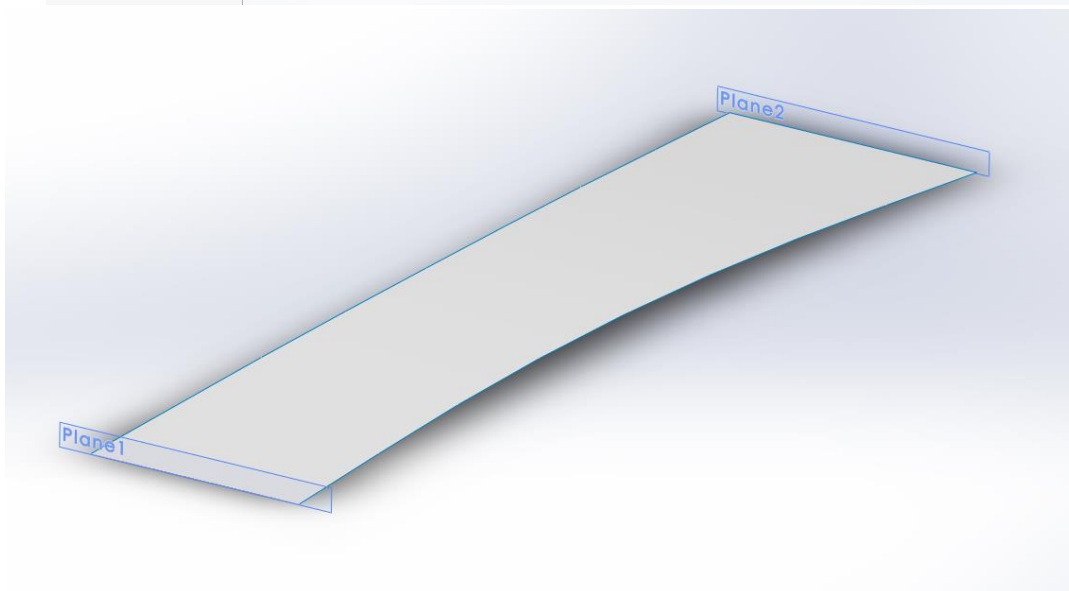
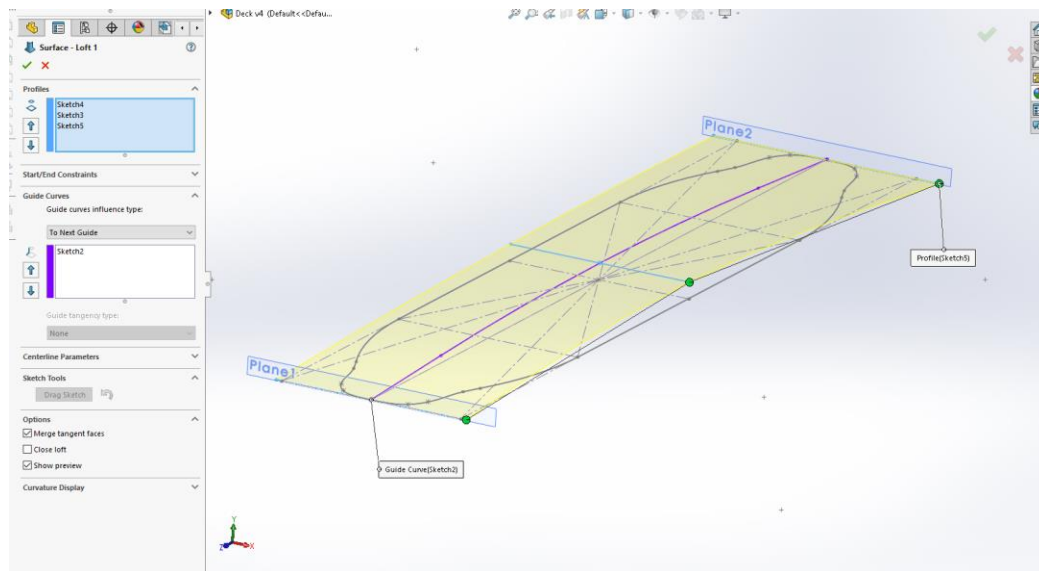


**\*Note, your part should look like this at this step\***

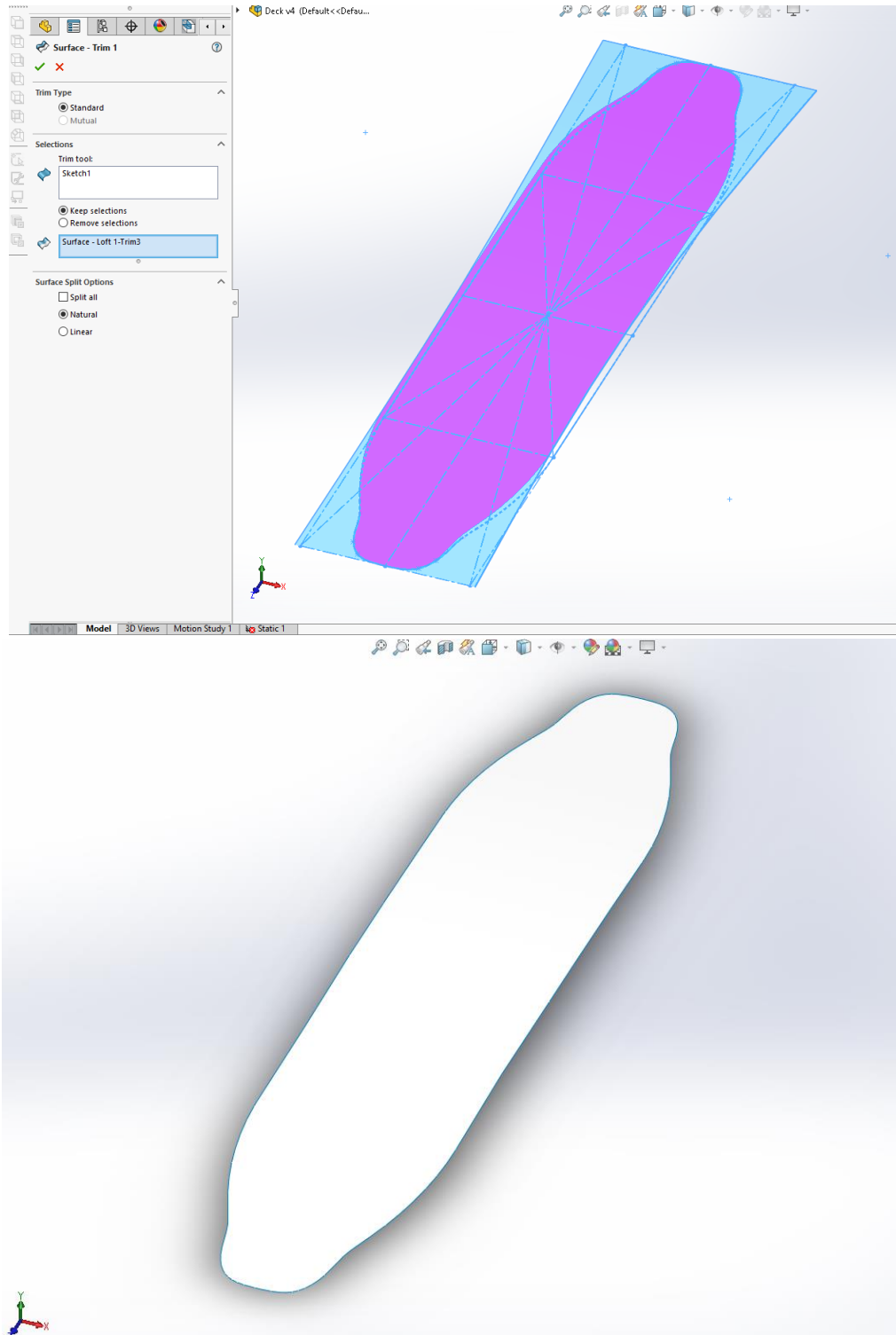




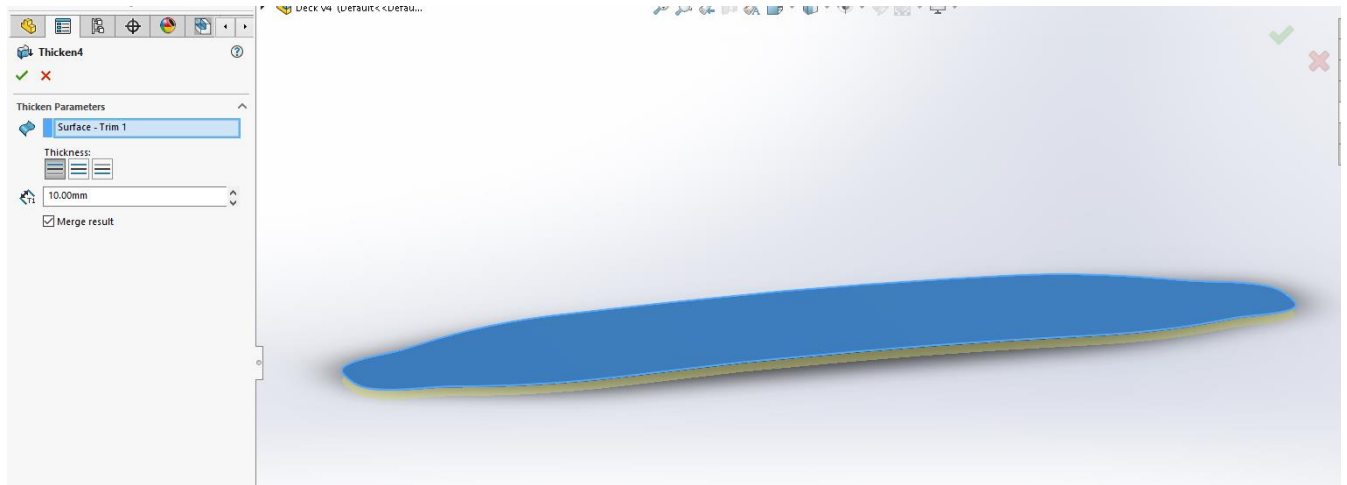
8. **Surface – Loft 1:** Create a surface loft with sketches 4, 5, and 6 for the profile and sketch 2 as the guide curve.



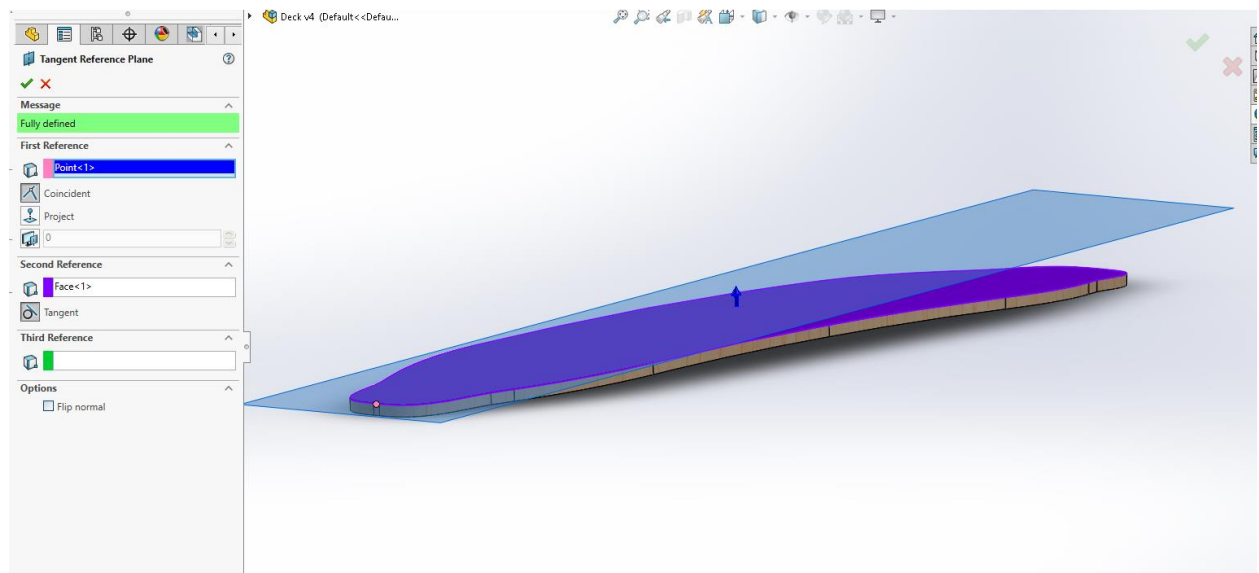
9. **Surface – Trim 1:** Use surface trim, selecting sketch 1 as trim tool and surface loft 1 as the selection.



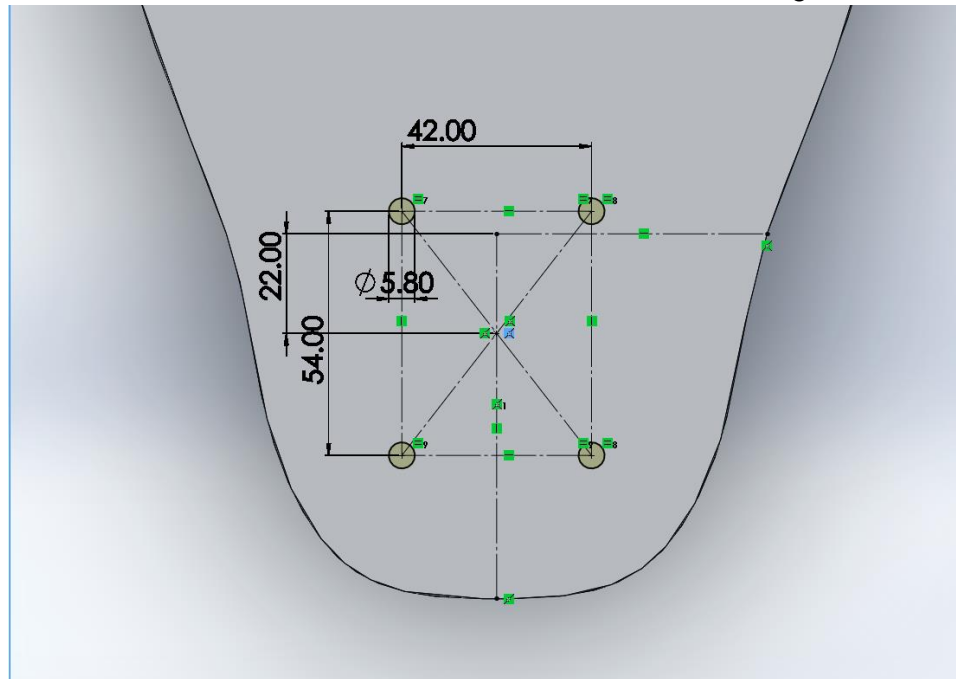
10. **Surface – Thicken 1:** Thicken surface, input 10mm.



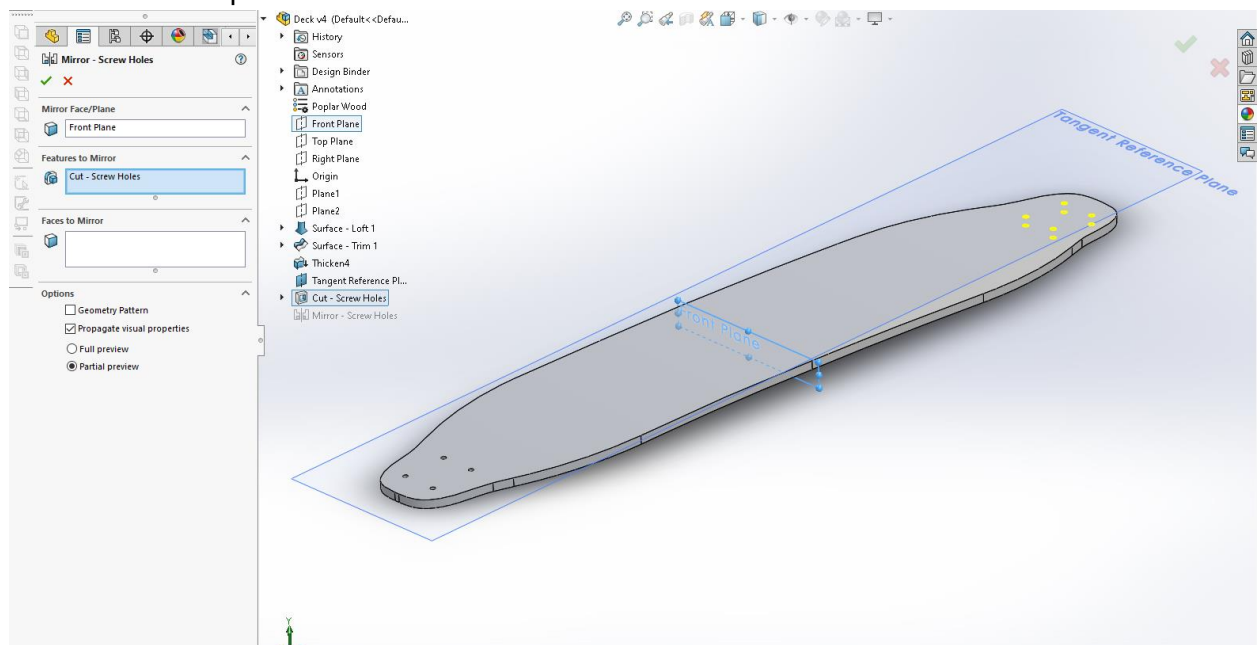
11. **Tangent Reference Plane:** Select end point and make a reference plane tangent from top surface



12. **Cut – Screw Holes:** Create sketch below and extrude cut, through-all

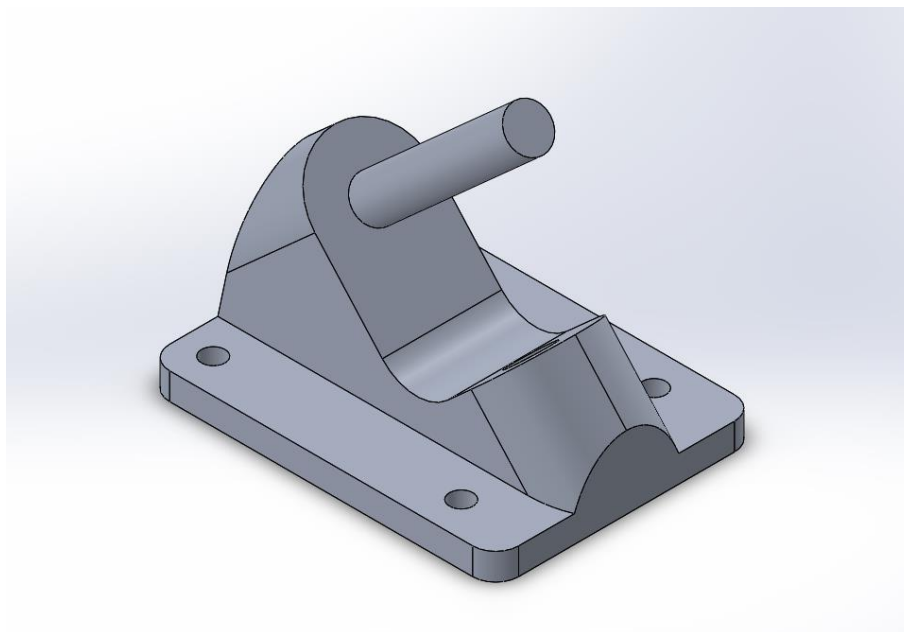
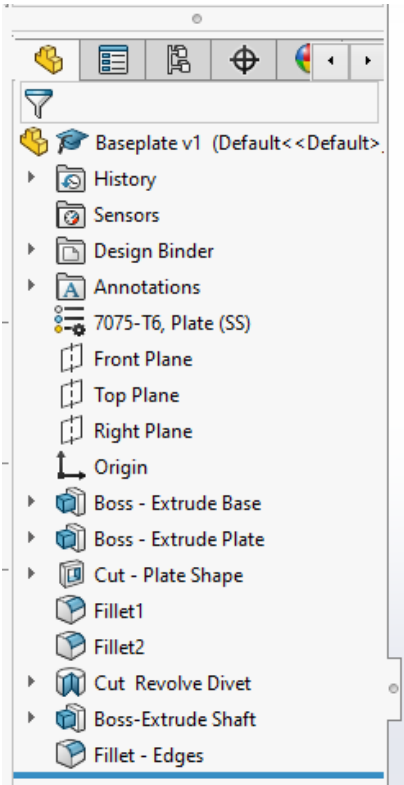


13. **Mirror – Screw Holes:** Use mirror feature to mirror the extrude cut, using the front plane as the mirror plane.

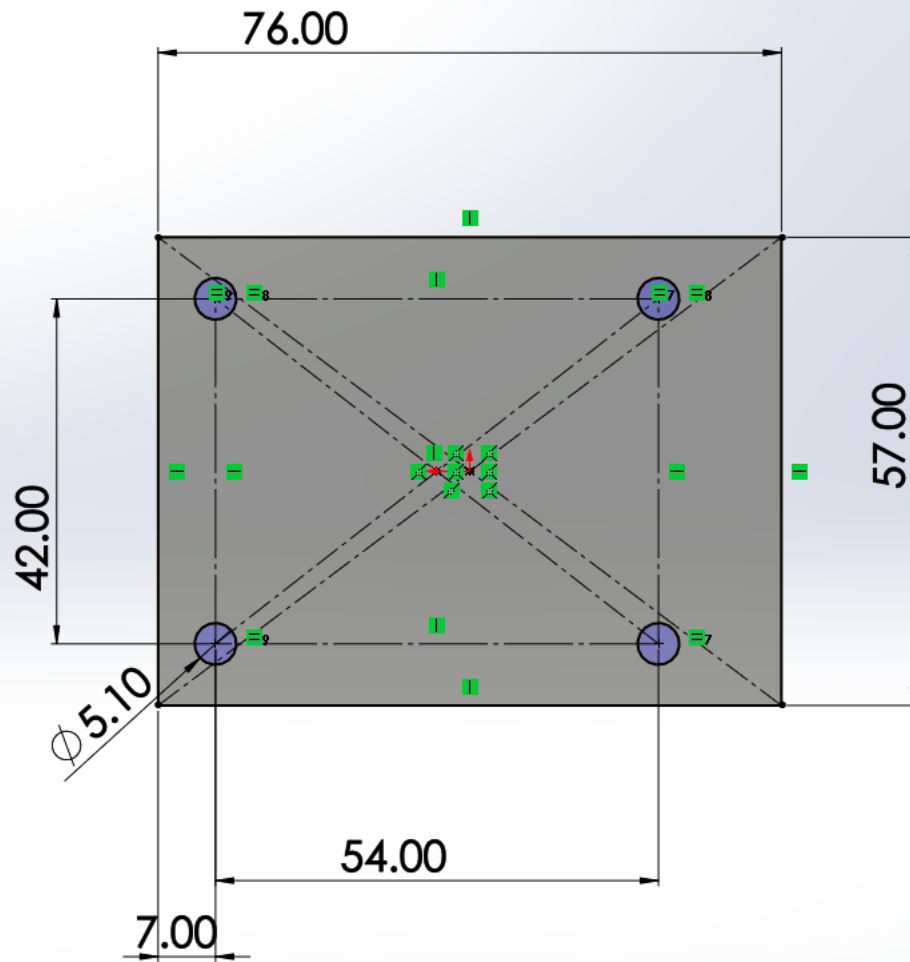


## Instructions 2: Baseplate

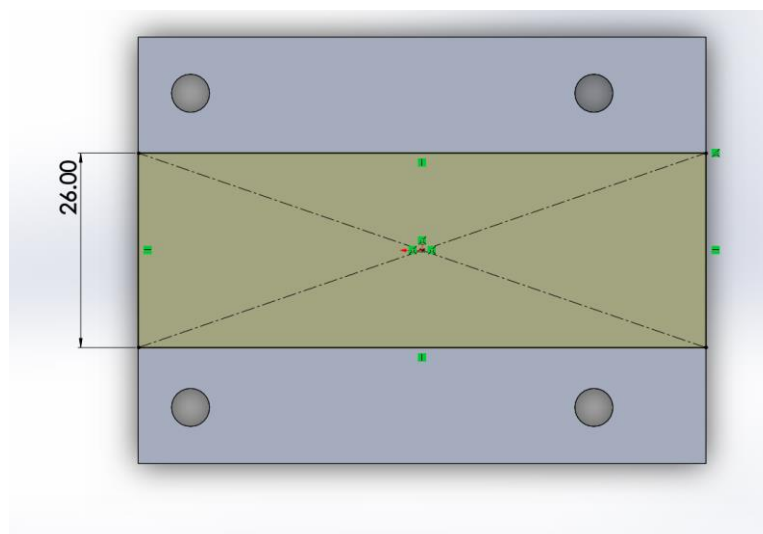
### Feature Manager Design Tree



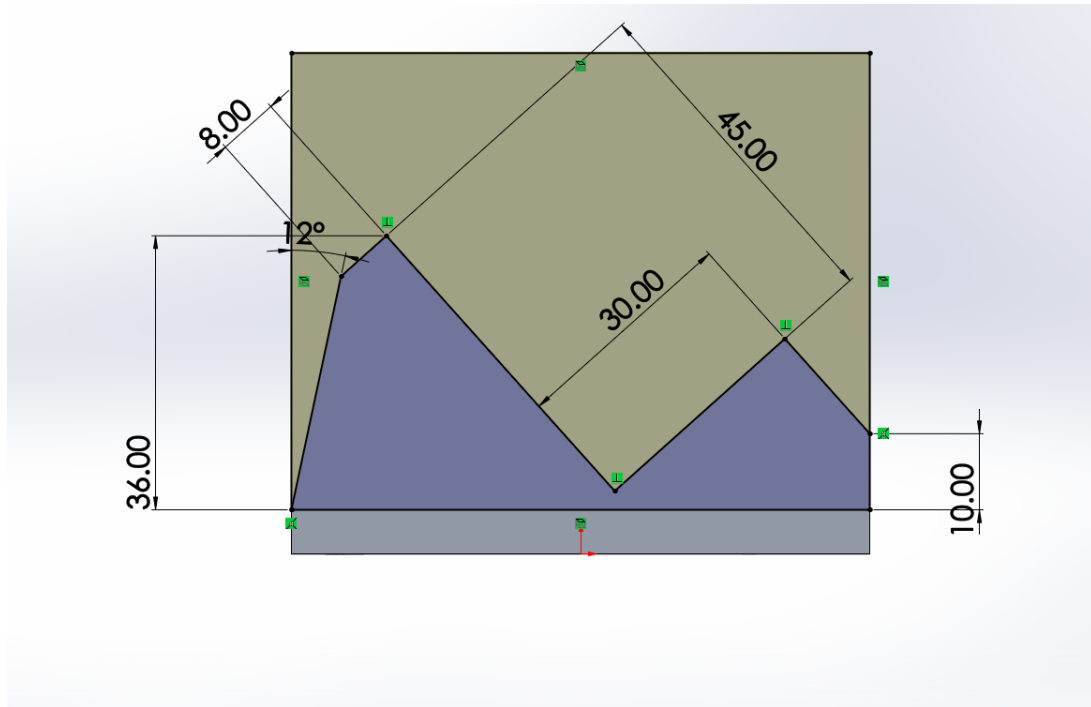
1. **Boss – Extrude Base:** Create sketch on top plane and extrude 5.80mm



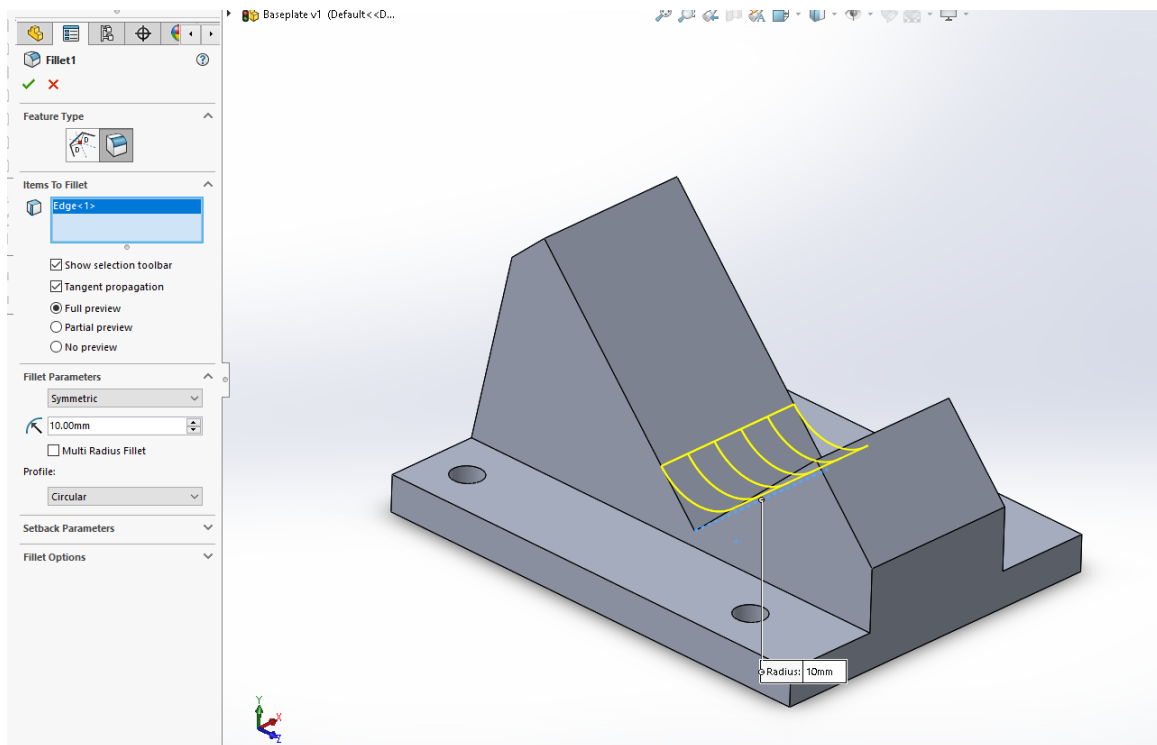
2. **Boss – Extrude Plate:** Create sketch on top of extrude base and extrude 60.00mm



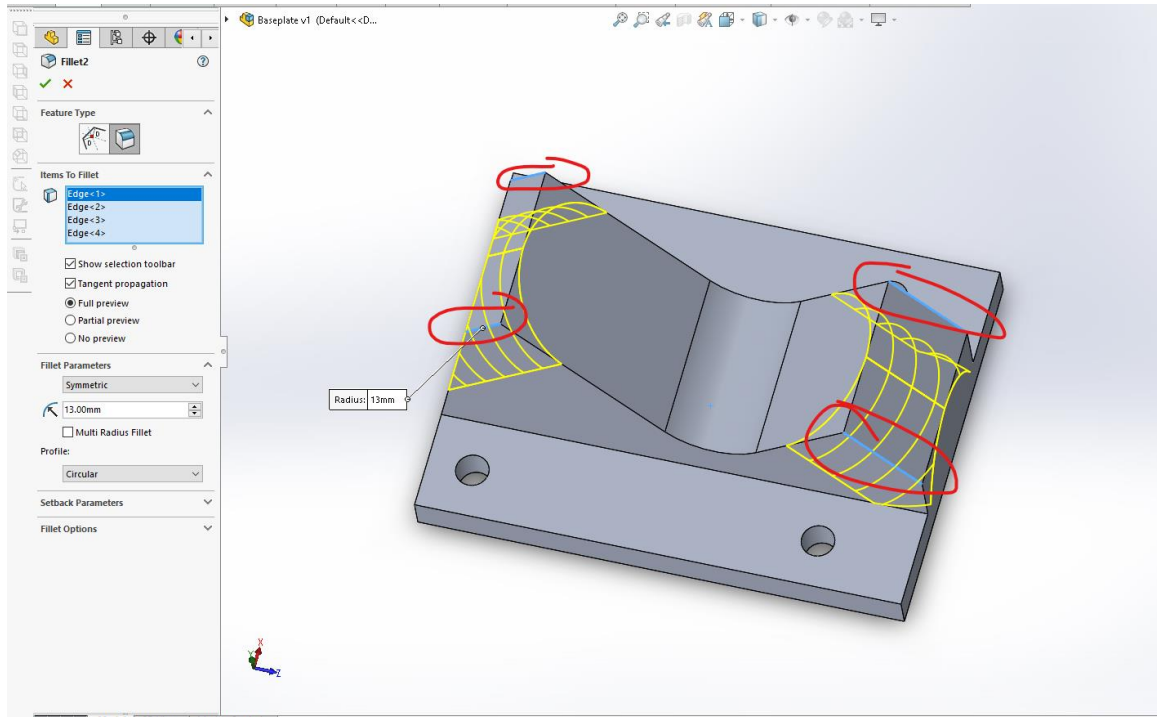
**3. Cut – Plate Shape:** Create sketch on edge of boss plate and cut through-all



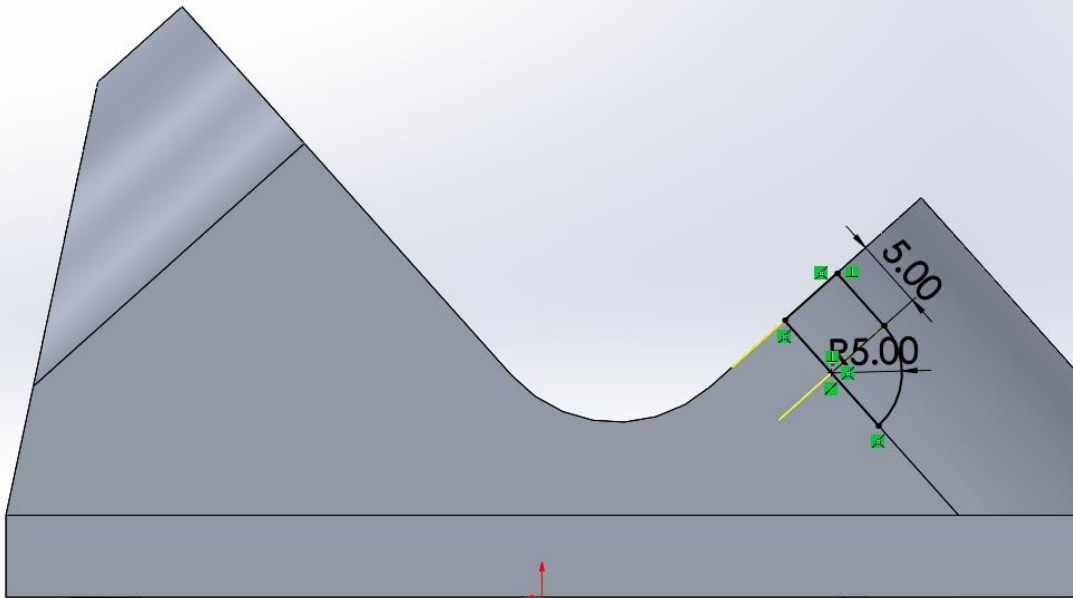
**4. Fillet 1:** Place a fillet in the middle. Enter 10mm



**5. Fillet 2: Create a fillet selecting the four edges shown. Enter 13.00mm**

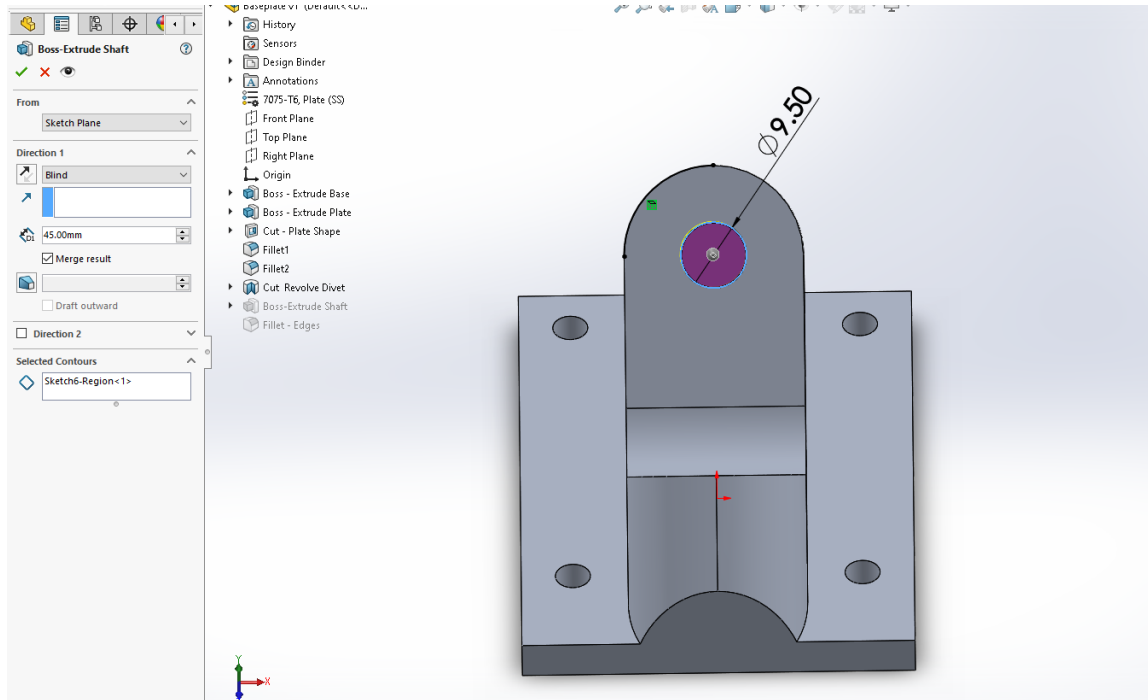


**6. Cut – Revolve Divot: Create a sketch on the right plane. Perform a revolved cut**

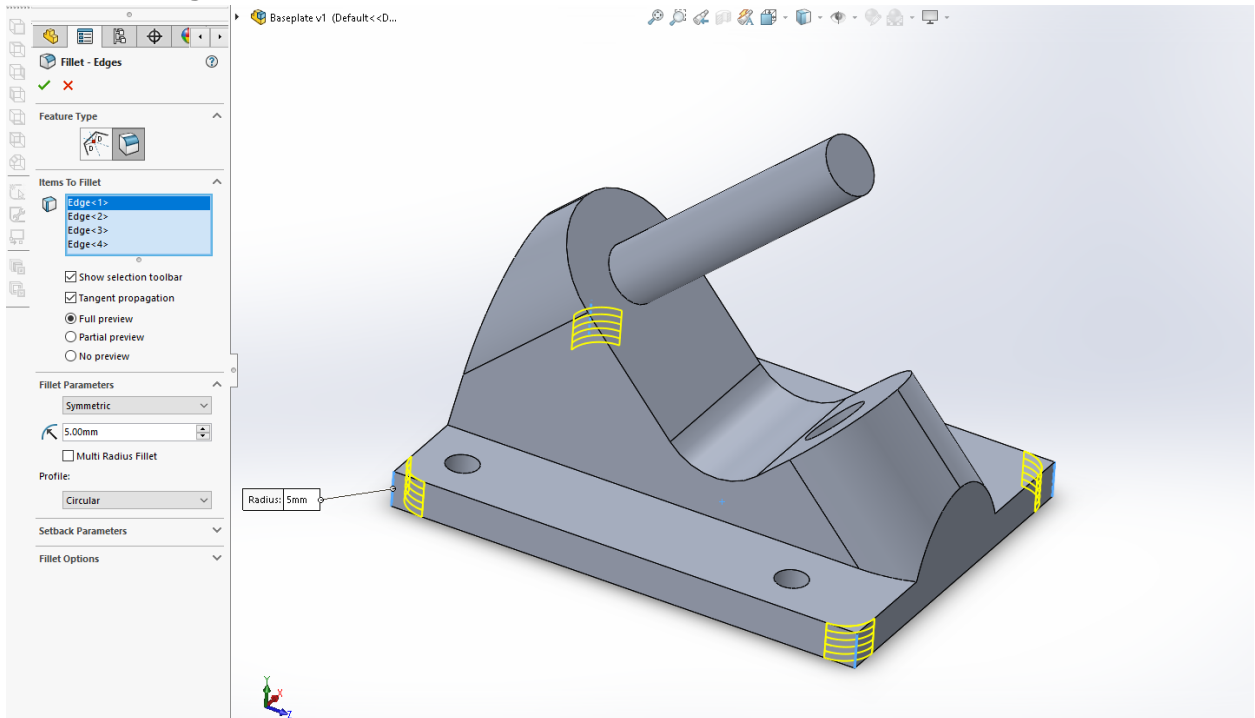




7. **Boss - Extrude Shaft:** Create sketch shown, concentric to fillet, and enter 45.00mm

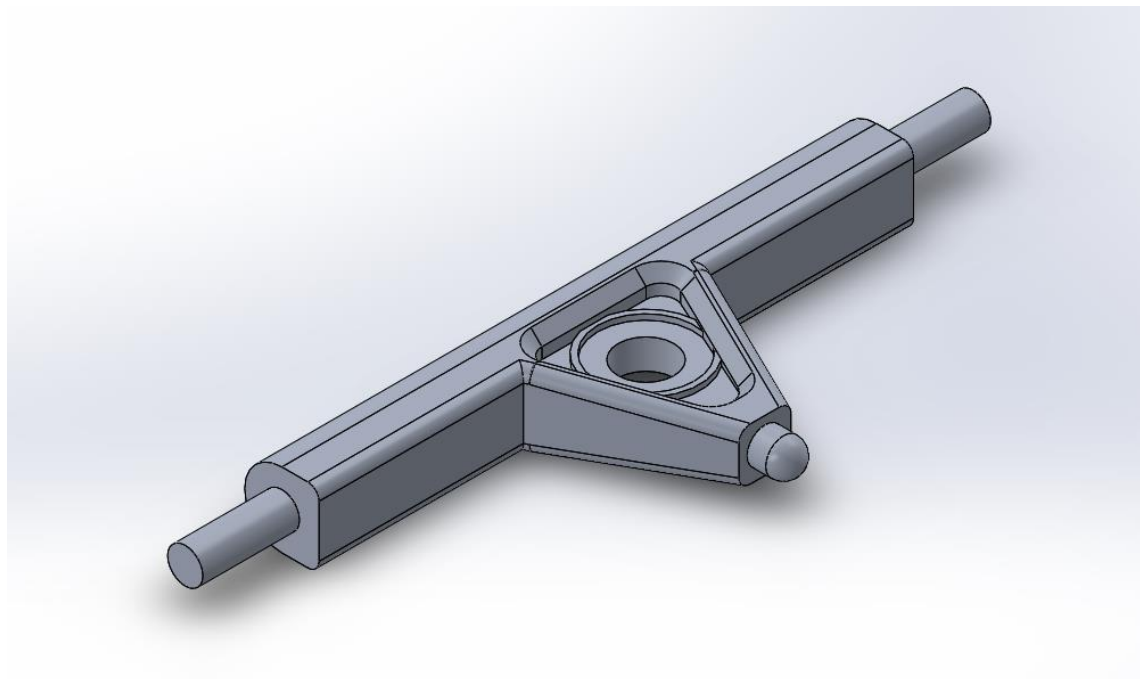
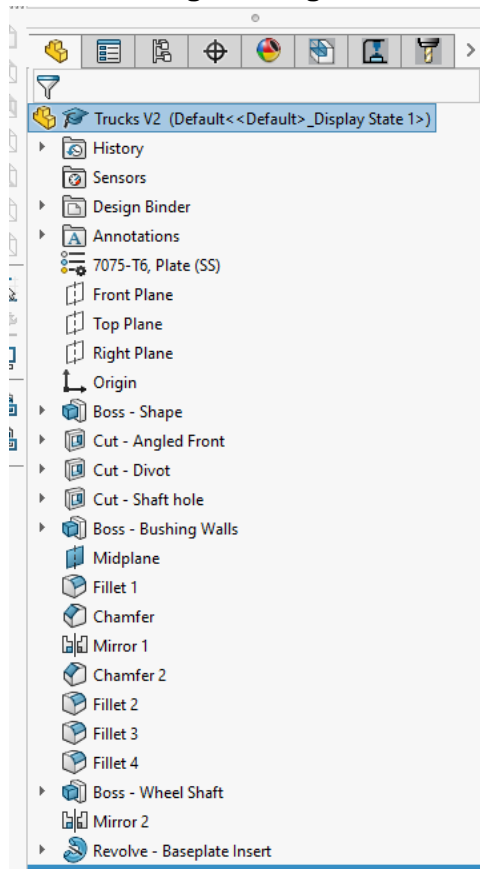


8. **Fillet - Edges:** Select four corners of base extrude and fillet. Enter 5.00mm

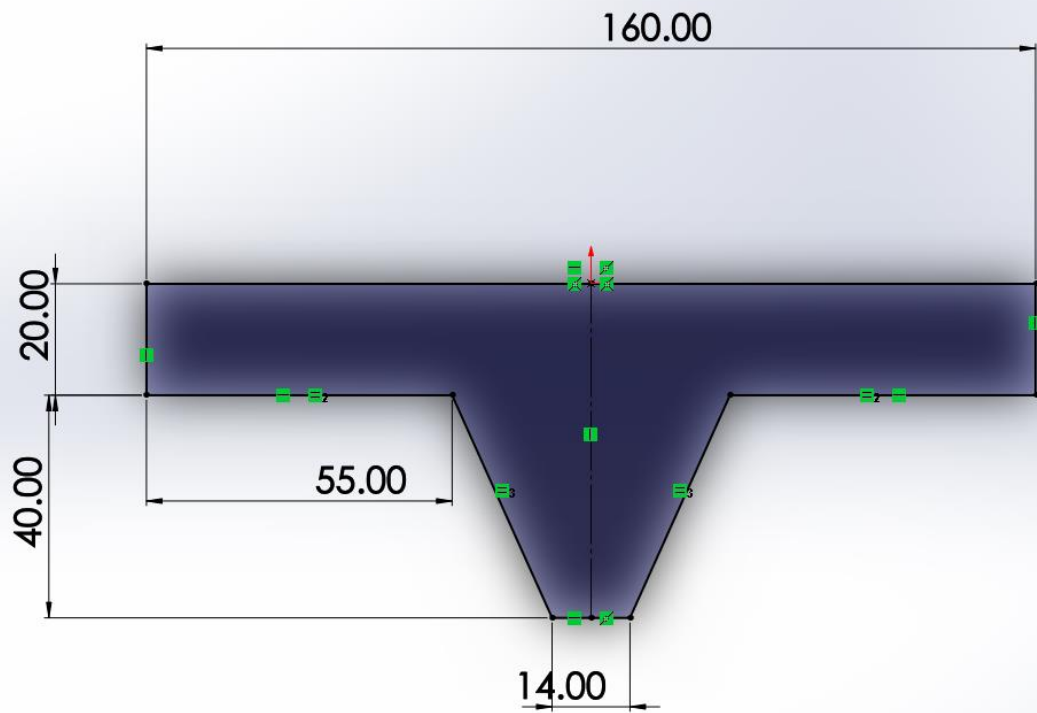


# Instructions 3: Trucks

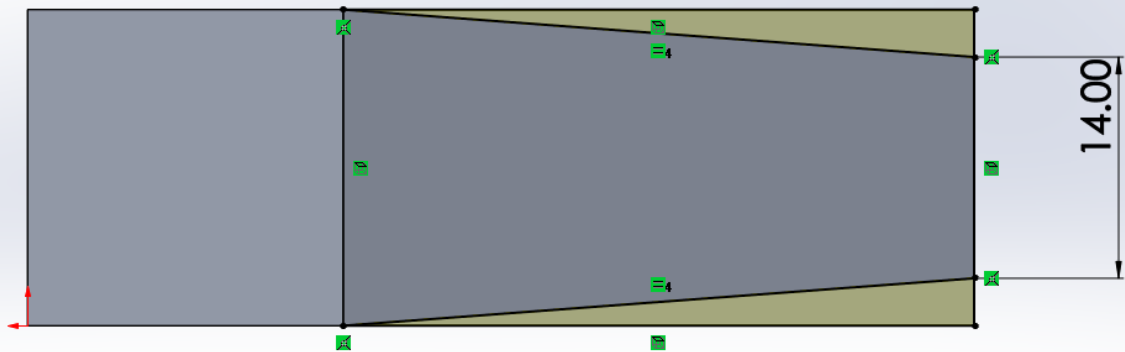
## Feature Design Manager Tree



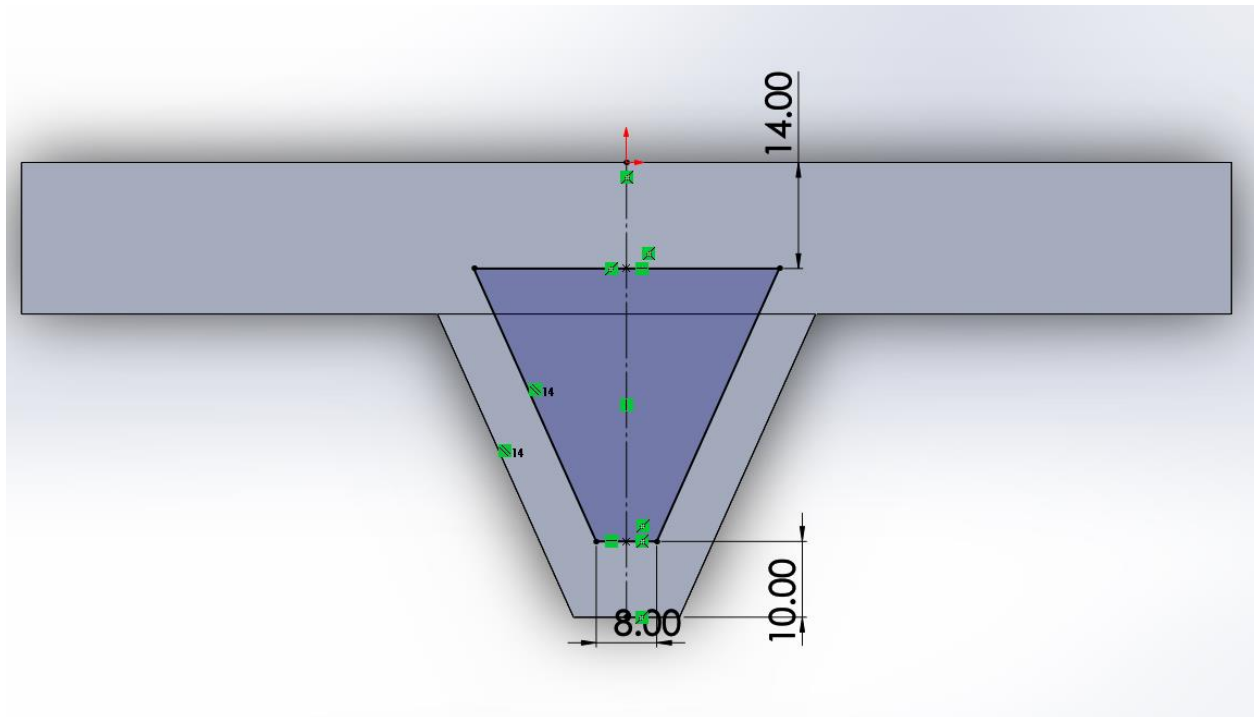
1. **Boss - Shape:** Create sketch on top plane. Extrude 0.4 cm.



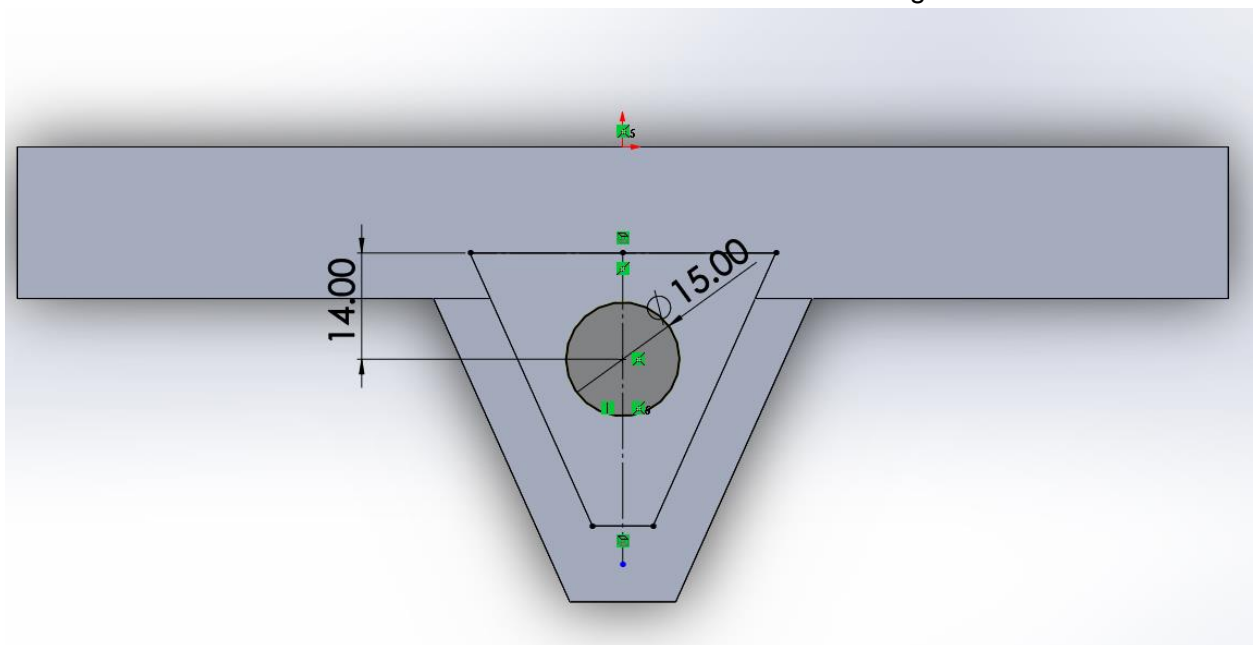
2. **Cut – Angled Front:** Create sketch on right plane. Through-all extrude cut



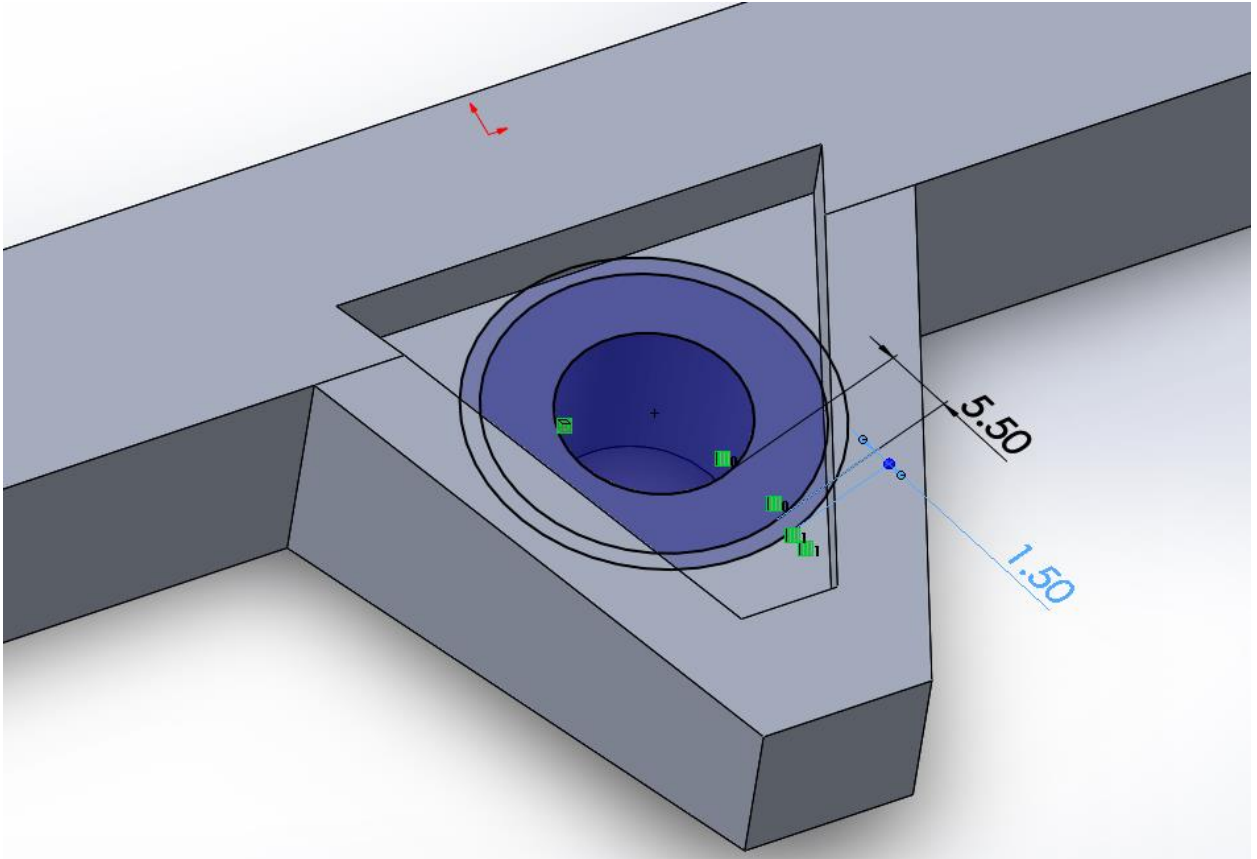
3. **Cut - Divot:** Create sketch, extrude cut 6.00mm



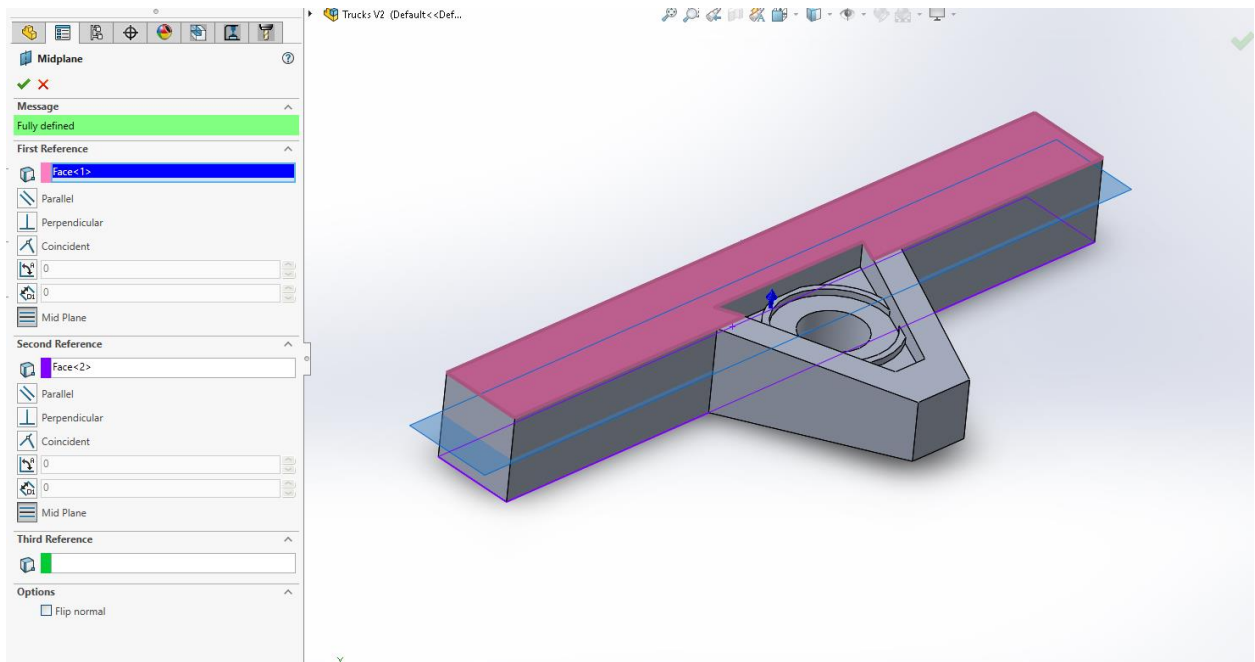
4. **Cut – Shaft Hole:** Create sketch on Cut – Divot and extrude cut through-all



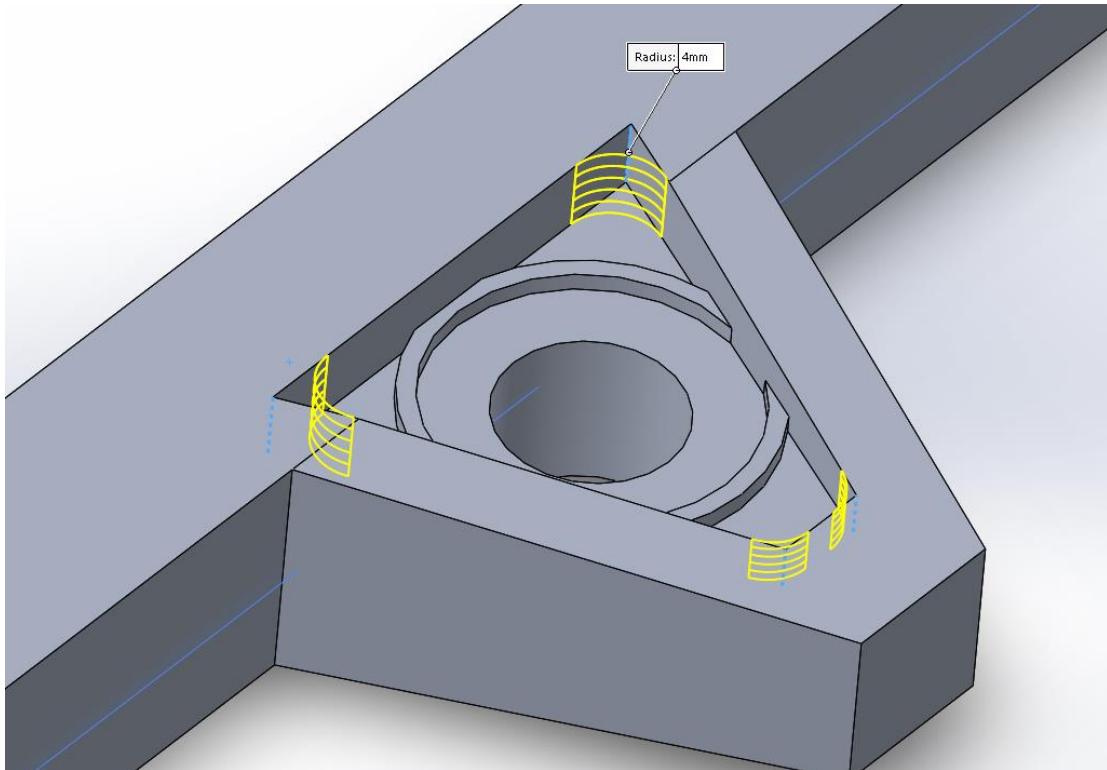
5. **Boss – Bushing Walls:** Create a circle with a diameter of 5.50mm, concentric to shaft hole, and offset circle by 1.50mm. Extrude by 1.50mm.



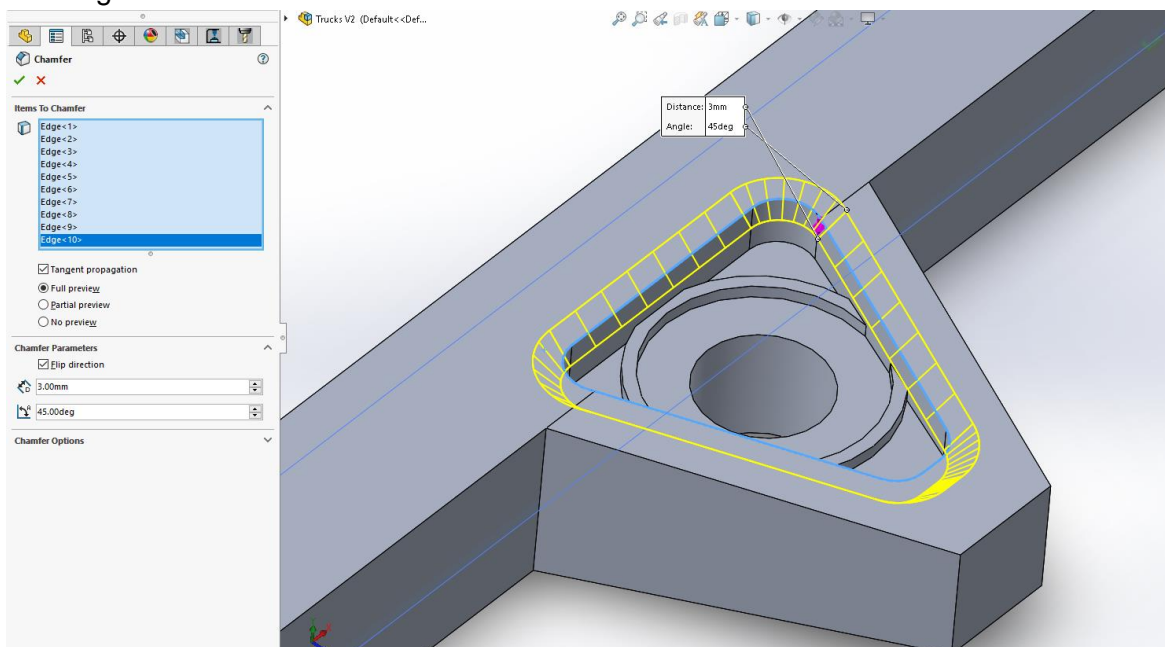
6. **Mid-Plane:** Create a midplane between the top and bottom surfaces.



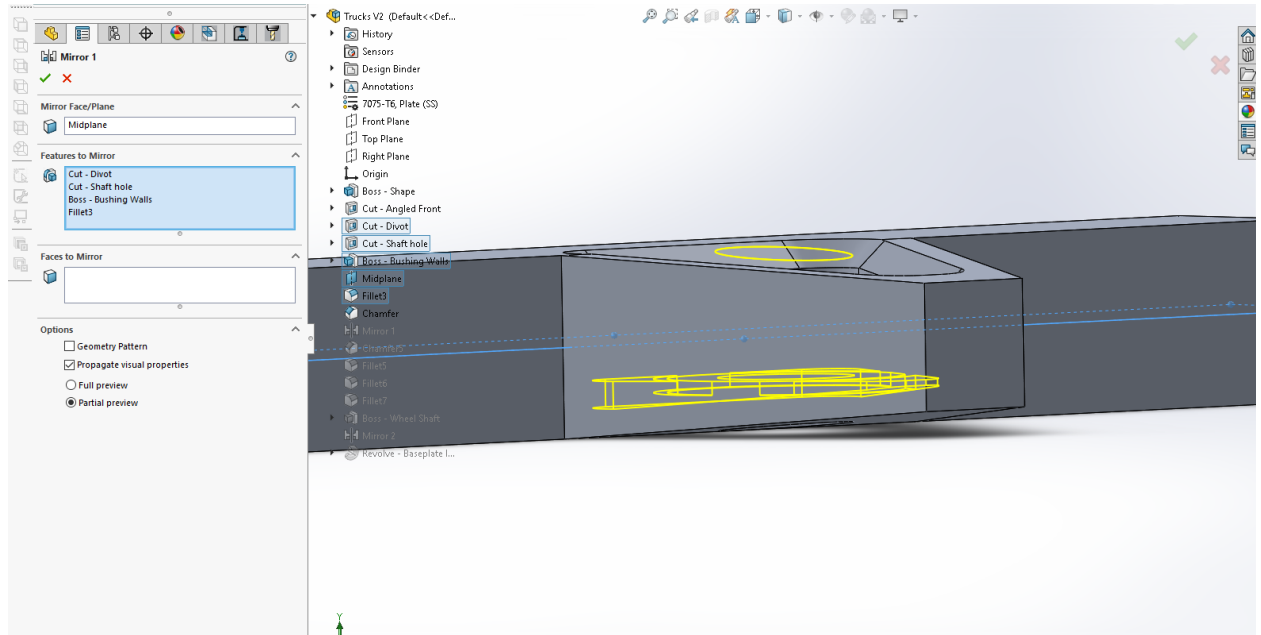
7. **Fillet 1:** Select these edges and fillet them, enter 4.00mm



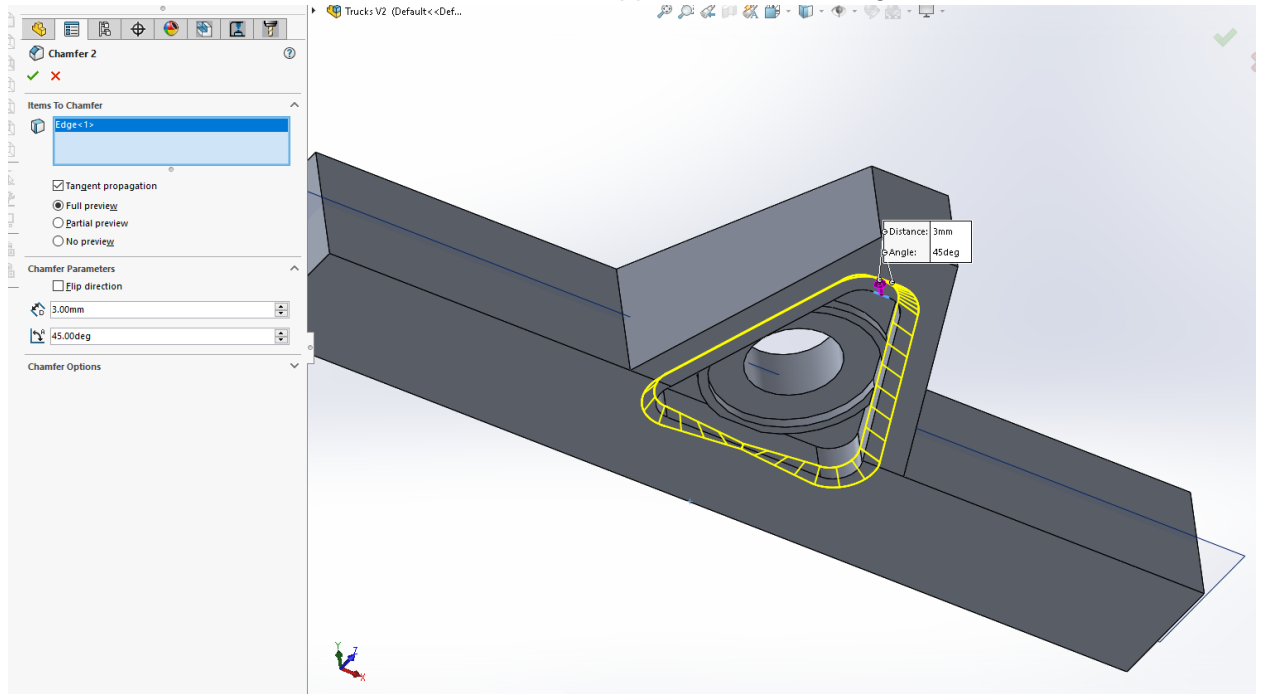
8. **Chamfer:** Select the surrounding edges of the divot and chamfer. Enter 3.00m @ 45 degrees



**9. Mirror 1:** Mirror the Divot, shaft Hole, Bushing Walls, and Fillet features across the midplane.

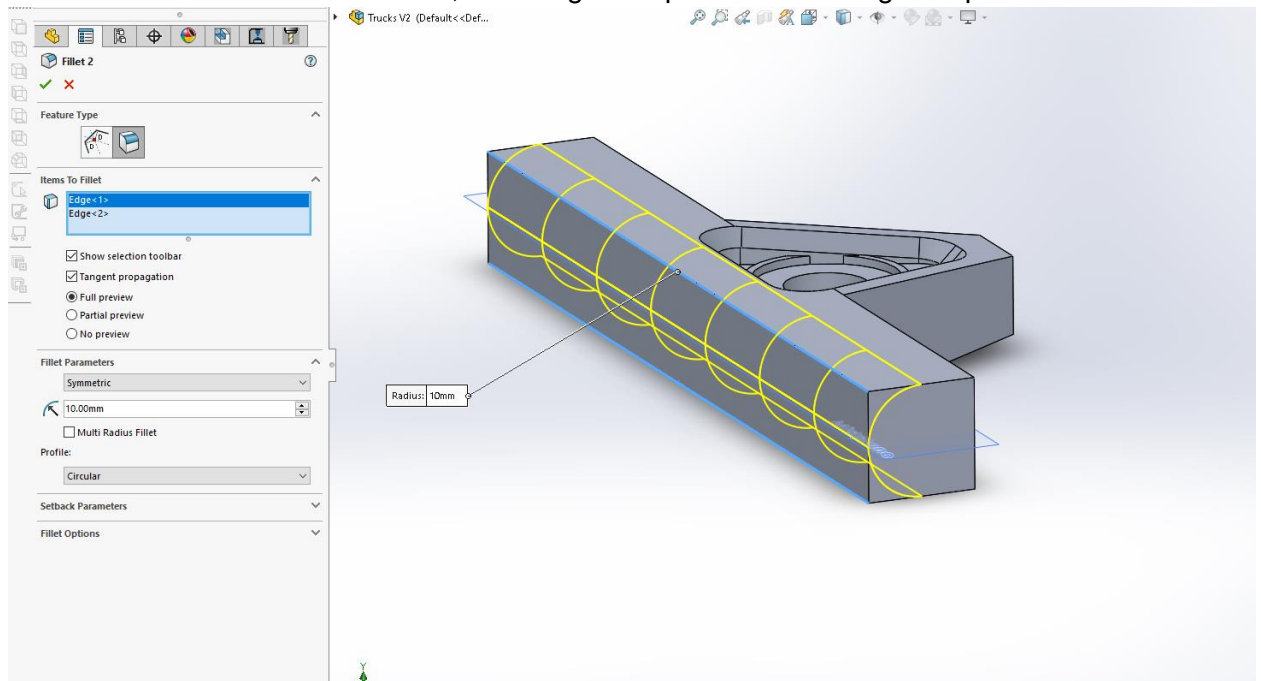


**10. Chamfer 2:** Perform a similar chamfer on the opposite mirrored edge.

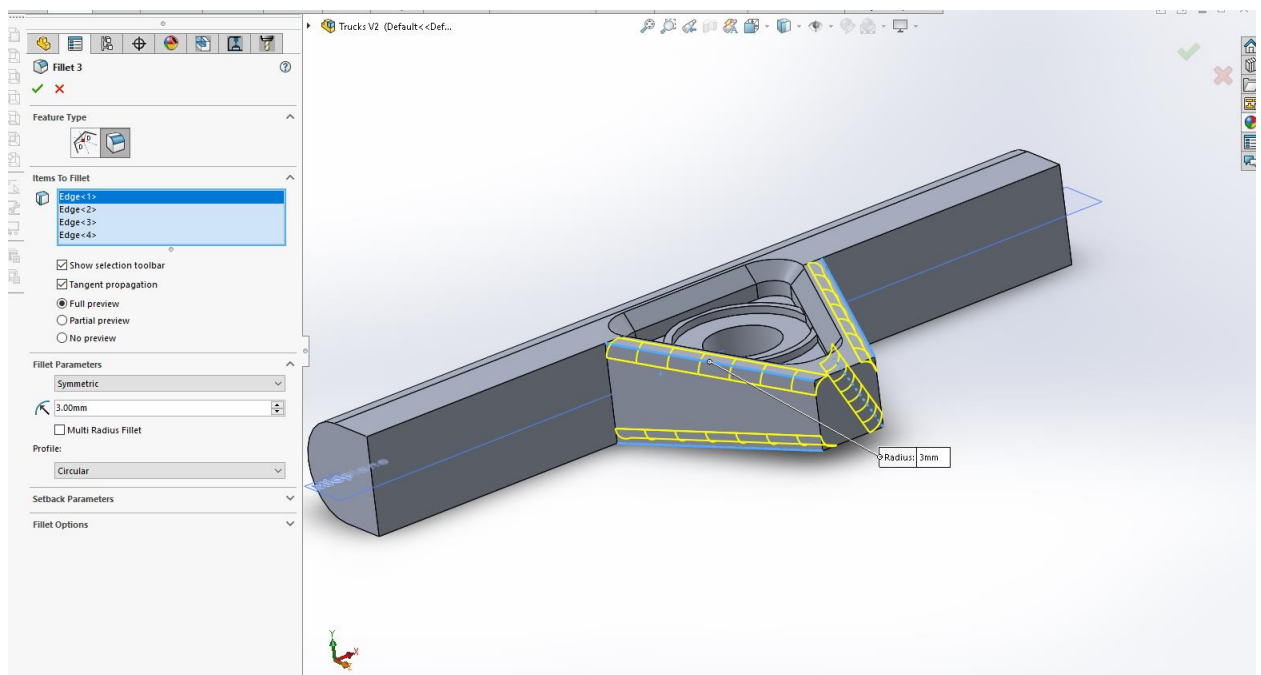




**11. Fillet 2:** Create a fillet on the back, selecting the top and bottom edges. Input 10.00mm.

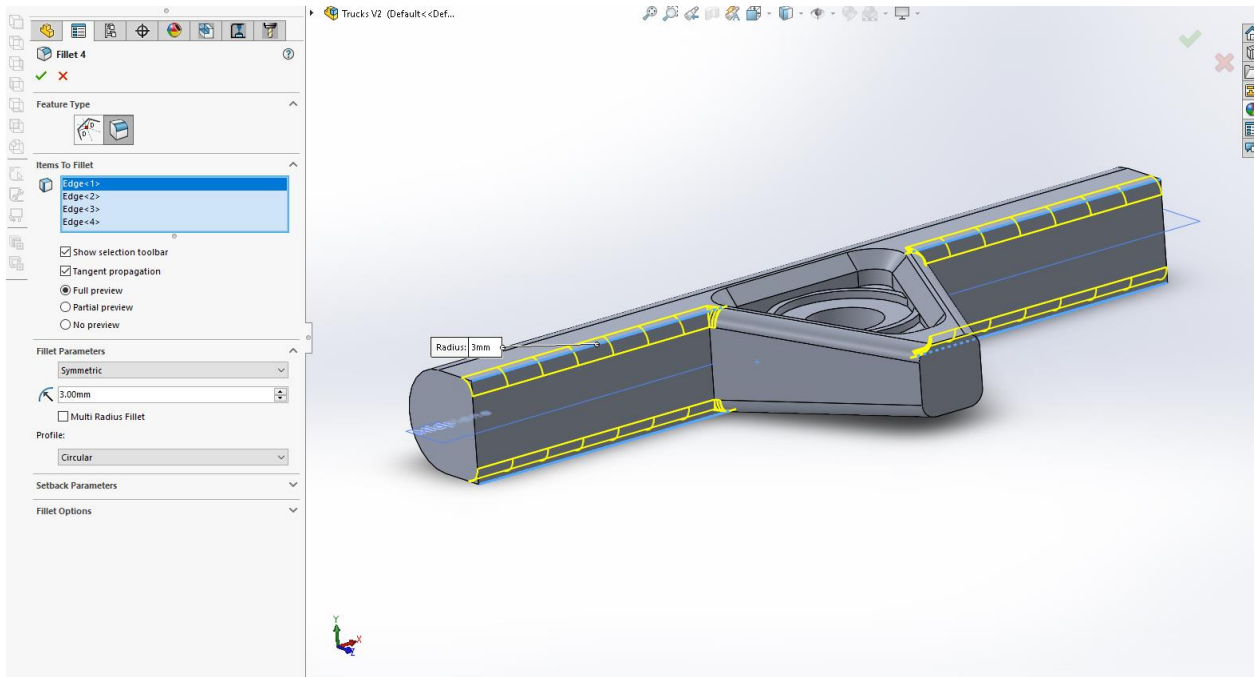


**12. Fillet 3:** Perform a fillet on the front nose of the trucks. Enter 3.00mm

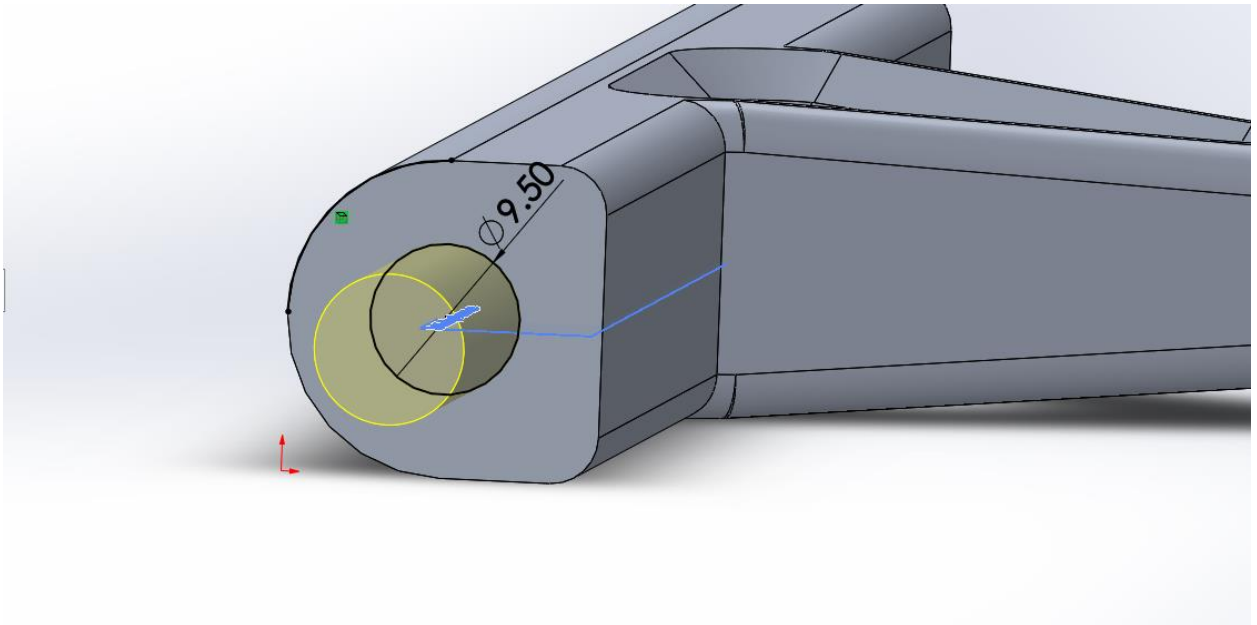




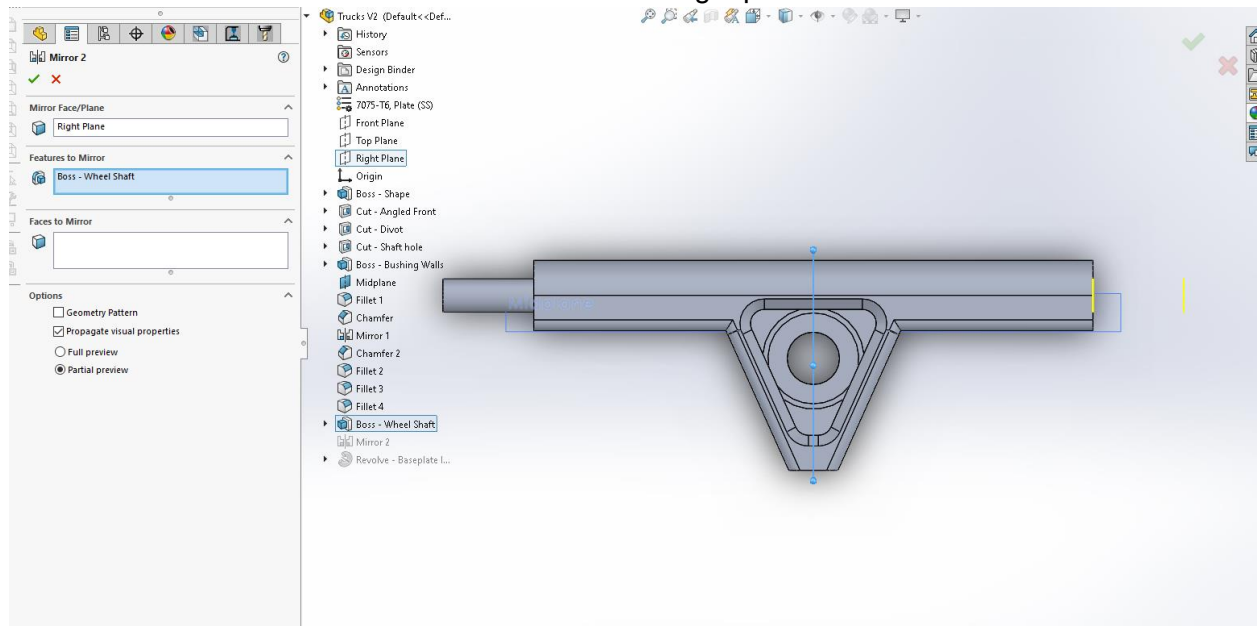
**13. Fillet 4:** Perform a fillet on the front edges. Enter 3.00mm



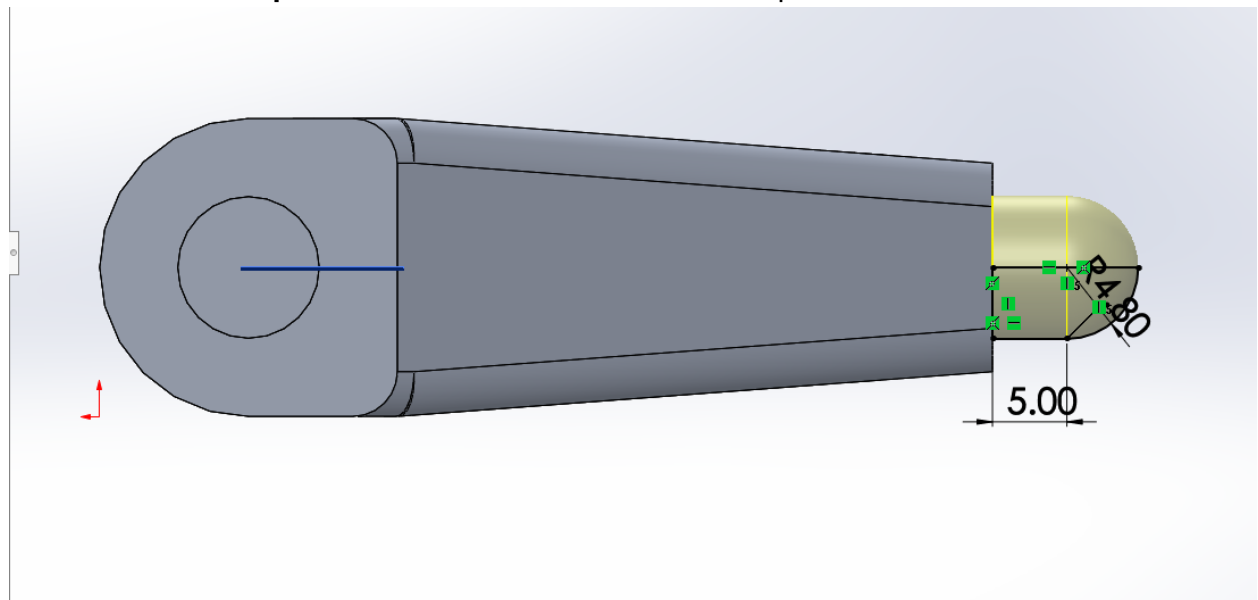
**14. Boss – Wheel Shaft:** Create sketch, concentric to the fillet, and extrude 9.50mm



## 15. Mirror 2: Mirror Boss – Wheel Shaft across the right plane



## 16. Revolve – Baseplate Insert: Create sketch below and perform a revolve



## Design Binder

### Design Journal

**File Name:** Longboard Assembly.SLDASM

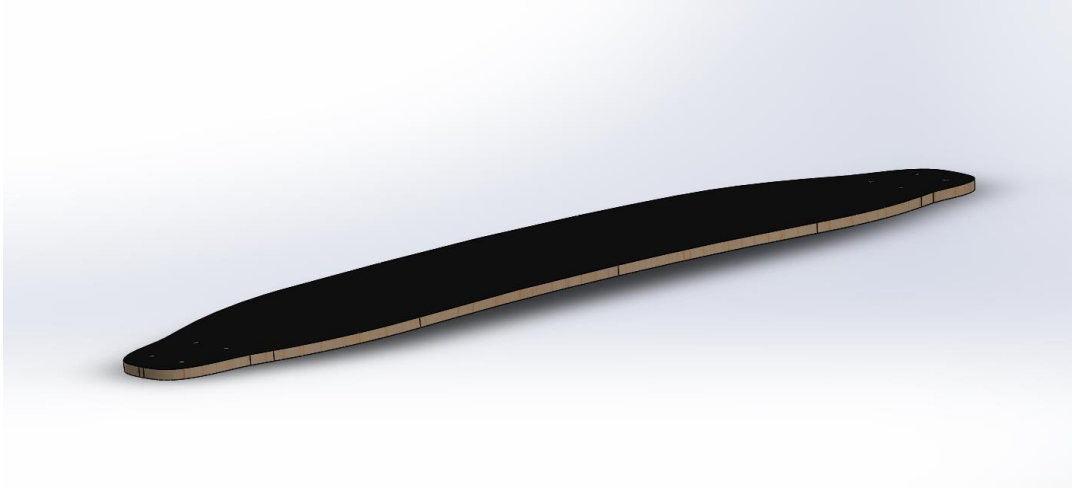
**Description:** Longboard

**Material:** Poplar Wood, ABS, Polyurethane, 7075-T6 Plate (SS),  
Cast Carbon Steel

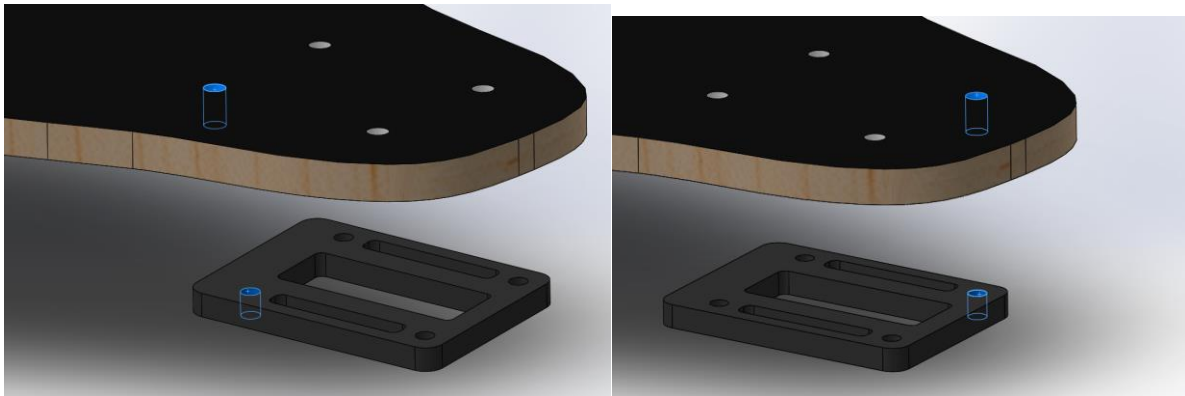
This longboard uses poplar wood for the deck to provide rigidity and flexibility when riding. The riser is made from ABS for a strong and simple part. Polyurethane is used in the bushings and wheels to provide a little bit of compression and cushioning. 7075-T6 Plate (SS) Aluminum Alloy is used in the trucks and baseplate for an extremely sturdy and rigid material for an important component of the assembly. The screw and nuts are made out of cast carbon steel. This product simply works by stepping on the board and allowing one self to roll smoothly forward while leaning one's weight to curve left or right.

# Assembly Instructions

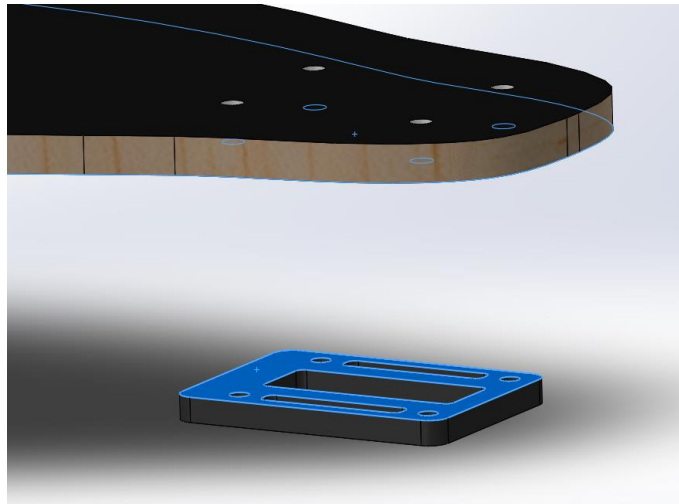
1. **Insert Component:** Insert the deck into the assembly



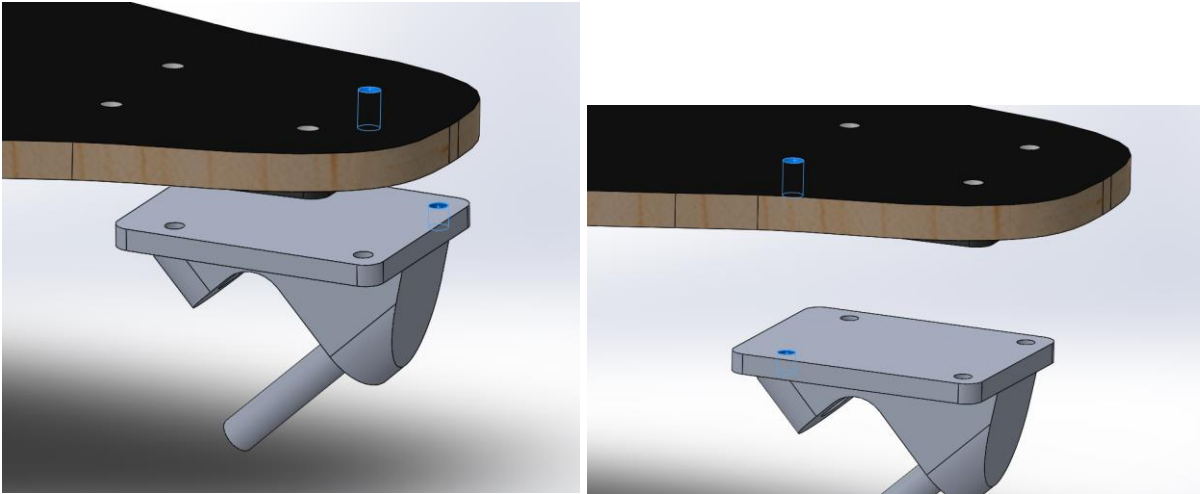
2. **Concentric mates:** Create concentric mates between the following faces of the **deck** and **riser**



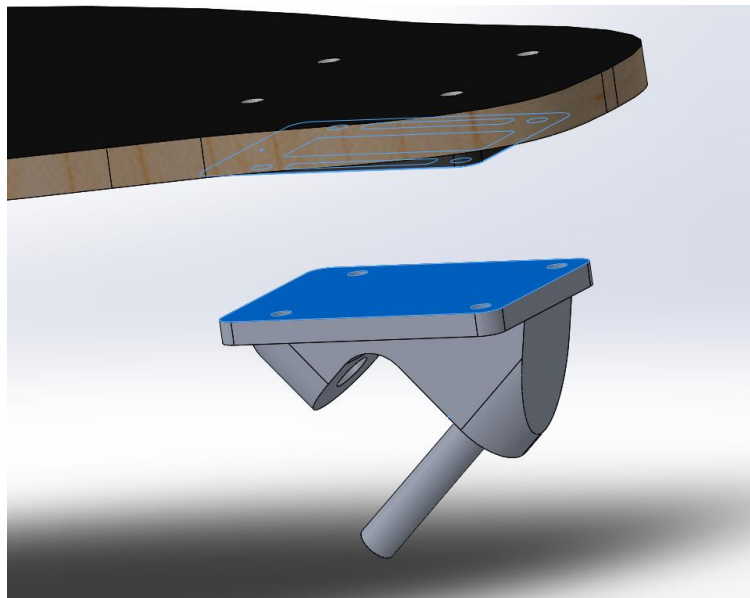
3. **Tangent Mate:** Create tangent mate between faces on the **deck** and **riser**



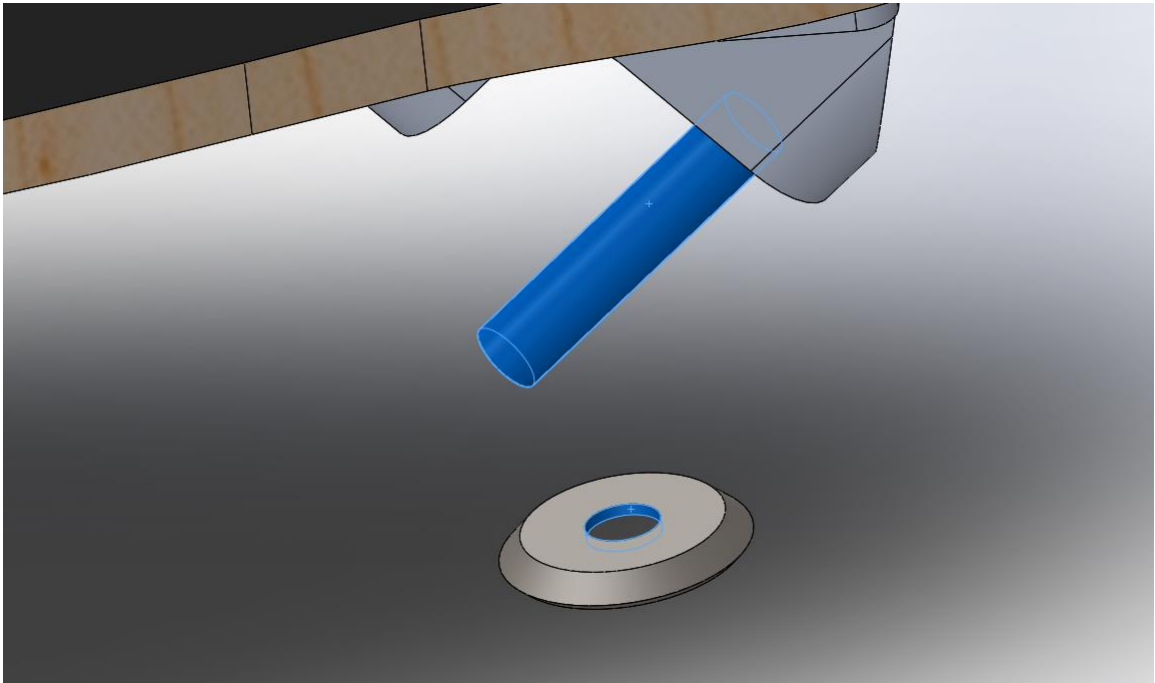
4. **Concentric mates:** Create concentric mates between the following faces of the **deck** and **baseplate**



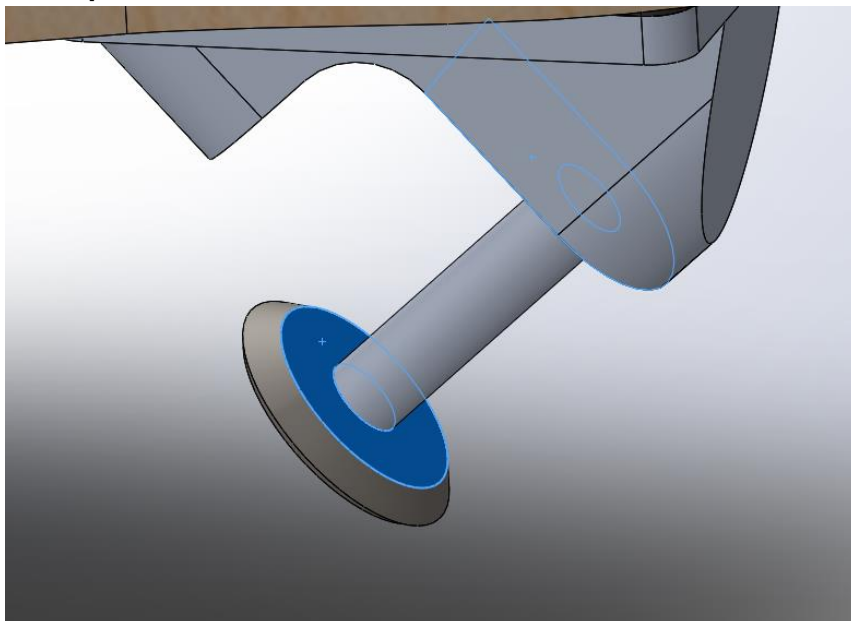
5. **Coincident mate:** Create coincident mate between following faces of the **riser** and **baseplate**



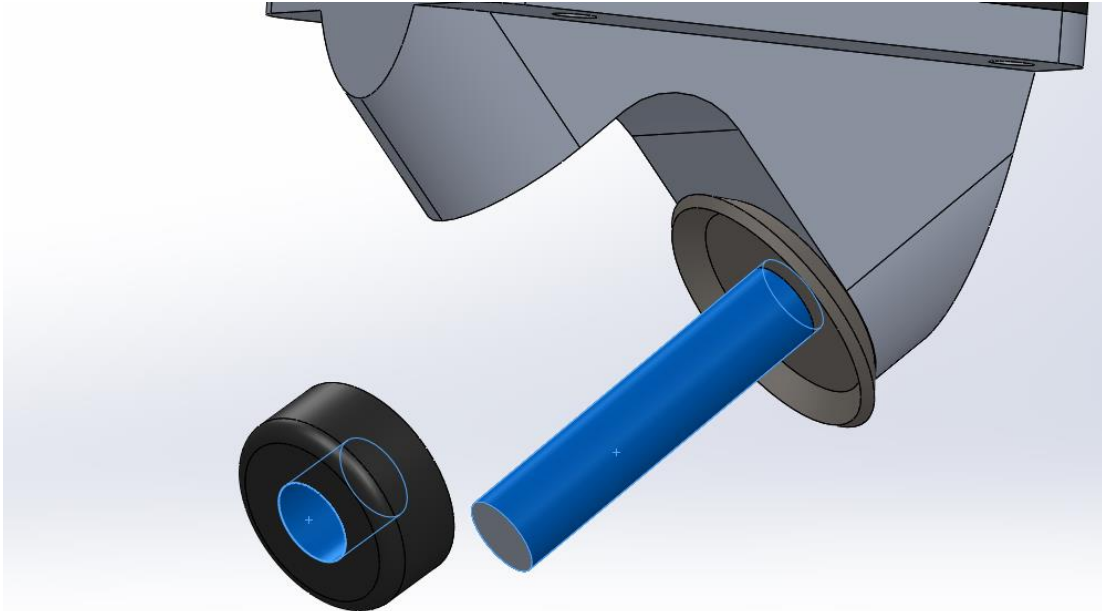
6. **Concentric mate:** Create concentric mate between the following faces of the **bushing cap** and the **baseplate**.



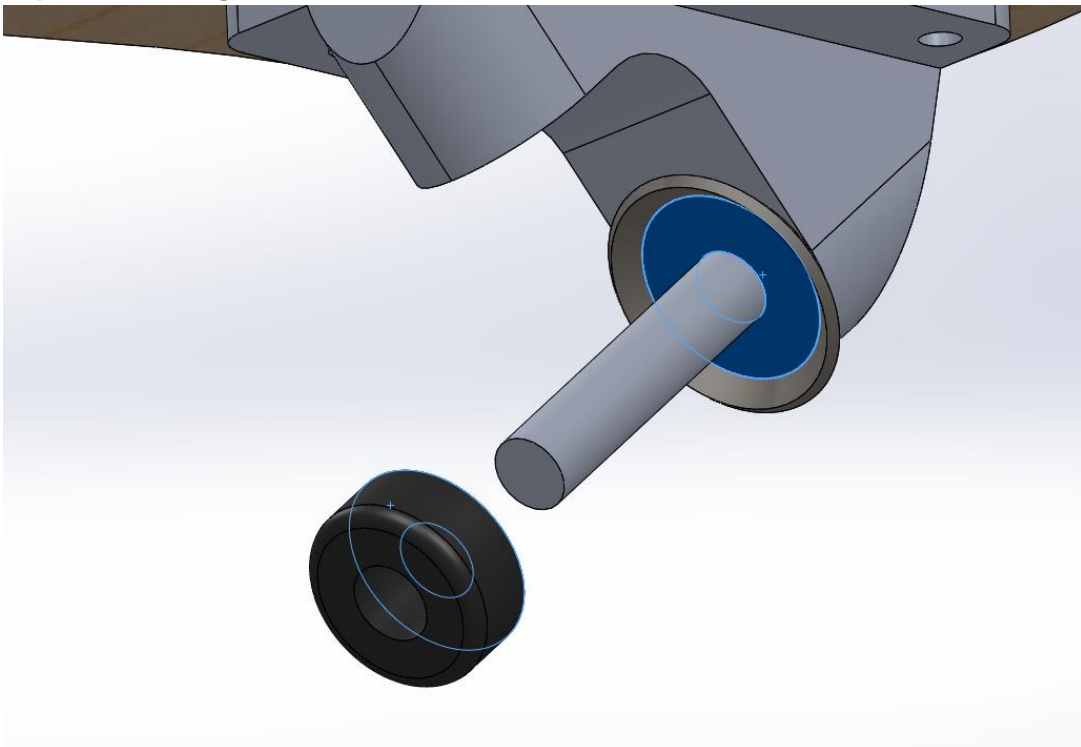
7. **Coincident mate:** Create coincident mate between the following faces of the **bushing cap** and the **baseplate**.



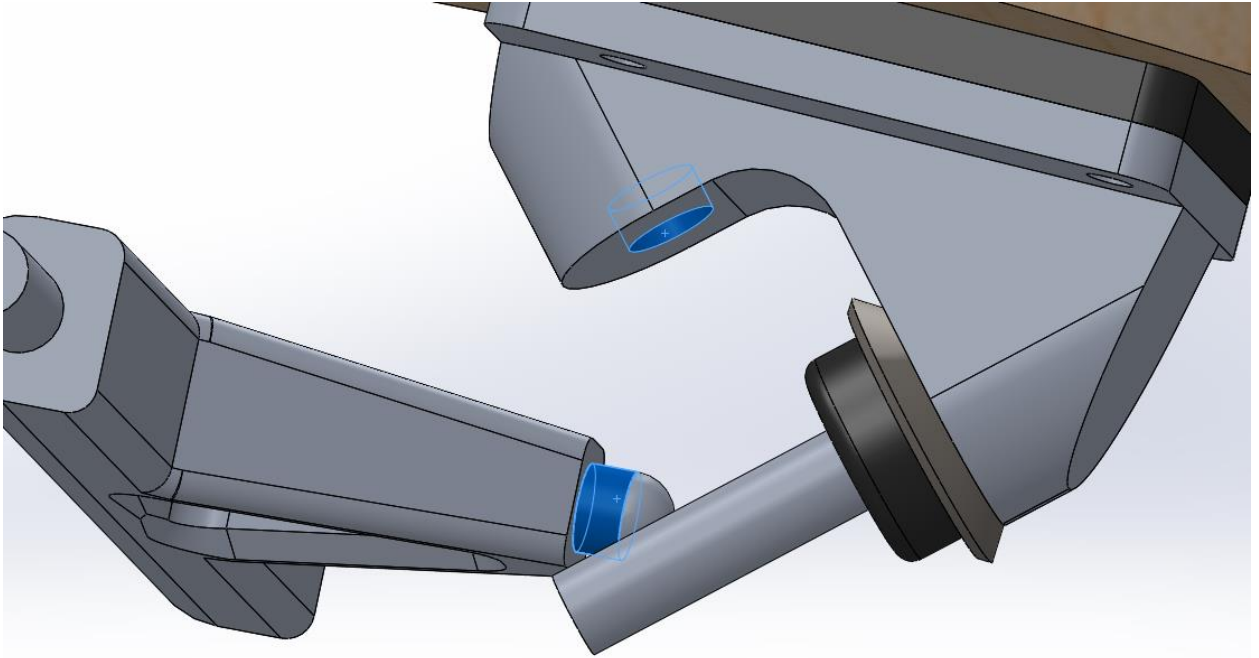
8. **Concentric mate:** Create concentric mate between the following faces on the **bushing cap** and **baseplate**



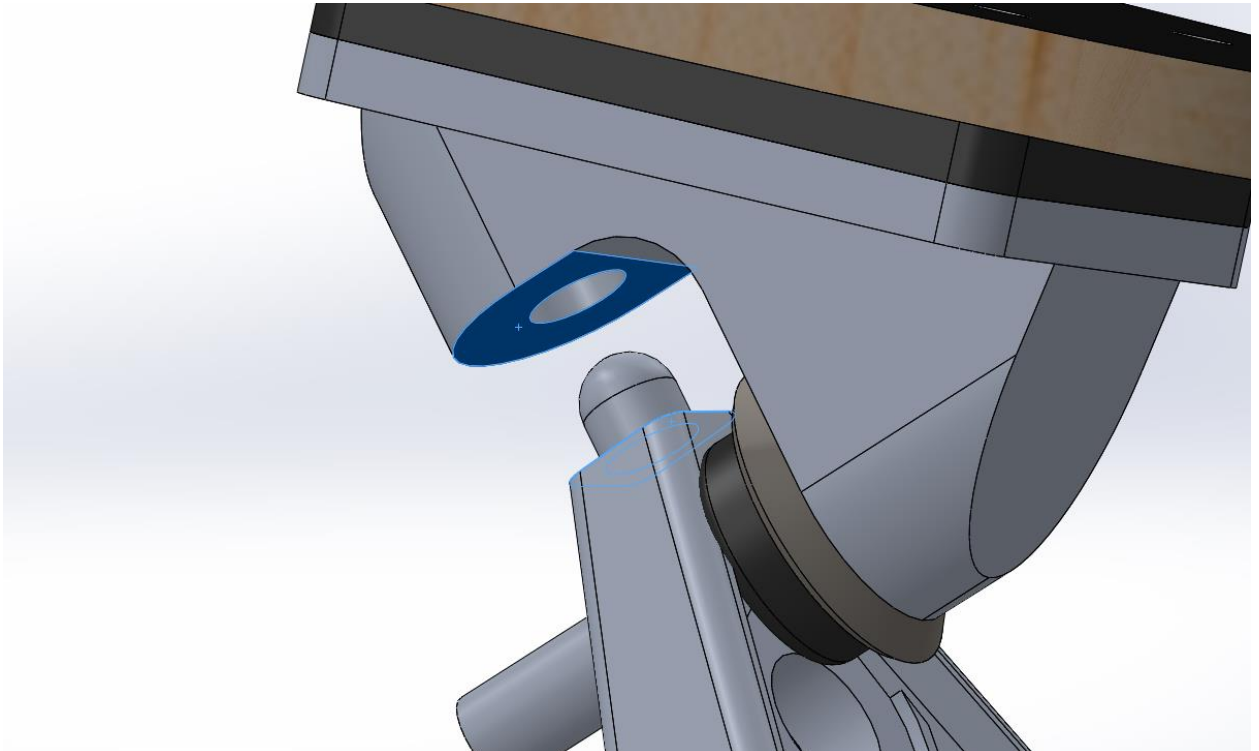
9. **Coincident mate:** Create coincident mate between the following faces on the **bushing cap** and **bushing**



10. **Concentric mate:** Create concentric mate between the revolve on the **trucks** and the revolve on the **baseplate**

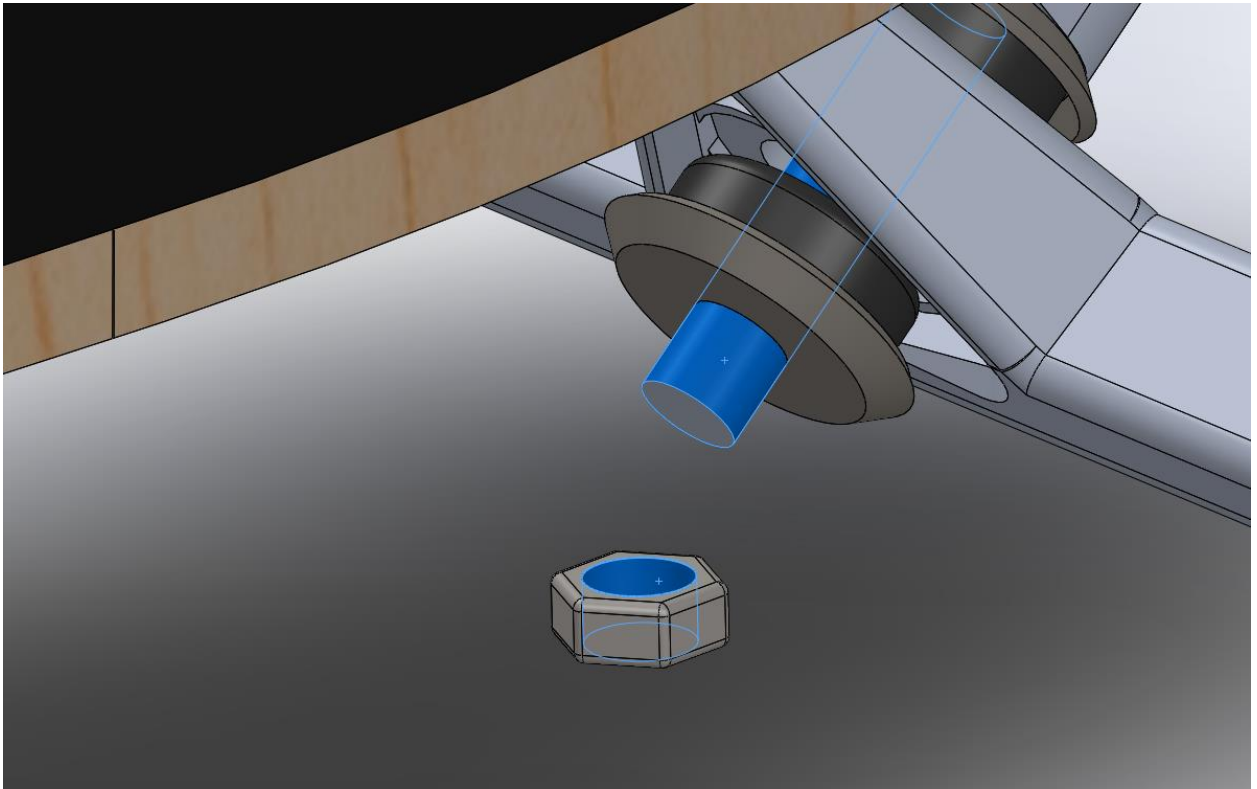


11. **Coincident mate:** Create coincident mate between the following faces on the **trucks** and the **baseplate**

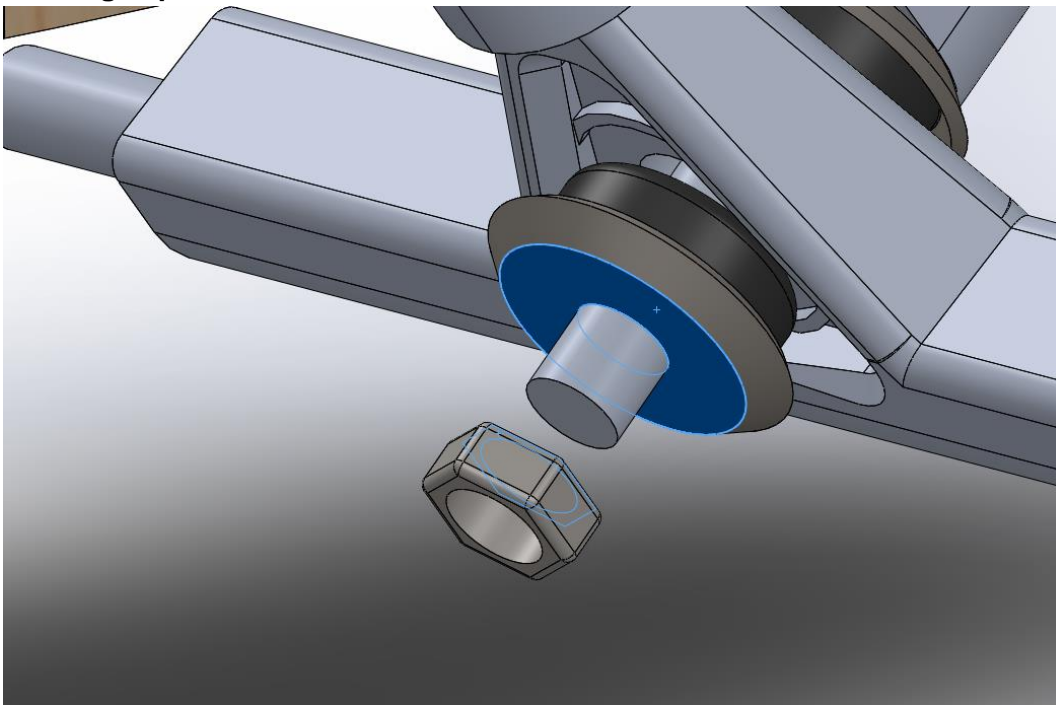




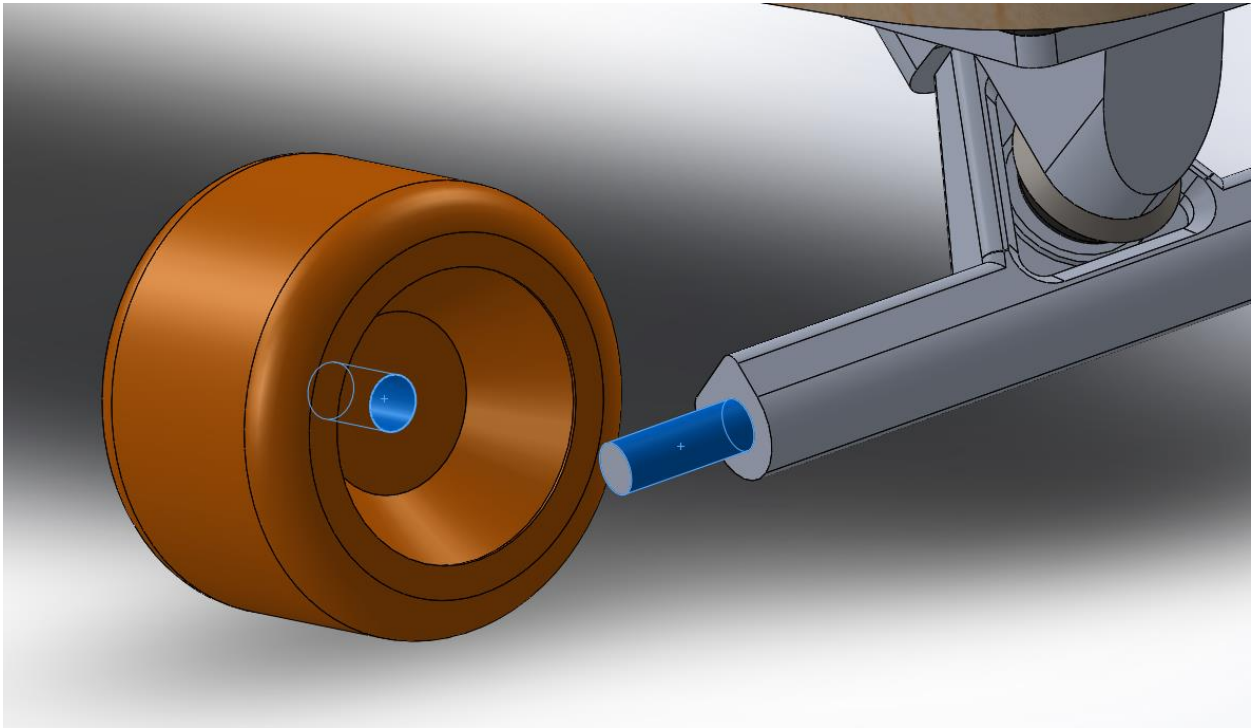
**12. Concentric mate:** Create concentric mate between the **Hex Nut** and the **Baseplate**



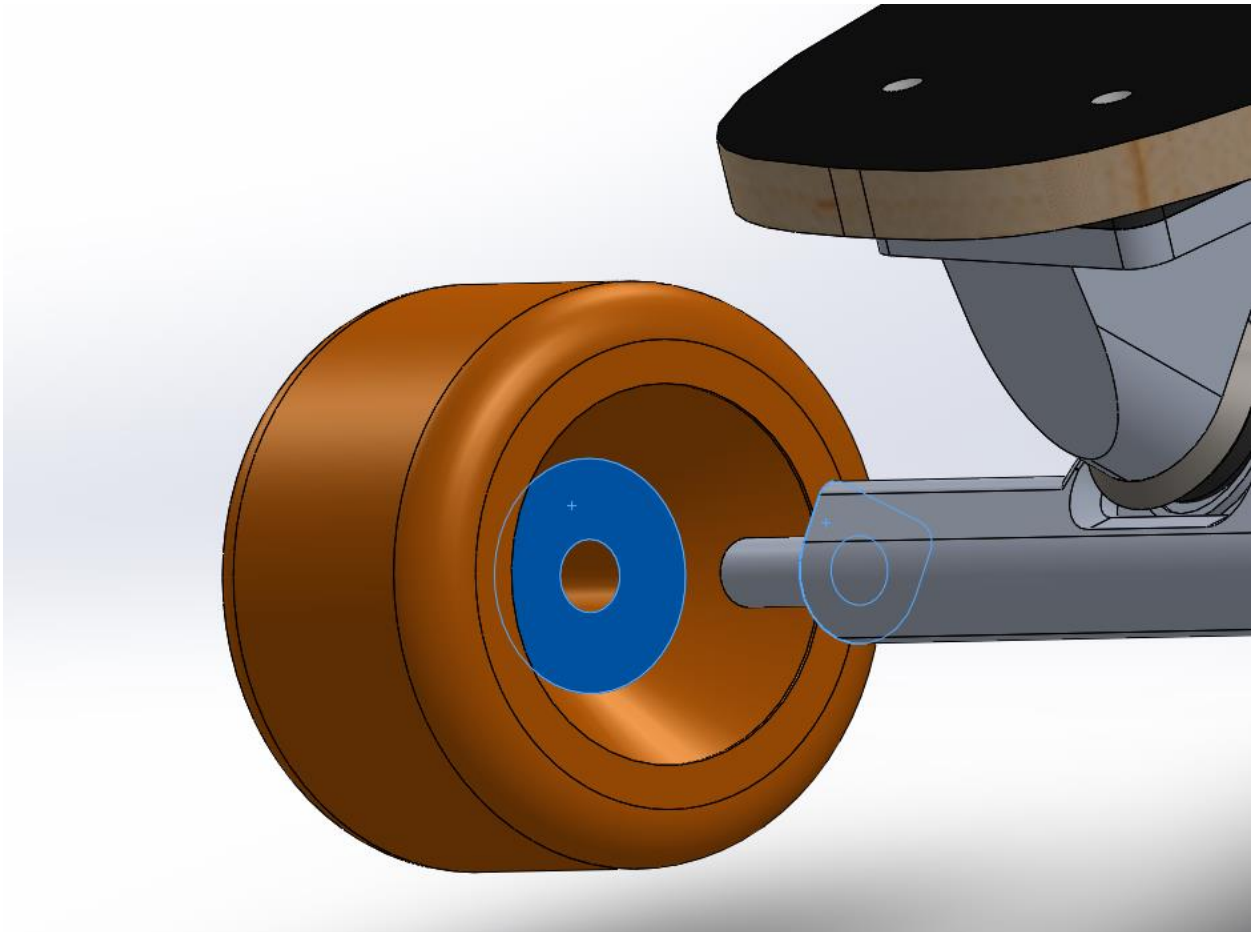
**13. Coincident mate:** Create coincident mate between following faces on the **Hex Nut** and **bushing cap**



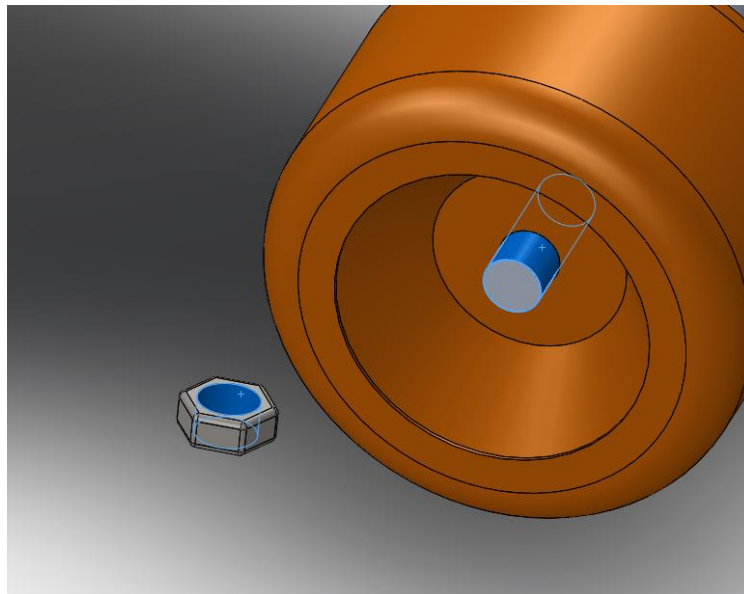
14. **Concentric mate:** Create concentric mate between the **wheel** and **trucks**



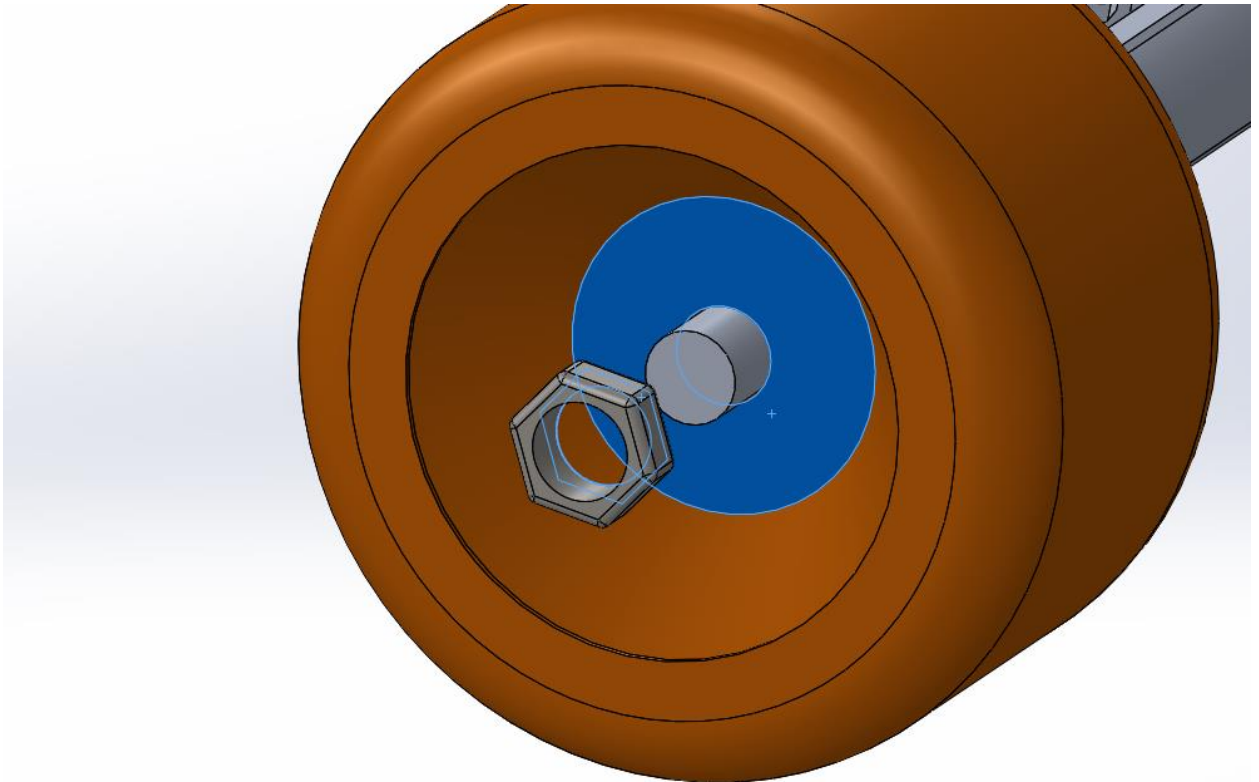
15. **Coincident mate:** Create coincident mate between the following faces on the **wheel** and **trucks**



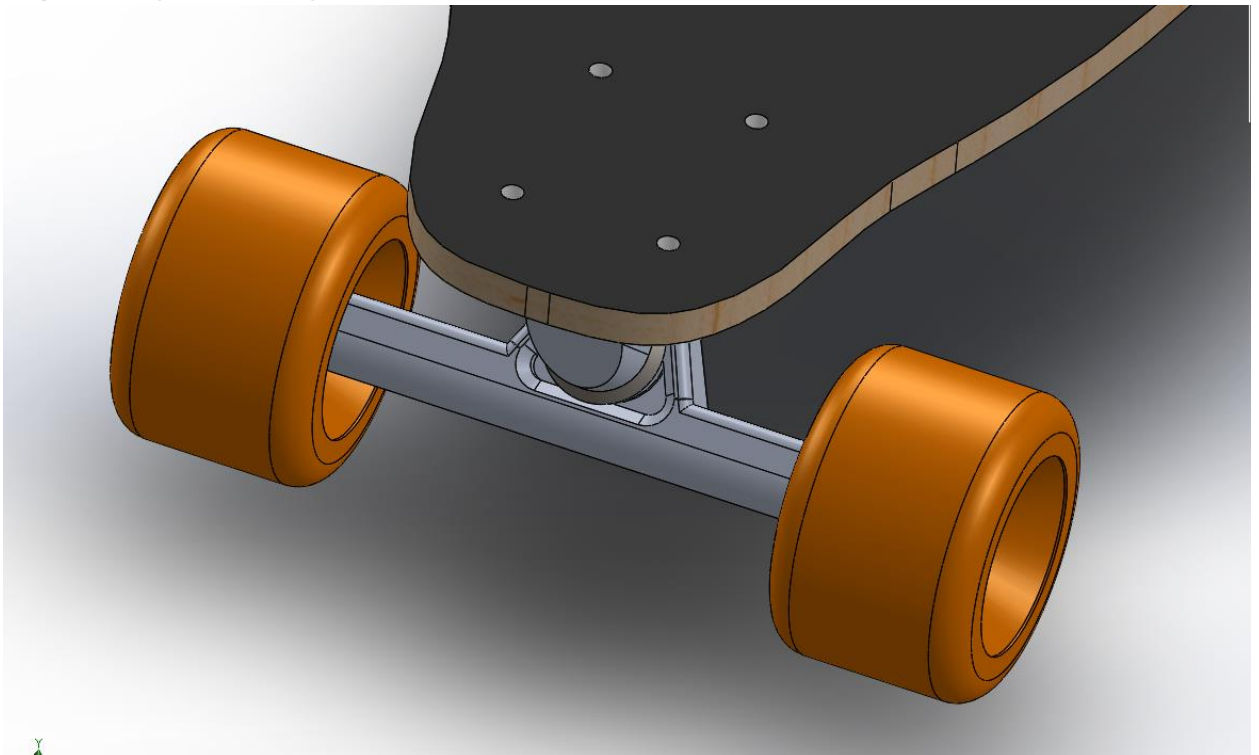
16. **Concentric mate:** Create concentric mate between the **Hex Nut** and **Trucks**



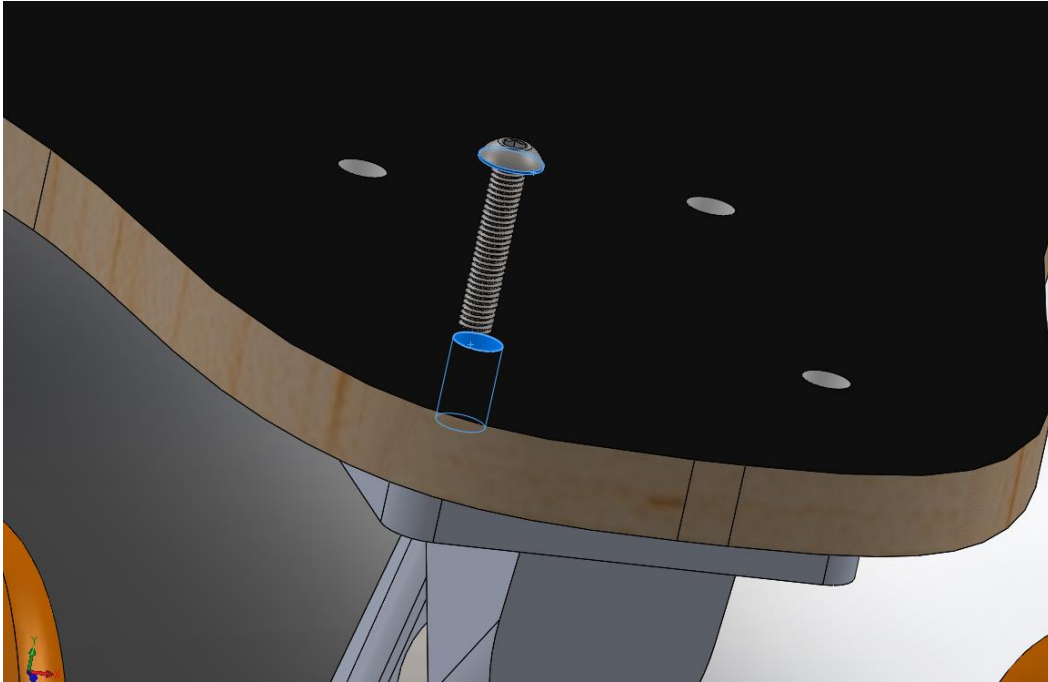
17. **Coincident mate:** Create coincident mate between the following faces on the **wheel** and **hex nut**



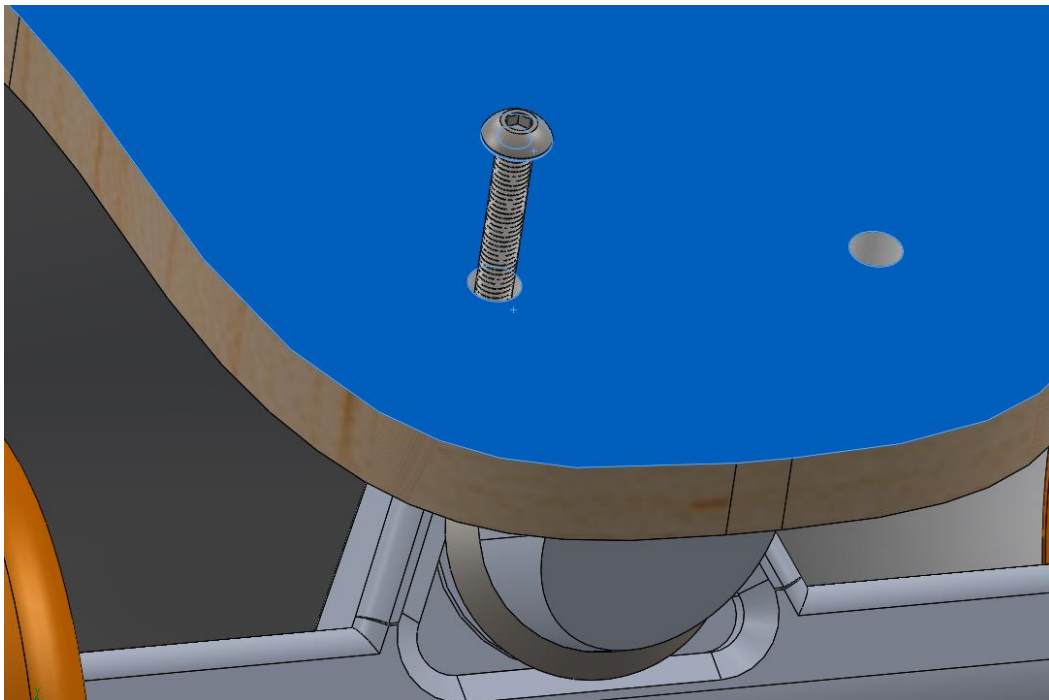
18. **Repeat:** Repeat the steps to mate the wheel on the other side of the truck.



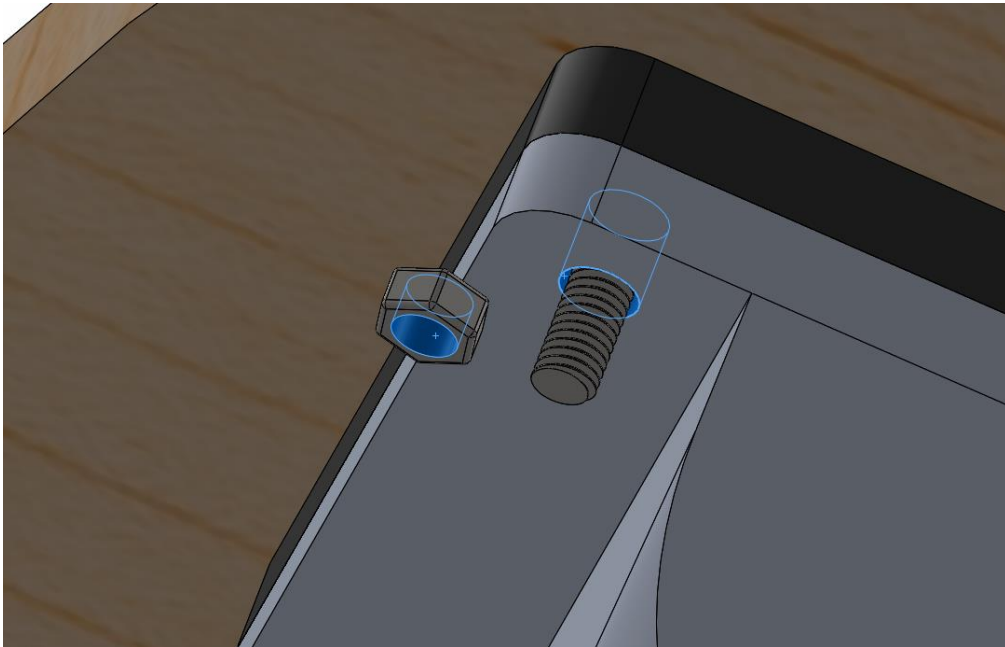
**19. Concentric mate:** Create a concentric mate between the **Screw** and the **Deck**



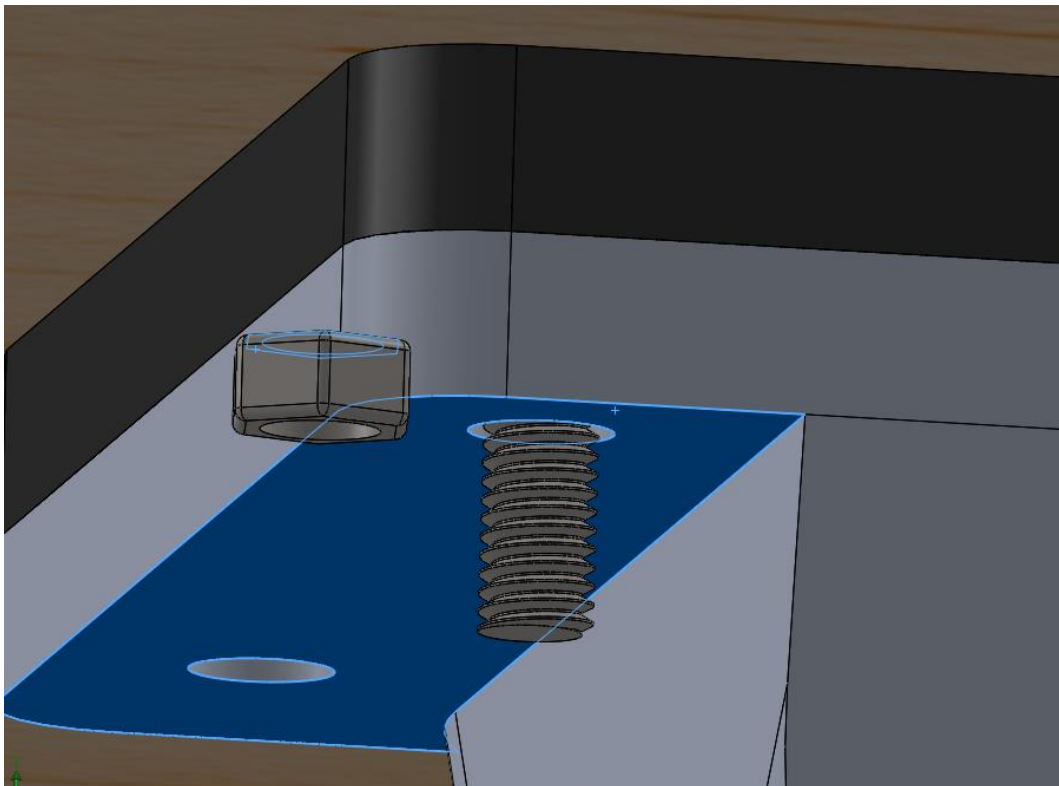
**20. Tangent Mate:** Create a tangent mate on the following faces between the **screw** and the **deck**



**21. Concentric Mate:** Create a concentric mate between the **screw nut** and **baseplate**

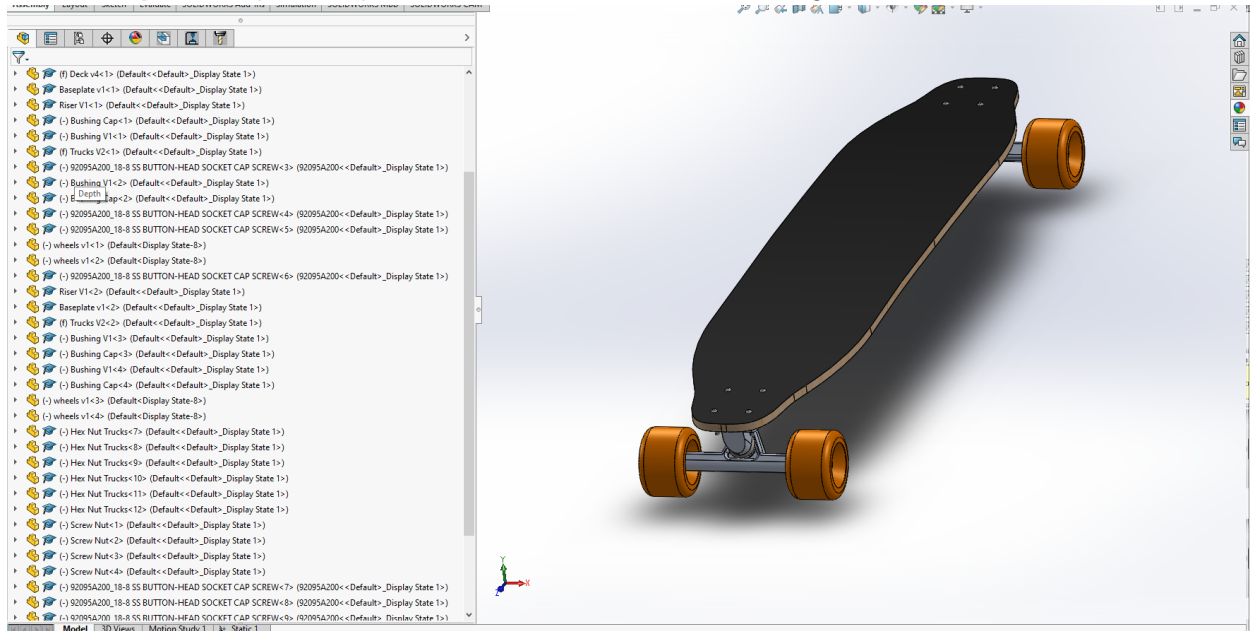


**22. Coincident Mate:** Create a coincident mate between the **screw but** and **baseplate**





**23. Repeat:** Repeat steps 2-22 on the other end of the longboard.



**24. Lights:** Display Manager Icon → View Scenes, Lights, Camera Icon → Right click lights to add light



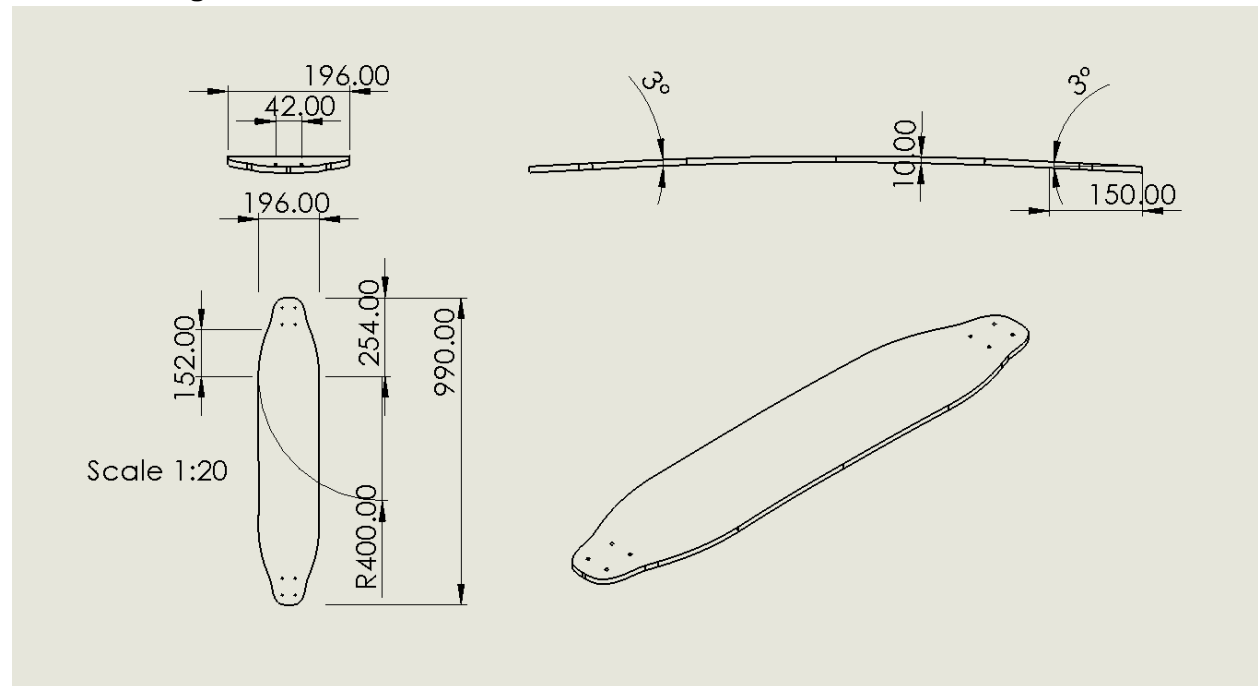
**25. Scenes:** Scenes, Lights, Camera Icon → Right click Scenes to edit scene.



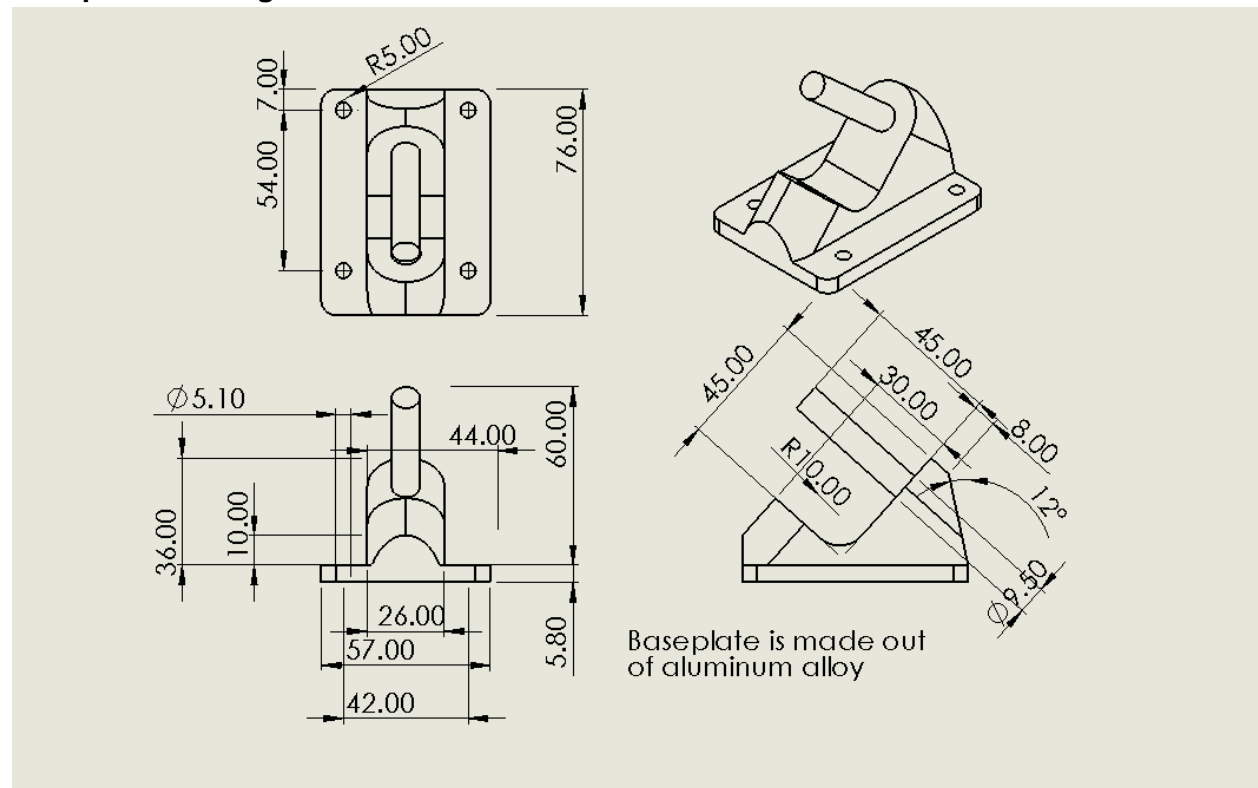


# Engineering Drawings

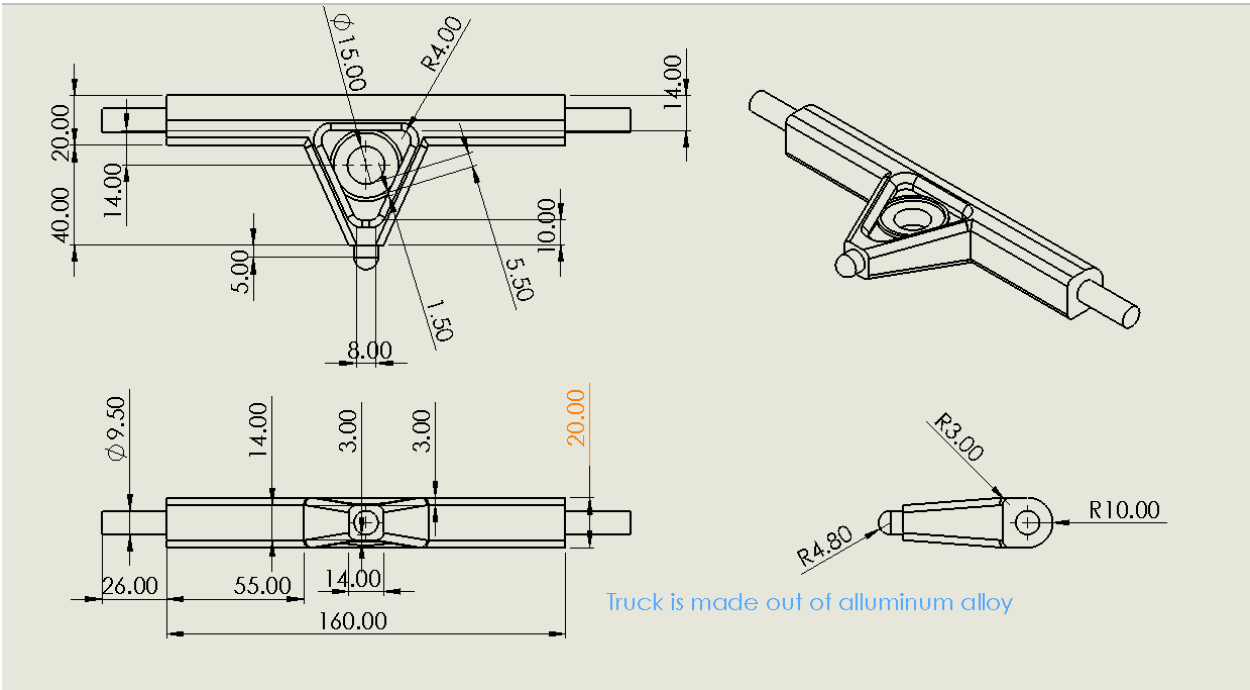
## Deck Drawing



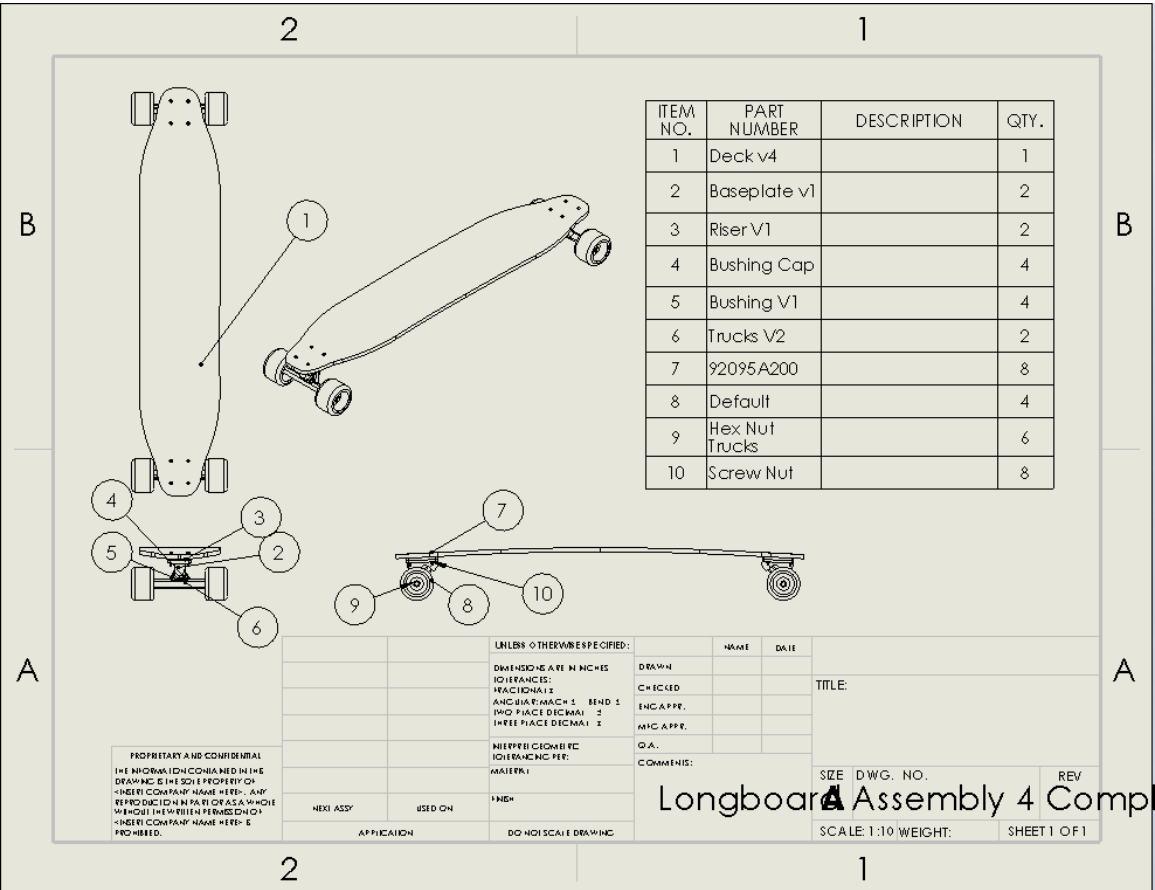
## Baseplate Drawing



Trucks Drawing



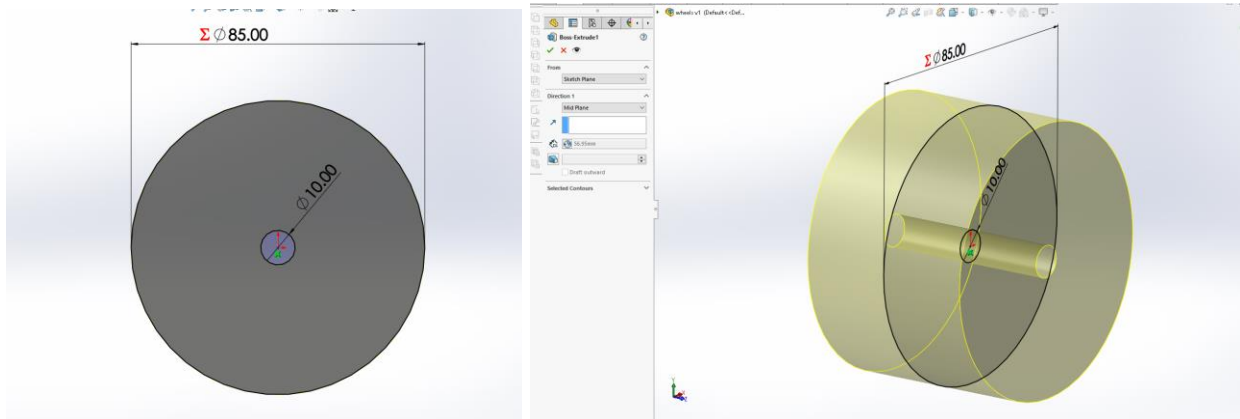
Assembly Drawing



# Design Intent & Part Configuration Analysis

## Equation

An equation was added to **Wheel**, relating the following dimensions:



## Equation table:

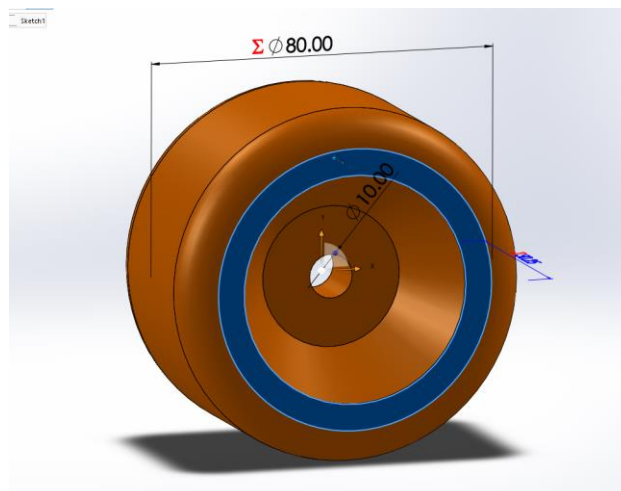
Equations, Global Variables, and Dimensions

Name	Value / Equation	Evaluates to	Comments
<b>Global Variables</b>			
"A"	= 85	85	
"B"	= 80	80	
"C"	= 105	105	
"D"	= "A" * .67	56.95	
Add global variable			
<b>Features</b>			
Add feature suppression			
<b>Equations</b>			
"D1@Sketch1"	= "A"	85mm	
"D1@Boss-Extrude1"	= "D"	56.95mm	
Add equation			

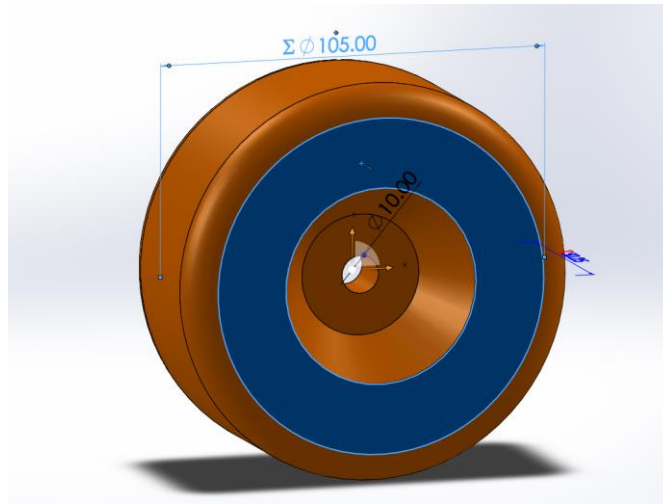
☐ Automatically rebuild ☐ Link to external file: Angular equation units: Degrees ☒ Automatic solve order

OK Cancel Import... Export... Help

**B = 80mm**



**C = 105mm**

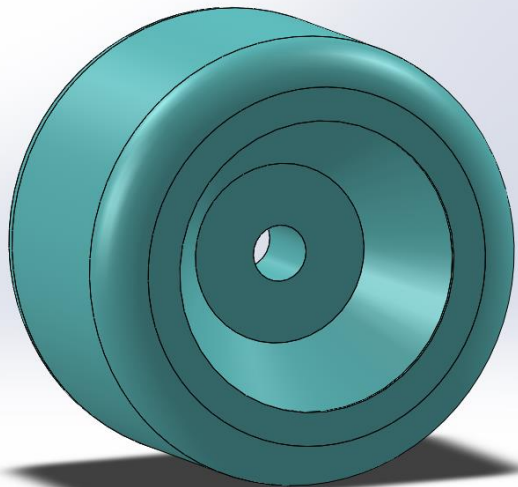
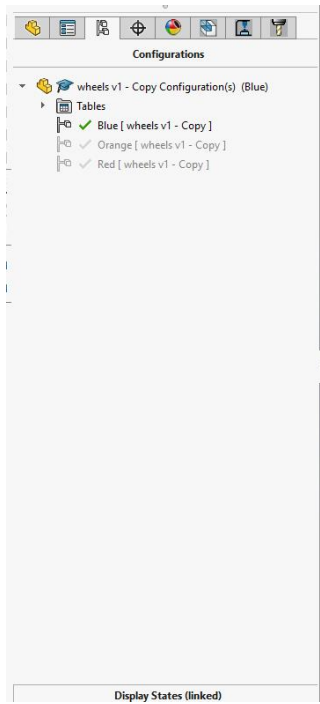
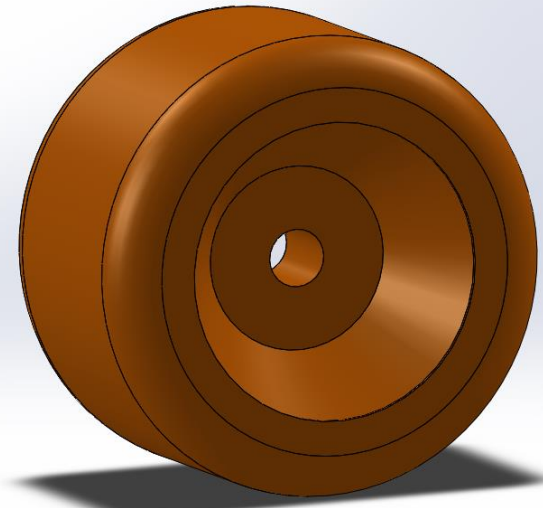
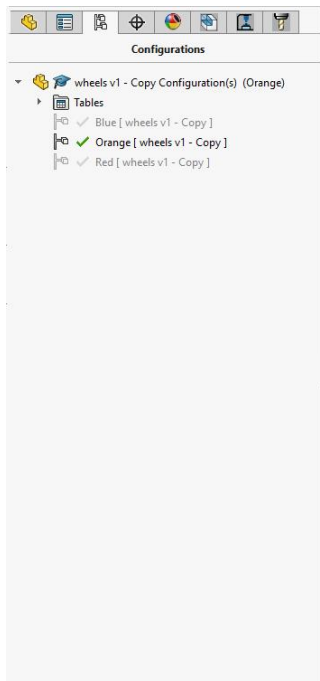


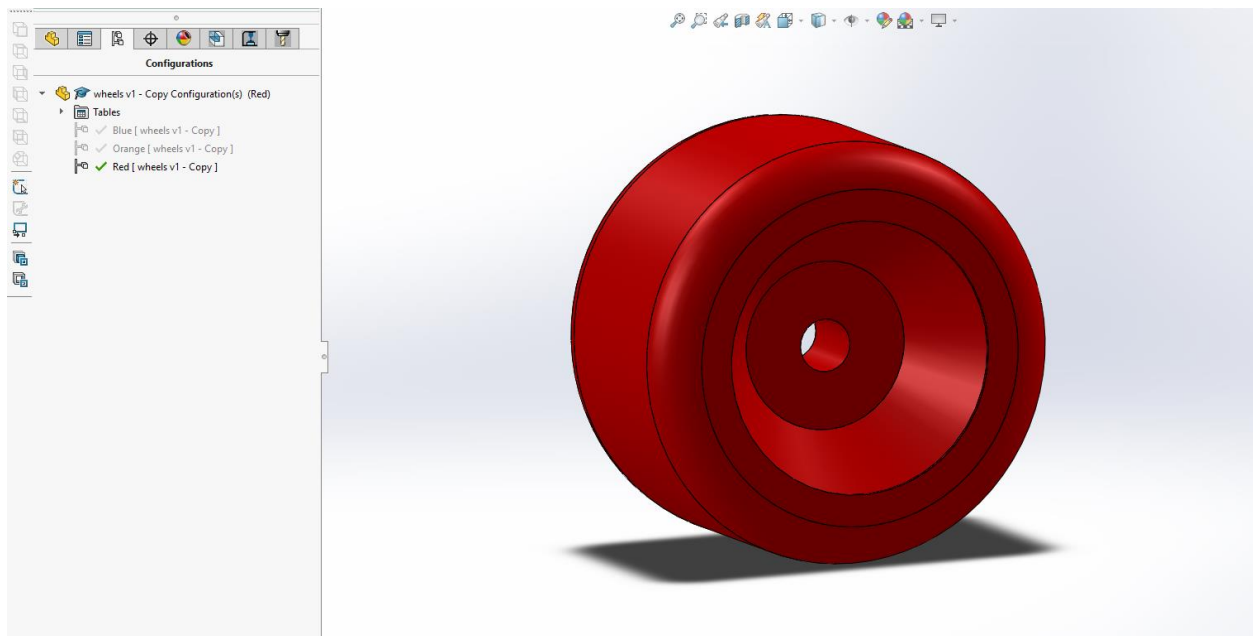
## Configuration

2 configurations were added to the **Wheel**, the original being a colored orange, one colored blue, one colored red

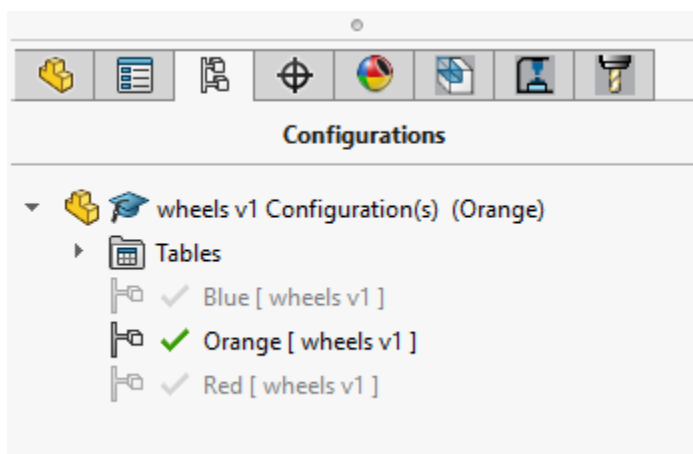
### Design Table

Design Table for: wheels v1				
	\$DESCRIPTION	\$COLOR	\$VALUE@A@Equations	\$VALUE@C@Equations
Default	Default	33535	=85	=10
105mm	105mm	33234	=105	=10
80mm	80mm	35347	=80	=10

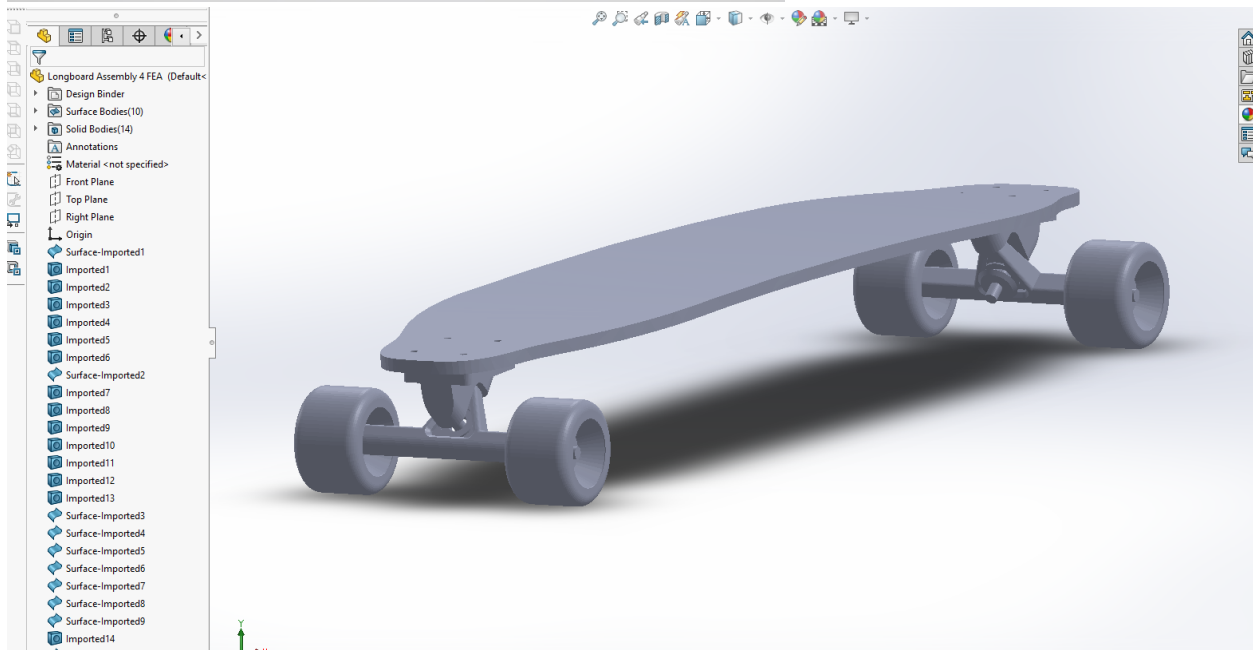




## Configuration Manager




# STL File



# Mass Properties

## Assembly Mass Properties

 Mass Properties

Longboard Assembly 4 FEA.SLDASM

Options...

Override Mass Properties...

Recalculate

☒ Include hidden bodies/components

☐ Create Center of Mass feature


☐ Show weld bead mass


Report coordinate values relative to: -- default --

Mass properties of Longboard Assembly 4 FEA  
Configuration: Default  
Coordinate system: -- default --  
  
Mass = 2840.08 grams  
  
Volume = 2823123.86 cubic millimeters  
  
Surface area = 547447.92 square millimeters  
  
Center of mass: ( millimeters )  
X = 432.20  
Y = 533.04  
Z = 689.99  
  
Principal axes of inertia and principal moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass.  
Ix = ( 0.00, 0.00, 1.00)    Px = 16217006.48  
Iy = ( 1.00, 0.00, 0.00)    Py = 426407158.58  
Iz = ( 0.00, 1.00, 0.00)    Pz = 434273672.19  
  
Moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass and aligned with the output coordinate system.  
Lxx = 426407158.58    Lxy = 13.58    Lxz = 166.31  
Lyx = 13.58    Lyy = 434273647.94    Lyz = 100673.89  
Lzx = 166.31    Lzy = 100673.89    Lzz = 16217030.72  
  
Moments of inertia: ( grams \* square millimeters )  
Taken at the output coordinate system.  
Ixx = 2585483839.54    Ixy = 654296931.84    Ixz = 846947233.38  
Iyx = 654296931.84    Iyy = 2316906623.45    Iyz = 1044659758.27  
Izx = 846947233.38    Izy = 1044659758.27    Izz = 1353691872.08



## Deck Mass Properties

 Mass Properties

 Deck v4.SLDPRT

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components

☐ Create Center of Mass feature

☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of Deck v4  
Configuration: Default  
Coordinate system: -- default --

Density = 0.00 grams per cubic millimeter

Mass = 1025.79 grams

Volume = 1684379.00 cubic millimeters

Surface area = 359694.64 square millimeters


Center of mass: ( millimeters )  
X = 0.00  
Y = 6.96  
Z = -0.24


Principal axes of inertia and principal moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass.  
Ix = ( 0.00, 0.00, 1.00) Px = 2847847.16  
Iy = ( 1.00, 0.00, 0.00) Py = 67926645.44  
Iz = ( 0.00, 1.00, 0.00) Pz = 70713553.39

Moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass and aligned with the output coordinate system.  
Lxx = 67926645.44 Lxy = -3.31 Lxz = 166.41  
Lyx = -3.31 Lyy = 70713553.39 Lyz = -761.36  
Lzx = 166.41 Lzy = -761.36 Lzz = 2847847.17

Moments of inertia: ( grams \* square millimeters )  
Taken at the output coordinate system.  
lxx = 67976464.63 lxy = -0.54 lxz = 166.31  
lyx = -0.54 lyy = 70713613.64 lyz = -2492.86  
lzx = 166.31 lzy = -2492.86 lzz = 2897606.11

## Baseplate Mass Properties

 Mass Properties

 Baseplate v1.SLDPRT

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components

☐ Create Center of Mass feature

☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of Baseplate v1  
Configuration: Default  
Coordinate system: -- default --

Density = 0.00 grams per cubic millimeter

Mass = 168.74 grams

Volume = 60049.80 cubic millimeters

Surface area = 15619.93 square millimeters

Center of mass: ( millimeters )  
X = 0.00  
Y = 12.49  
Z = -3.37

Principal axes of inertia and principal moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass.  
lx = ( 0.00, -0.13, 0.99) Px = 47203.31  
ly = ( 0.00, -0.99, -0.13) Py = 101897.10  
lz = ( 1.00, 0.00, 0.00) Pz = 102774.52

Moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass and aligned with the output coordinate system.  
Lxx = 102774.52 Lxy = 0.12 Lxz = 0.08  
Lyx = 0.12 Lyy = 100981.33 Lyz = -7017.70  
Lzx = 0.08 Lzy = -7017.70 Lzz = 48119.07

Moments of inertia: ( grams \* square millimeters )  
Taken at the output coordinate system.  
lxx = 131013.96 lxy = 0.12 lxz = 0.08  
lyx = 0.12 lyy = 102892.14 lyz = -14110.57  
lzx = 0.08 lzy = -14110.57 lzz = 74447.71

## Trucks Mass Properties

Mass Properties

Trucks V2.SLDPRT

Options...

Override Mass Properties... Recalculate

☒ Include hidden bodies/components

☐ Create Center of Mass feature

☐ Show weld bead mass

Report coordinate values relative to: -- default --

Mass properties of Trucks V2  
Configuration: Default  
Coordinate system: -- default --

Density = 0.00 grams per cubic millimeter

Mass = 202.35 grams

Volume = 72012.24 cubic millimeters

Surface area = 17855.87 square millimeters

Center of mass: ( millimeters )  
X = 0.00  
Y = 9.98  
Z = 16.18

Principal axes of inertia and principal moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass.

lx = ( 1.00, 0.00, 0.00)	Px = 41272.65
ly = ( 0.00, 0.00, -1.00)	Py = 439035.14
lz = ( 0.00, 1.00, 0.00)	Pz = 470423.36

Moments of inertia: ( grams \* square millimeters )  
Taken at the center of mass and aligned with the output coordinate system.

Lxx = 41272.65	Lxy = 0.09	Lxz = -0.01
Lyx = 0.09	Lyy = 470423.36	Lyz = -7.88
Lzx = -0.01	Lzy = -7.88	Lzz = 439035.14

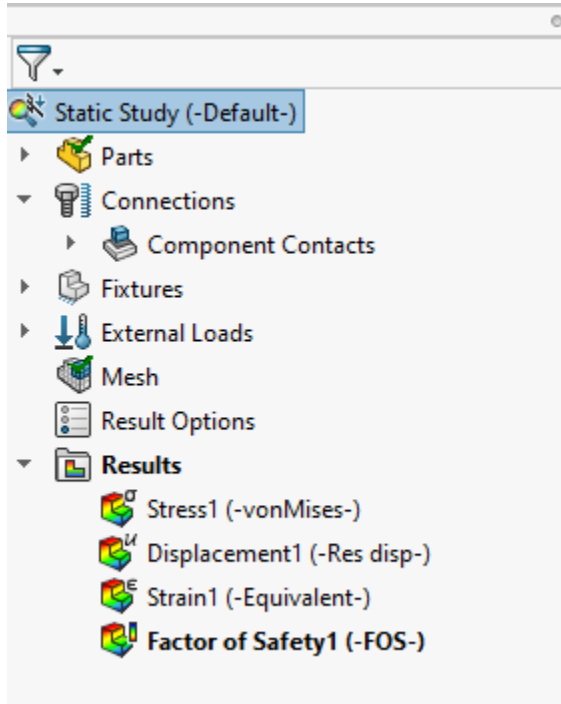
Moments of inertia: ( grams \* square millimeters )  
Taken at the output coordinate system.

lxx = 114409.63	lxy = 0.06	lxz = -0.06
lyx = 0.06	lyy = 523411.07	lyz = 32667.24
lzx = -0.06	lzy = 32667.24	lzz = 459184.41

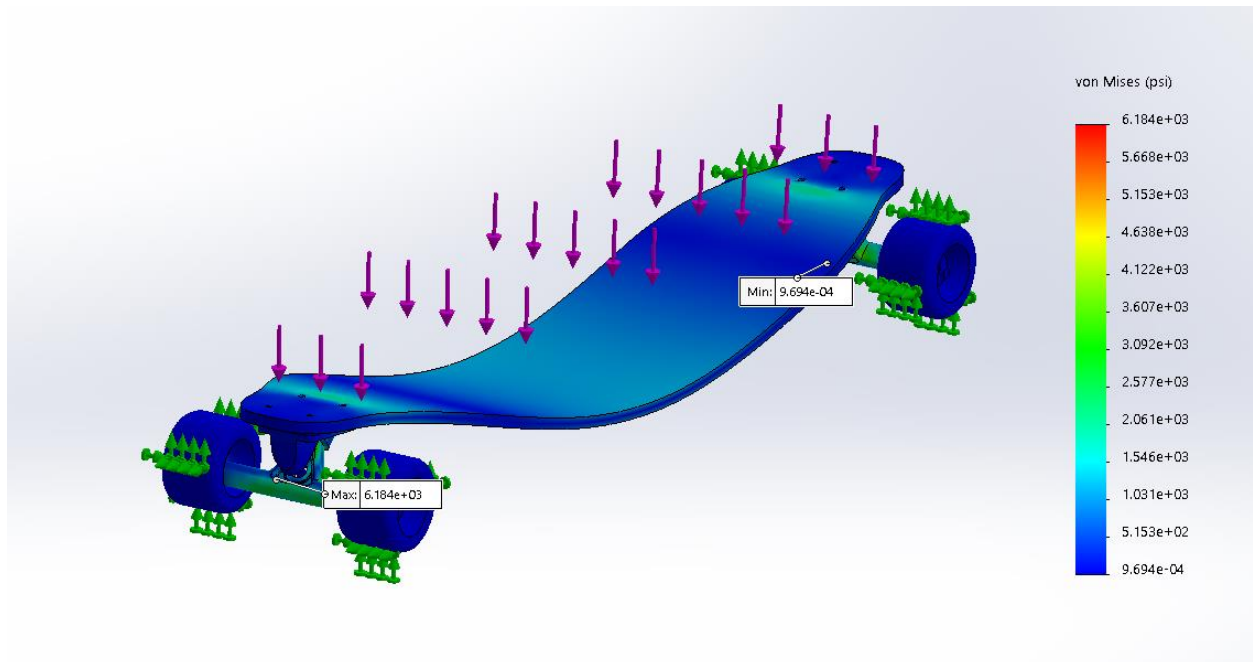
## FEM/FEA

An FEM/FEA was performed on the longboard to analyze stress and displacement resulting from a compressive normal 160lb force on the wooden deck. This was analyzed with fixtures on the flat faces of the wheels.

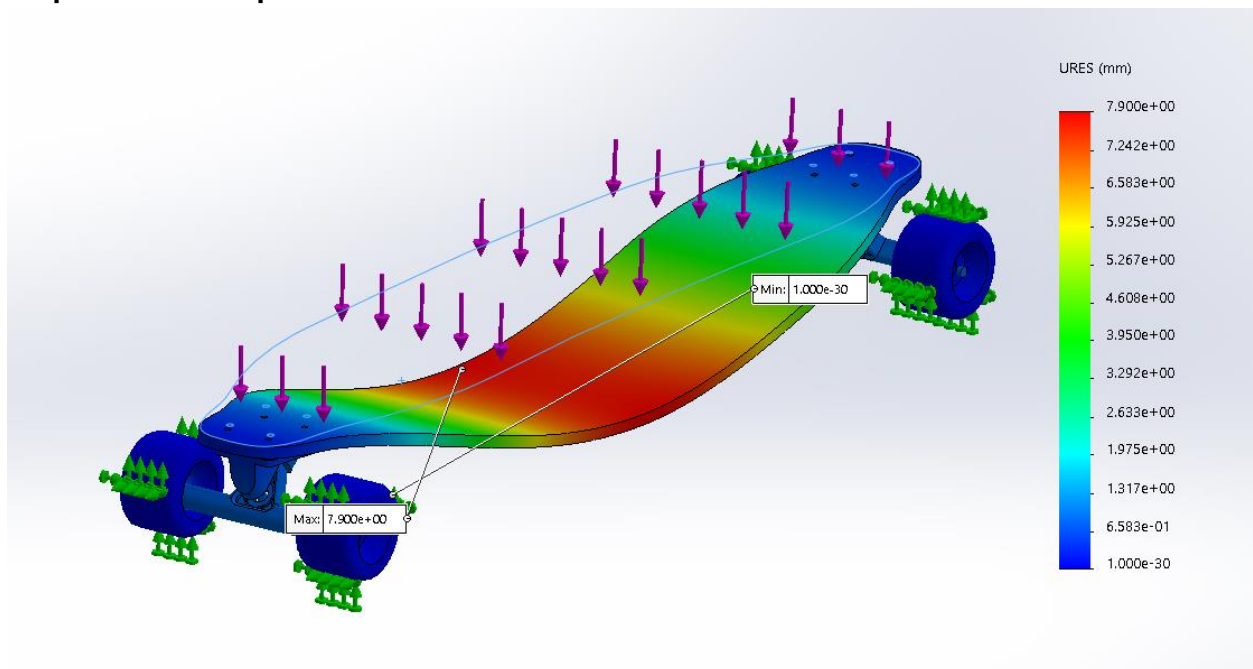
### Simulation Tree



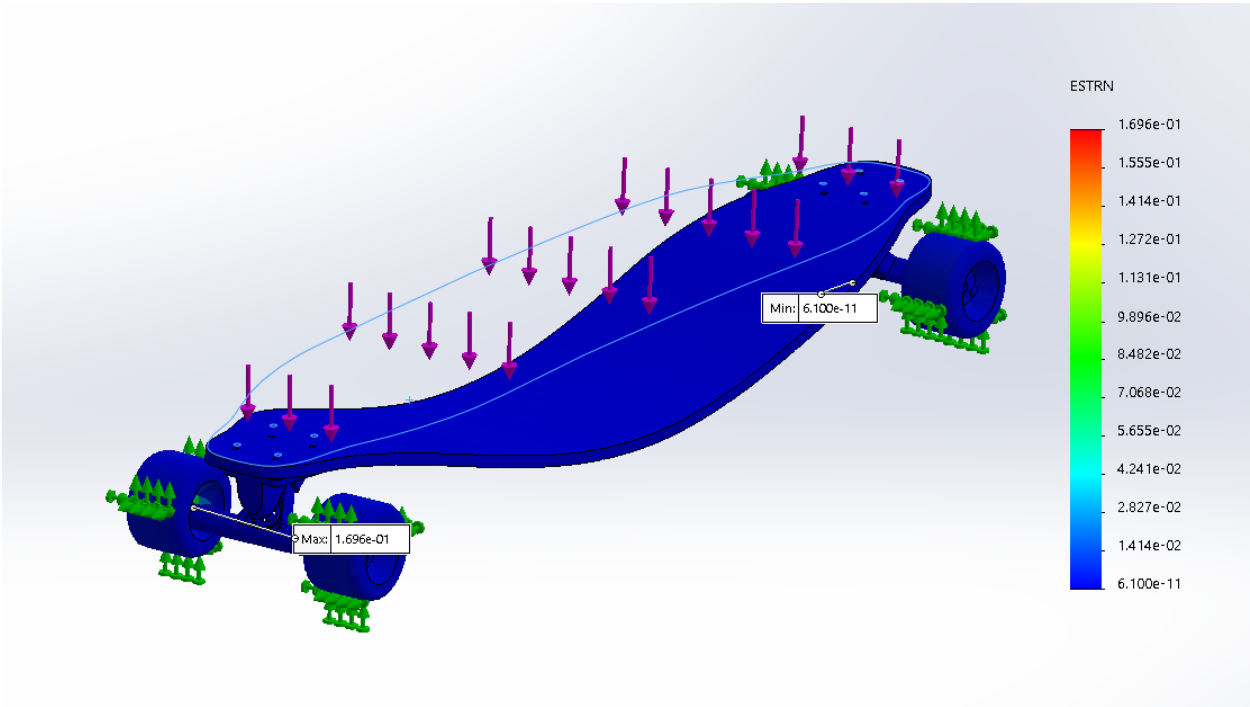
## Stress Graph



## Displacement Graph




Strain graph

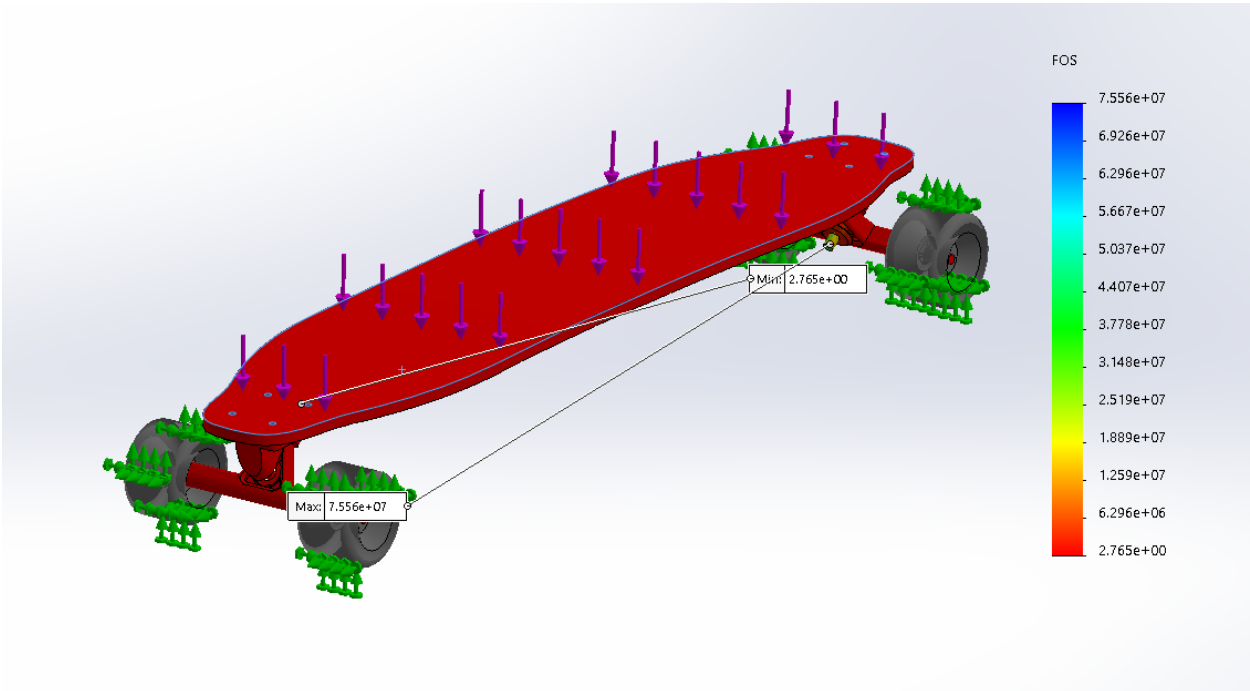


FOS Graph (due to materials not having enough stress limits, graph was displayed in gray)

Simulation ×

 Some materials do not have sufficient stress limits to calculate the requested results and hence those bodies will be displayed in gray.

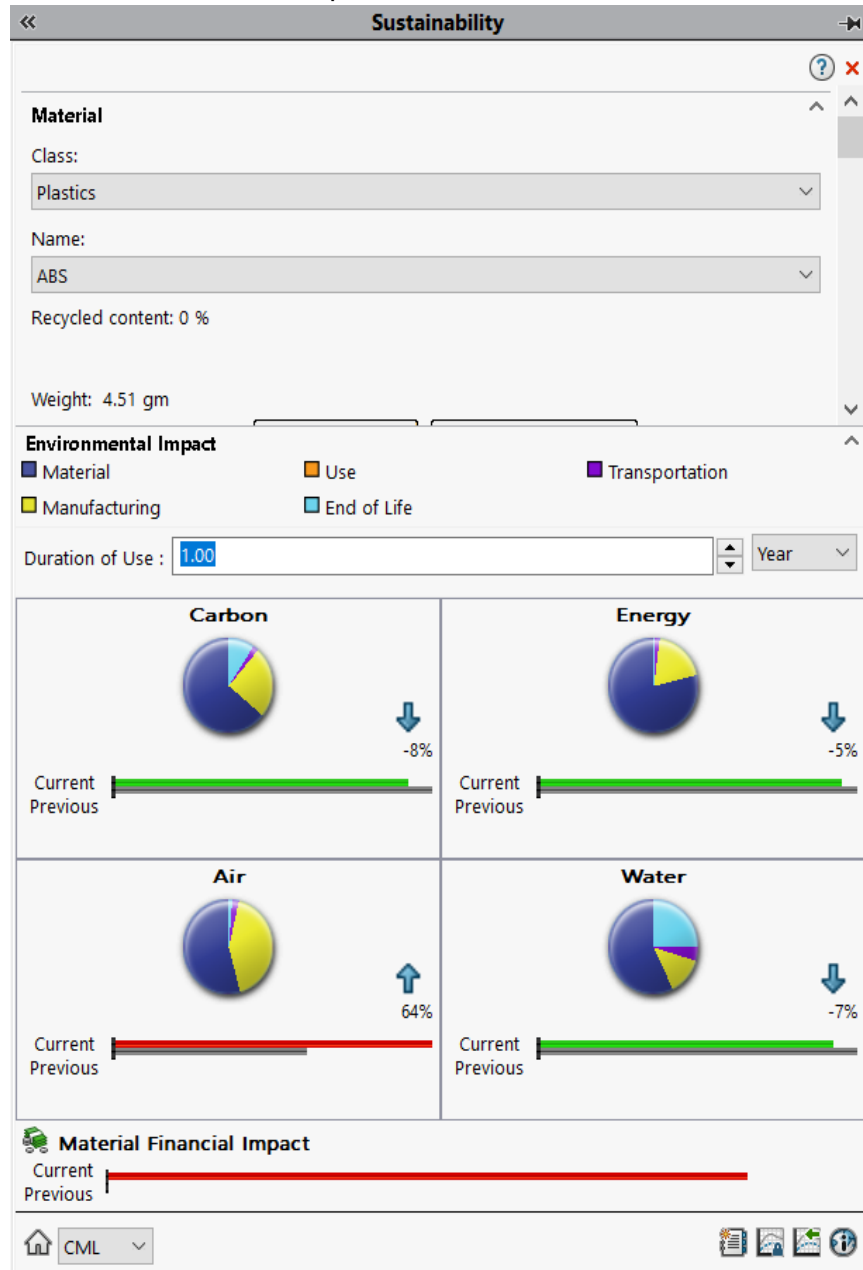
OK



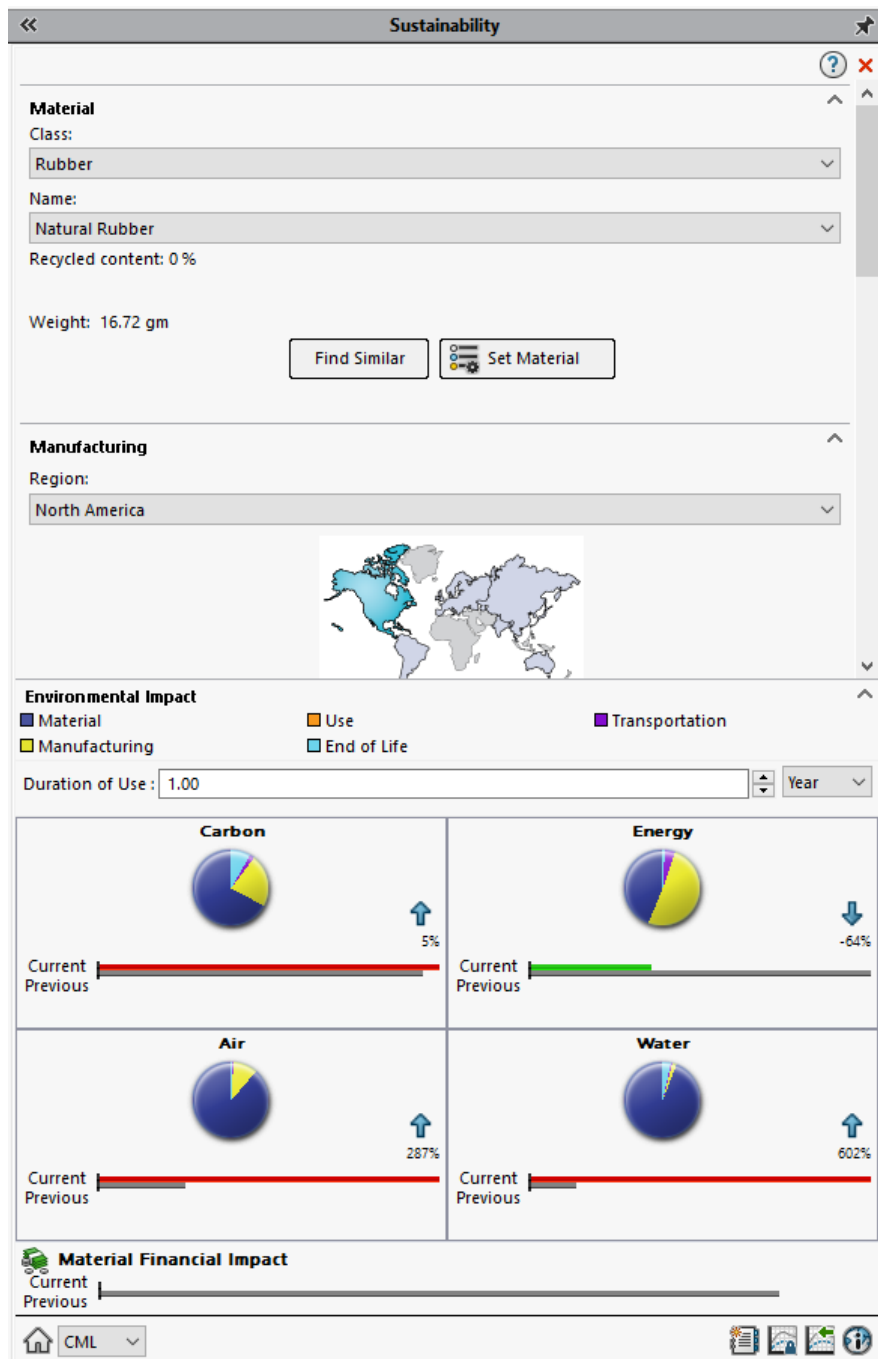
# Sustainable Design

The **risers** were evaluated for sustainable design

Using ABS plastic the environmental impact is shown below:



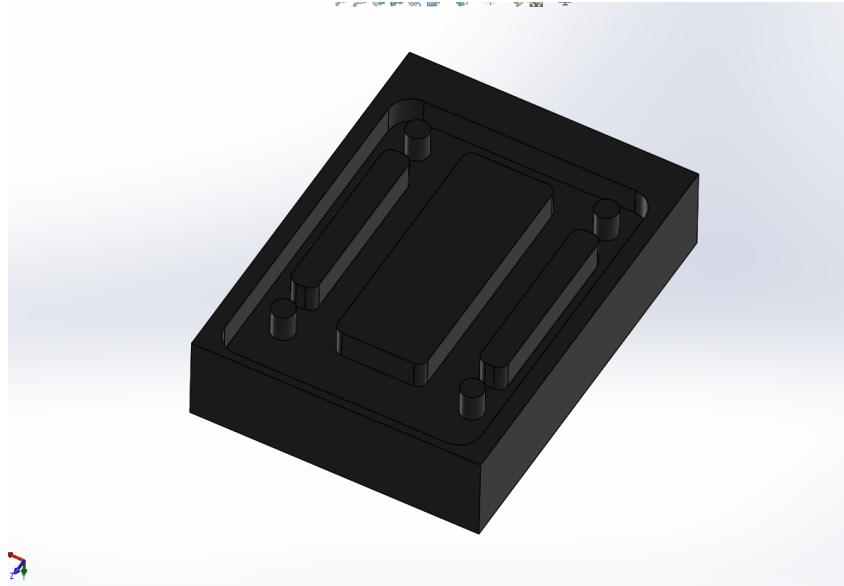
Using Rubber, the environmental impact is shown below:



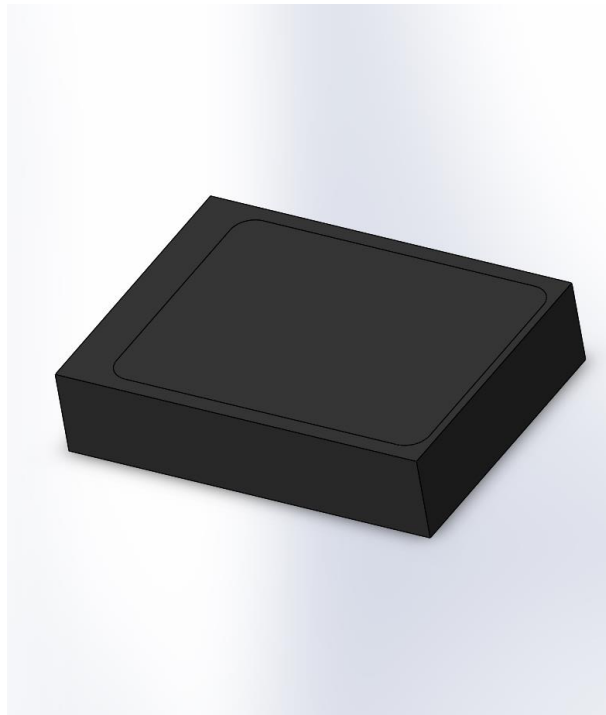


# Part Manufacturing

Injection molding would be used to create the **risers**. Below are the mold pieces for the riser.  
**Cavity**



**Core**



## Cavity , Part, and Core

